

Ch - :- Fourier Transform (F.T.)

$\Rightarrow$ Transformation is the process in which one domain is converted to another domain such that signal analysis becomes easy.

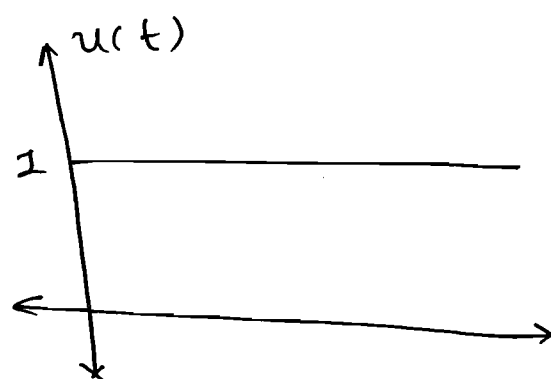
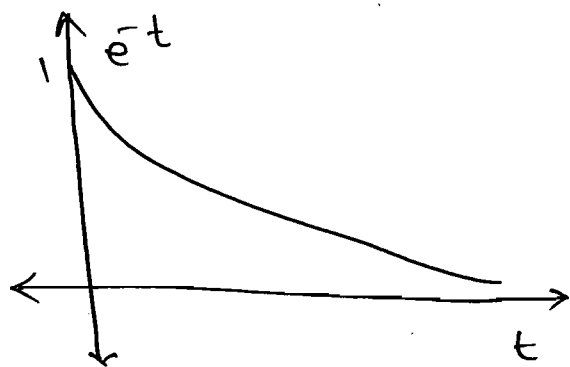
$\Rightarrow$ For any Non Periodic signal as $T \rightarrow \infty$ implies $\omega_0 \rightarrow 0$.

$\Rightarrow$ The discrete spectrum of Fourier Series is converted to continuous spectrum in Fourier Transform.

$\Rightarrow$ Extension of F.S. is F.T.

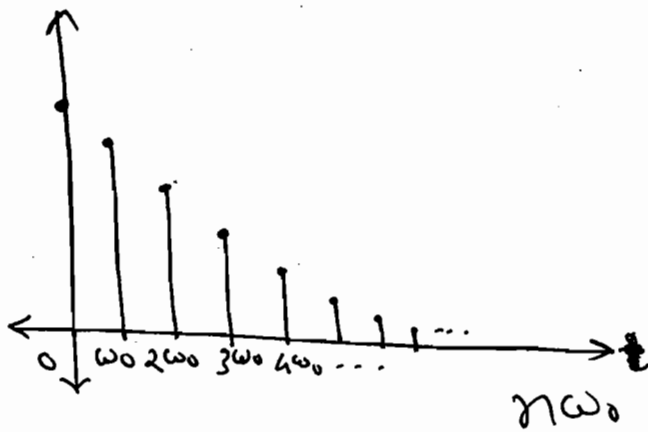
$\Rightarrow$ F.T. is extension of F.S. to non-periodic signal.

$$\Rightarrow x(t) = e^{-t} \cdot u(t), \quad u(t)$$



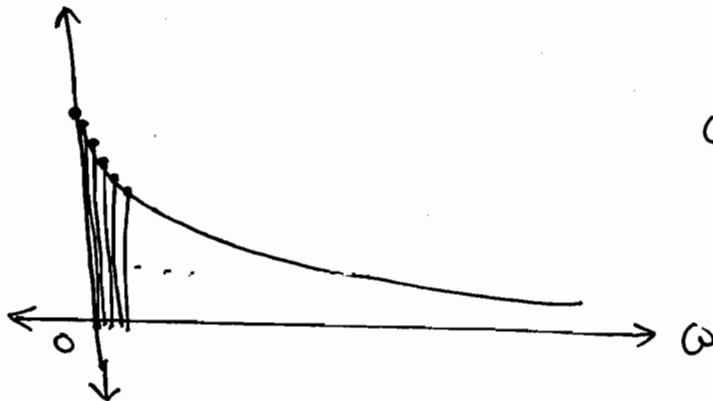
$T \rightarrow \infty$, Non-periodic.

⇒



$T \rightarrow \infty$
 $\omega \rightarrow 0$
 i.e. $n\omega_0 \rightarrow \omega$.

⇓



$\omega = n\omega_0$

⇒

From F.S.

$$x(t) = \sum_{n=-\infty}^{\infty} c_n \cdot e^{j\omega_n t}$$

x

2

$$C_n = \frac{1}{T} \int_{-T/2}^{+T/2} x(t) \cdot e^{-j\omega_n t} dt.$$

$T \rightarrow \infty$

$$\lim_{T \rightarrow \infty} T C_n = \int_{-\infty}^{+\infty} x(t) \cdot e^{-j\omega t} dt.$$

⇒

$$X(\omega) = \int_{-\infty}^{+\infty} x(t) \cdot e^{-j\omega t} dt.$$

⇓

F.T. of $x(t)$.

kernel.

⇒ I.F.T.

$$\therefore x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) \cdot e^{j\omega t} \cdot d\omega.$$

$$\omega = 2\pi f$$

$$\therefore d\omega = 2\pi df.$$

I.F.T.

$$\therefore x(t) = \int_{-\infty}^{\infty} X(f) \cdot e^{j2\pi ft} \cdot df.$$

⇒ F.T.

$$X(f) = \int_{-\infty}^{+\infty} x(t) \cdot e^{-j2\pi ft} \cdot dt$$

⇒

$$2\pi \delta(\omega) = \delta(f).$$

Proof: $2\pi \delta(\omega) = 2\pi \delta(2\pi f).$

$$= \frac{2\pi}{|2\pi|} \cdot \delta(f)$$

$$2\pi \delta(\omega) = \delta(f).$$

* Convergence of F.T.:

⇒ $X(\omega) < \infty.$

⇒ Fourier transform is defined for
Stable and energy signal. ✓

⇒ Fourier transform of a power signal is defined as approximation to energy signals (or) impulse functions. are permitted.

⇒ Fourier transform is not defined for neither absolutely integrable nor square integrable signals.

P 4.1.1. If $x(t)$ is a voltage waveform, then what are the units of $X(f)$?

Soln:

$$X(f) = \int_{-\infty}^{\infty} x(t) \cdot e^{-j2\pi ft} \cdot dt$$

$\downarrow$ $\uparrow$ $\swarrow$
 = Volts · sec.

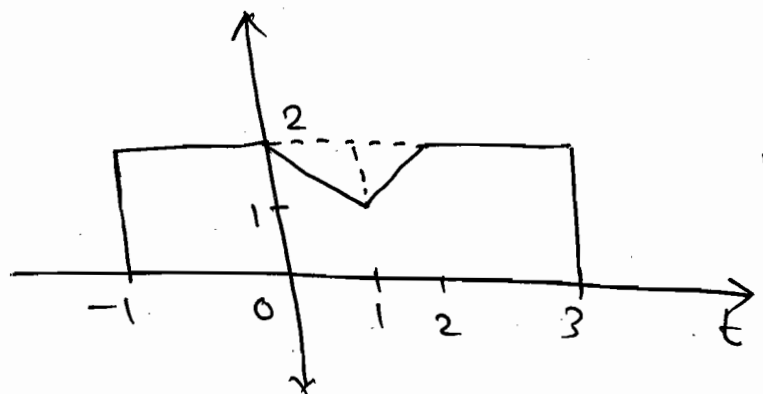
So, $X(f)$ unit is Volts · sec (or)

$$\boxed{\text{Volts} \mid \text{Hz}}$$

P 4.1.2 For the signal $x(t)$ shown in figure, find

(a) $X(0)$.

(b) $\int_{-\infty}^{+\infty} X(\omega) d\omega$



Soln: ⑨ $X(\omega) = \int_{-\infty}^{\infty} x(t) \cdot e^{-j\omega t} \cdot dt.$

make $\omega = 0.$

$$\therefore X(0) = \int_{-\infty}^{+\infty} x(t) \cdot dt = \text{Area under the curve.}$$

$$\therefore X(0) = (4 \times 2) - \left(\frac{1}{2} \times 1 \times 2\right)$$

$$\boxed{X(0) = 7}$$

(b) $x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(\omega) \cdot e^{j\omega t} \cdot d\omega.$

make $t = 0.$

$$\therefore x(0) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(\omega) \cdot e^0 \cdot d\omega.$$

$$\begin{aligned} \Rightarrow \int_{-\infty}^{+\infty} X(\omega) \cdot d\omega &= 2\pi x(0). \\ &= 2\pi \times 2 \\ &= 4\pi. \end{aligned}$$

Note:

→ Area under one domain corresponds to observing the other domain at origin.

[P 4.1.3.] Consider the signal $x(t) = \begin{cases} e^{-t} ; t > 0 \\ 0 ; t < 0 \end{cases}$

and $X(\omega)$ is the F.T. of this signal.

Then the value of $\frac{1}{2\pi} \int_{-\infty}^{+\infty} X(\omega) d\omega$ is ____.

Soln.

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(\omega) \cdot e^{j\omega t} \cdot d\omega$$

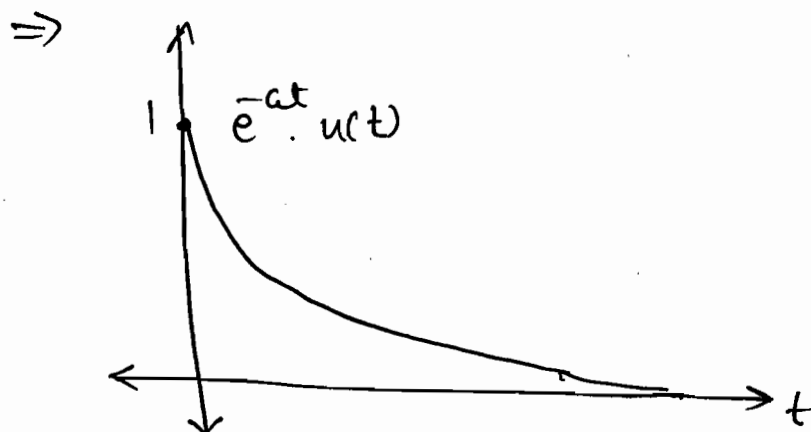
$$\text{So, } x(0) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(\omega) d\omega = e^{-0} = 1.$$

$$\text{So, } \boxed{\frac{1}{2\pi} \int_{-\infty}^{+\infty} X(\omega) \cdot d\omega = 1.}$$

* F.T. of Standard signals:

1) Decaying exponential

$$x_1(t) = e^{-at} \cdot u(t), \quad a > 0.$$



$$X(\omega) = \int_{-\infty}^{\infty} x(t) \cdot e^{-j\omega t} \cdot dt.$$

$$= \int_{-\infty}^{+\infty} e^{-at} \cdot e^{-j\omega t} \cdot dt.$$

$$\therefore X(\omega) = \int_{-\infty}^{\infty} e^{-(a+j\omega)t} \cdot dt.$$

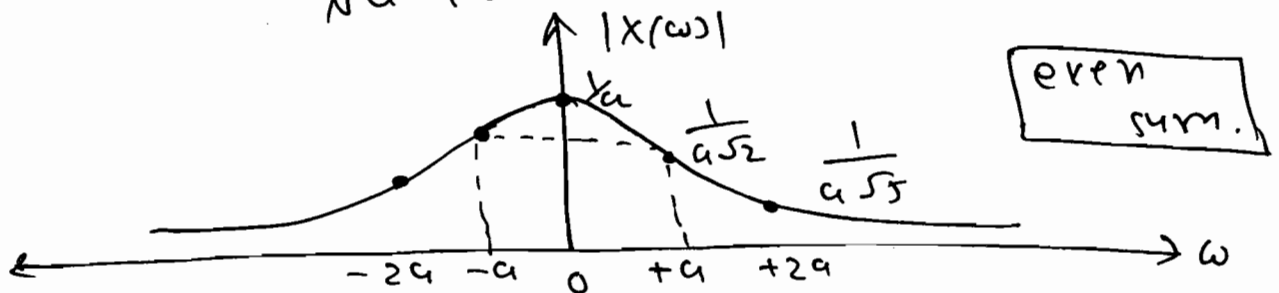
$$= \left[\frac{e^{-(a+j\omega)t}}{-(a+j\omega)} \right]_0^{\infty}$$

$$X(\omega) = 0 + \frac{1}{a+j\omega}.$$

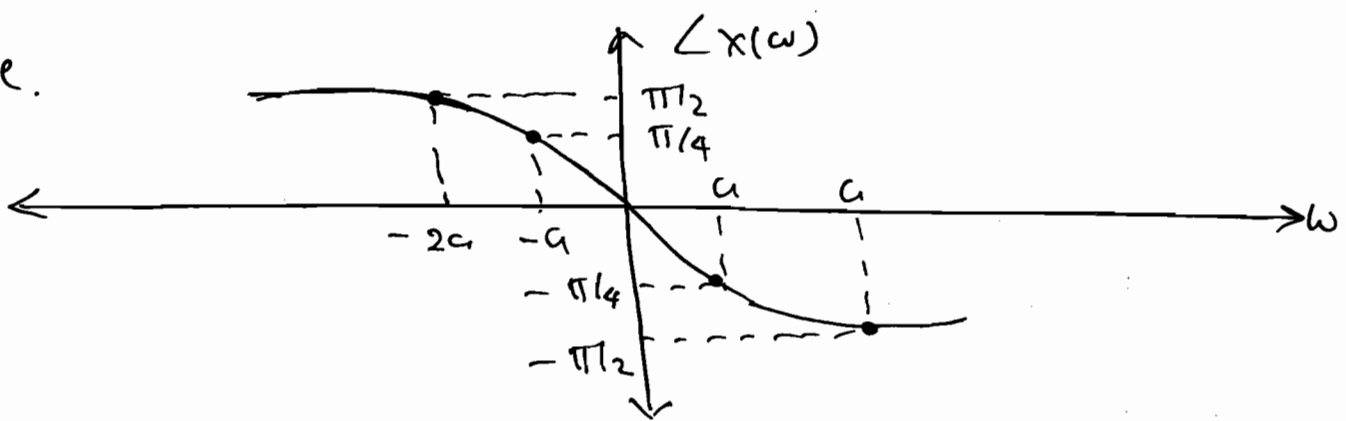
$$\therefore e^{-at} \cdot u(t) \xleftrightarrow{\text{F.T.}} \frac{1}{a+j\omega}.$$

$$\Rightarrow |X(\omega)| = \frac{1}{\sqrt{a^2 + \omega^2}}, \quad \angle X(\omega) = -\tan^{-1}\left(\frac{\omega}{a}\right).$$

Mag.

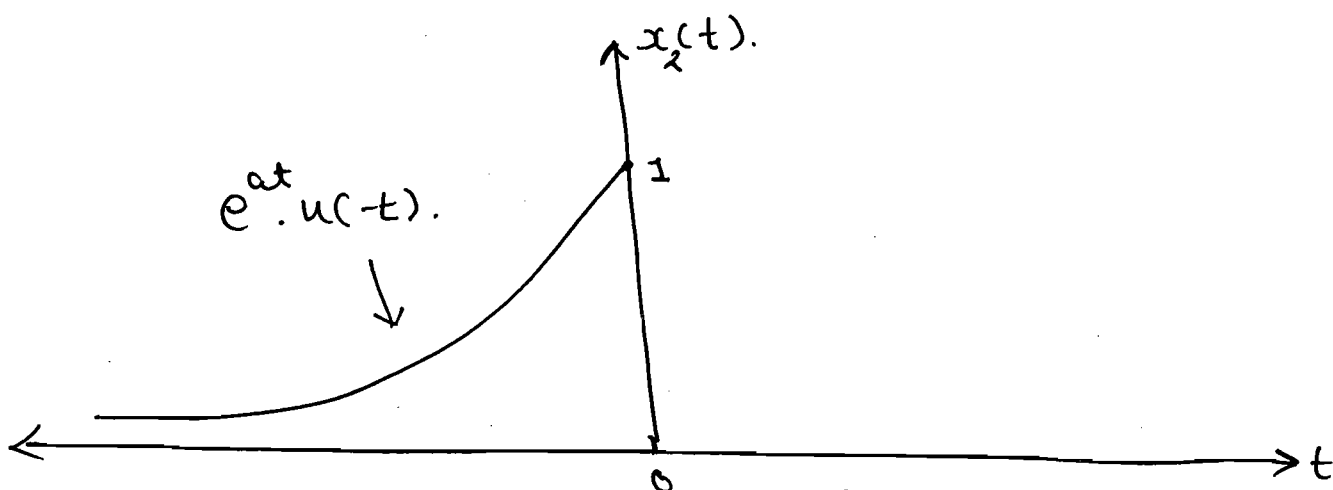


Phase.



2) $e^{at} \cdot u(-t), \quad a > 0.$

$\Rightarrow$



$\therefore x_2(t) = x_1(-t)$

$\Rightarrow$ using time reversal property,

$$x(t) \xleftrightarrow{\text{F.T.}} X(\omega).$$

$$x(-t) \xleftrightarrow{\text{F.T.}} X(-\omega).$$

$$\therefore X(-\omega) = \frac{1}{a - j\omega}.$$

$$\therefore \boxed{e^{at} u(-t) \xleftrightarrow{\text{F.T.}} \frac{1}{a - j\omega}}.$$

③ $x(t) = \delta(t).$

$\Rightarrow$

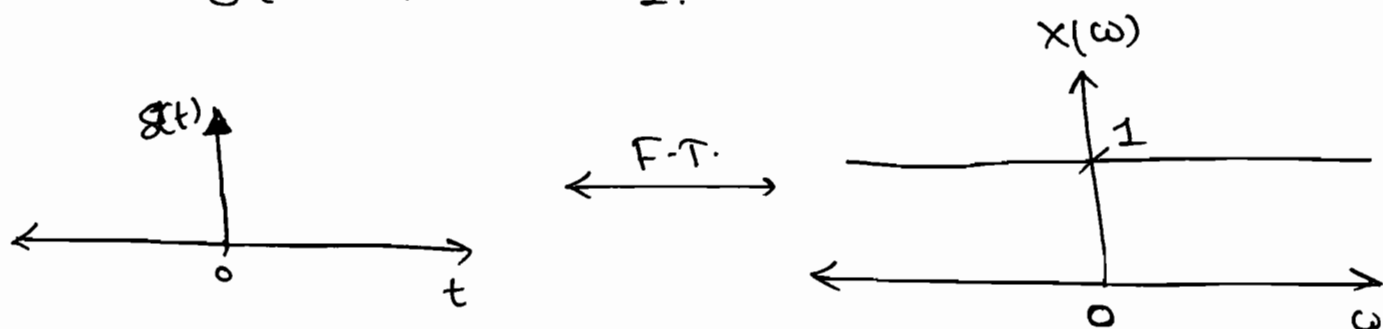
$$X(\omega) = \int_{-\infty}^{\infty} \delta(t) \cdot e^{-j\omega t} dt$$

$$X(\omega) = e^{-j\omega(0)} \quad \text{at } t_0 = 0$$

(shifting property of impulse).

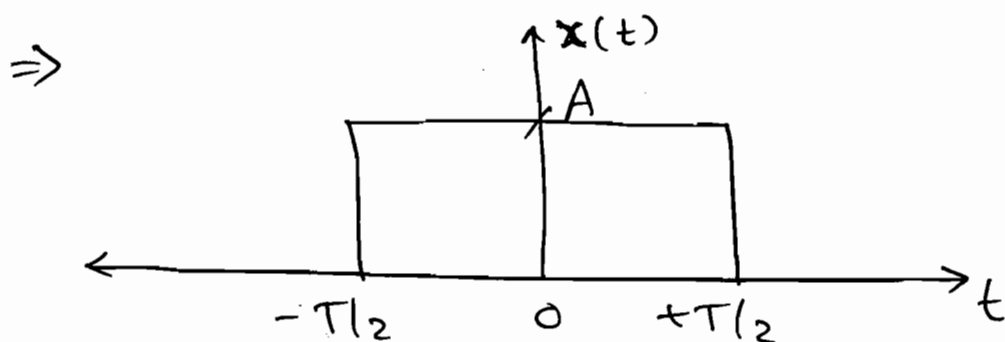
$$\boxed{X(\omega) = 1}$$

$$\therefore \delta(t) \xleftrightarrow{F.T.} 1.$$



$\Rightarrow$ Spectrum of impulse is constant for all the frequencies.

$$\textcircled{4} \quad x(t) = A \text{rect}(t|_T) \quad (\text{or}) \quad A \pi(t|_T).$$



$$\Rightarrow \quad X(\omega) = \int_{-\infty}^{+\infty} x(t) \cdot e^{-j\omega t} \cdot dt.$$

$$\therefore X(\omega) = \int_{-T/2}^{+T/2} A \cdot e^{-j\omega t} \cdot dt.$$

$$= A \left[\frac{e^{-j\omega t}}{-j\omega} \right]_{-T/2}^{+T/2}$$

$$\therefore X(\omega) = \frac{A}{j\omega} \left[e^{j\frac{\omega T}{2}} - e^{-j\frac{\omega T}{2}} \right].$$

$$= \frac{A}{j\omega} \times 2j \left[\frac{e^{j\frac{\omega T}{2}} - e^{-j\frac{\omega T}{2}}}{2j} \right]$$

$$= \frac{2A}{\omega} \times \sin \frac{\omega T}{2}$$

$$= \frac{2A}{\omega} \times \frac{1}{\frac{\omega T}{2}} \times \frac{\omega T}{2} \sin \frac{\omega T}{2}$$

$$= \frac{2A}{\omega} \times \frac{\omega T}{2} \times \frac{\sin \frac{\omega T}{2}}{\frac{\omega T}{2}}$$

$$\therefore \boxed{X(\omega) = AT \operatorname{sinc}\left(\frac{\omega T}{2}\right)} \quad \checkmark$$

$$\Rightarrow \operatorname{sinc}(x) = \frac{\sin(x)}{x}$$

$$\operatorname{sinc}(x) = \frac{\sin(\pi x)}{x} = \frac{\sin \pi x}{\pi x}$$

$$\Rightarrow \operatorname{sinc}\left(\frac{x}{\pi}\right) = \frac{\sin\left(\frac{\pi x}{\pi}\right)}{\frac{\pi x}{\pi}}$$

$$= \frac{\sin x}{x} = \operatorname{sinc}(x)$$

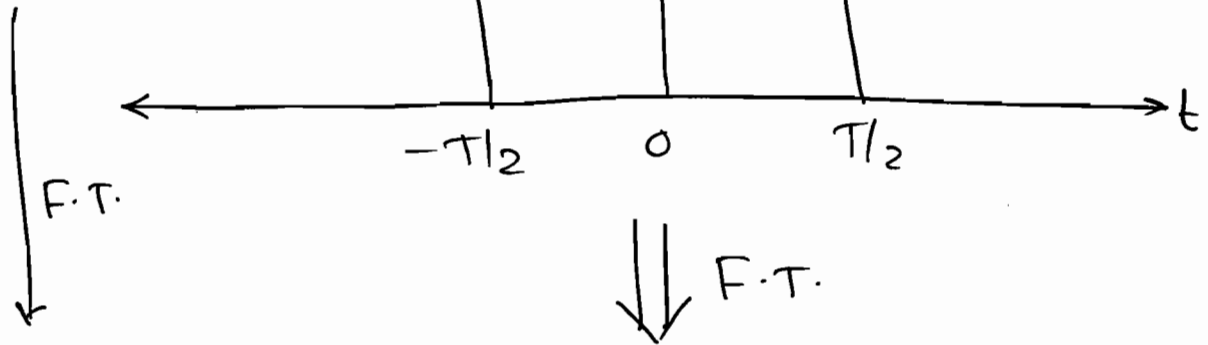
$$\Rightarrow \boxed{\operatorname{sinc}\left(\frac{x}{\pi}\right) = \operatorname{sinc}(x)}$$

$$\therefore \boxed{X(\omega) = AT \operatorname{sinc}\left(\frac{\omega T}{2\pi}\right)} \quad \checkmark$$

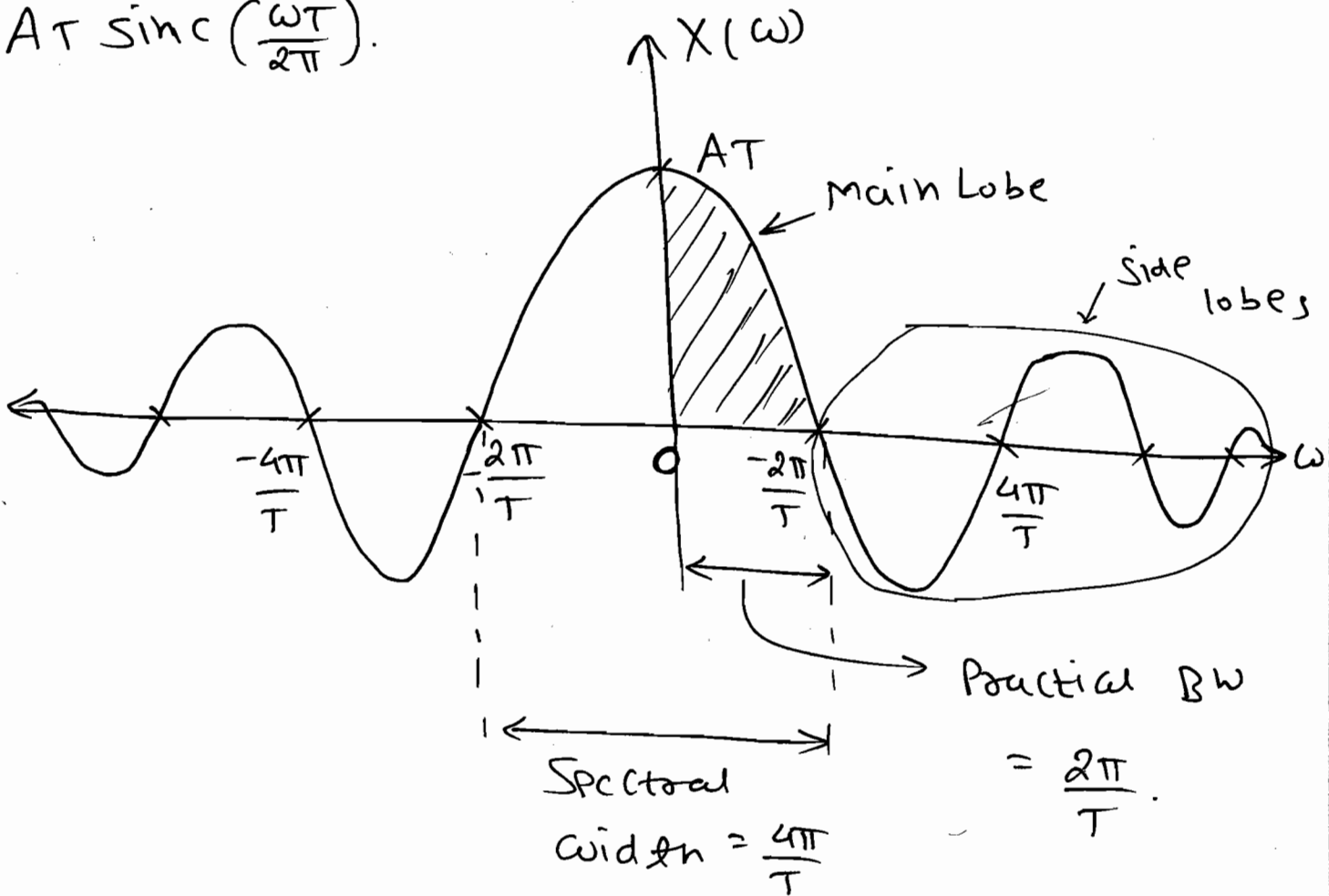
$$= AT \operatorname{sinc}(fT) \quad (\because \omega = \frac{2\pi}{T})$$

⇒

$$A \text{rect}(t/\tau)$$



$$AT \text{sinc}\left(\frac{\omega T}{2\pi}\right)$$



⇒ Area under spectrum is

⇒ Value (Amp) of signal at $t=0$.

⇒ Area under signal ⇒ Value (Amp) of spectrum at $t=0$
 $\omega=0$.

$$\Rightarrow \text{Practical BW} = \frac{2\pi}{T}$$

$$\text{Spectrum width} = \frac{4\pi}{T}$$

$\Rightarrow$ Signal is zero at multiple of $\frac{2\pi}{T}$ of ω .

$$\Rightarrow \boxed{\text{Null to Null BW} = \text{Zero crossing BW} = \frac{2\pi}{T}}$$

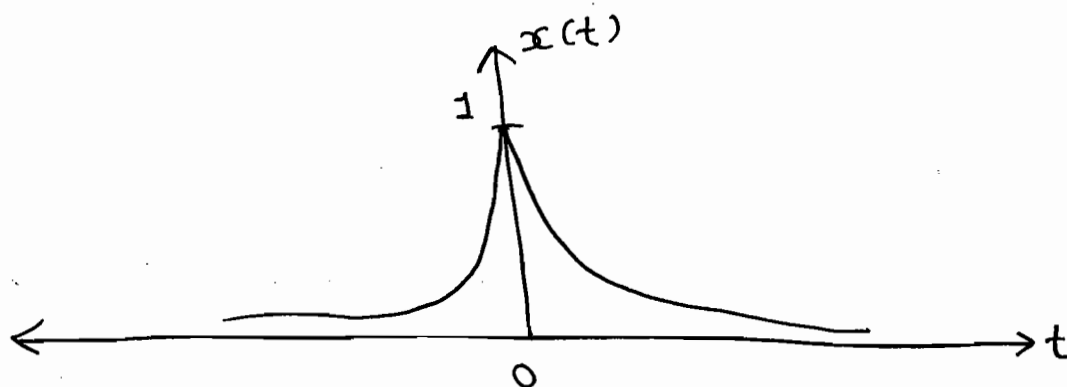
$\Rightarrow$ A signal can not be time limited and Band limited simultaneously.

$\Rightarrow$ Narrow Band in one domain becomes wideband in other domain.

$$(5) \quad x(t) = e^{-\alpha|t|}$$

$$\Rightarrow x(t) = e^{-\alpha t}; \quad t > 0$$

$$= e^{\alpha t}; \quad t < 0.$$



$$\therefore y(t) = e^{-\alpha t} \cdot u(t) + e^{\alpha t} \cdot u(-t).$$

$$= \frac{1}{\alpha + j\omega} + \frac{1}{\alpha - j\omega}.$$

$$y(t) = \frac{2\alpha}{\alpha^2 + \omega^2}.$$

$$\therefore \boxed{e^{-\alpha|t|} \xleftrightarrow{\text{F.T.}} \frac{2\alpha}{\alpha^2 + \omega^2}}.$$

Method - II:

$$\Rightarrow \text{secu} \longleftrightarrow \text{even}.$$

$$\text{e.g. } x(t) = e^{-\alpha t} \cdot u(t).$$

$$X(\omega) = \frac{1}{\alpha + j\omega} \times \frac{\alpha - j\omega}{\alpha - j\omega}.$$

$$X(\omega) = \frac{\alpha - j\omega}{\alpha^2 + \omega^2}.$$

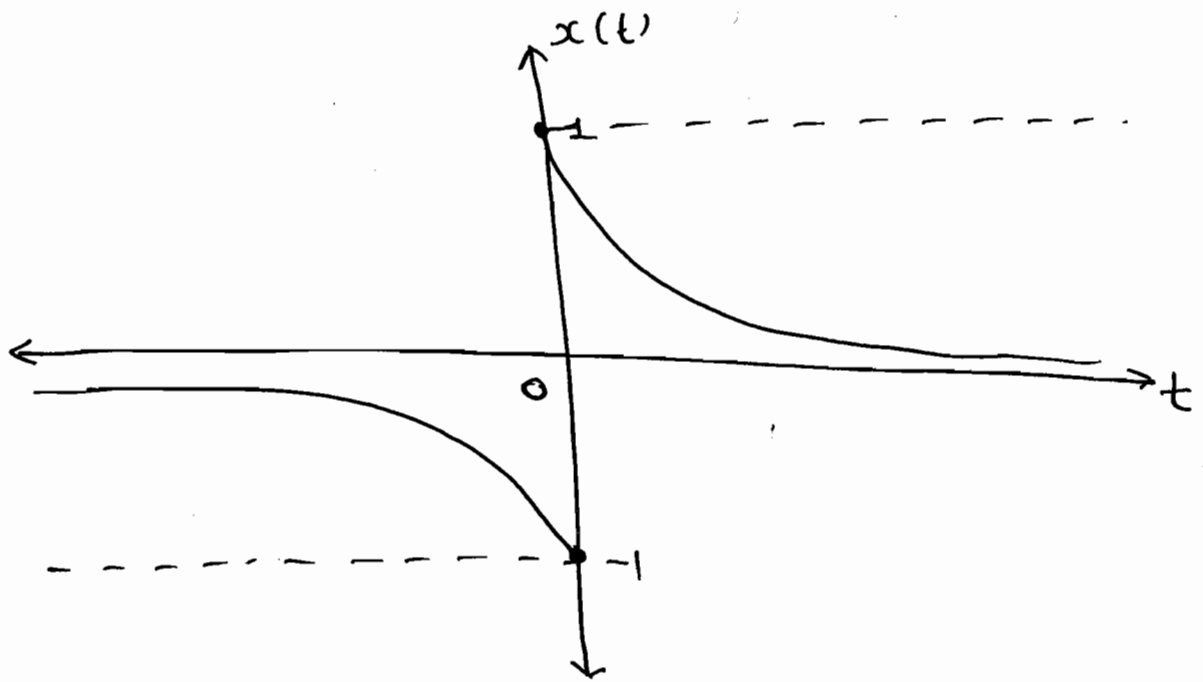
$$\Rightarrow x_{\text{even}}(t) = \frac{x(t) + x(-t)}{2}$$

$$= \frac{X(\omega) + X(-\omega)}{2}$$

$$\boxed{x_{\text{even}}(t) = \frac{2\alpha}{\alpha^2 + \omega^2}}.$$

$$\textcircled{6} \quad x(t) = e^{-\alpha t} u(t) - e^{\alpha t} \cdot u(-t).$$

$\Rightarrow$



$$\Rightarrow \quad X(\omega) = \frac{\alpha - j\omega}{\alpha^2 + \omega^2} - \frac{\alpha + j\omega}{\alpha^2 + \omega^2}.$$

$$\boxed{X(\omega) = \frac{-2j\omega}{\alpha^2 + \omega^2}}$$

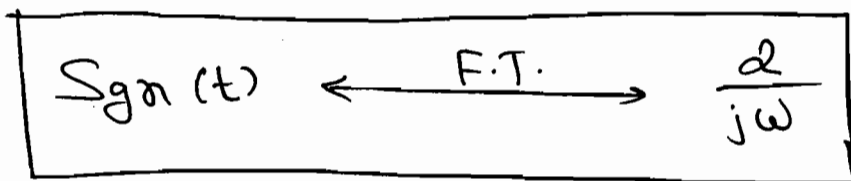
$\Rightarrow$ Real $\longleftrightarrow$ Odd.

Now, say $\alpha \rightarrow 0$

$$\begin{aligned} \lim_{\alpha \rightarrow 0} X(\omega) &= \lim_{\alpha \rightarrow 0} \frac{-2j\omega}{\alpha^2 + \omega^2} = \frac{-2j\omega}{\omega^2} \\ &= \frac{2}{j\omega}. \end{aligned}$$

$$\begin{aligned} \text{Now, } \lim_{\alpha \rightarrow 0} y(t) &= \lim_{\alpha \rightarrow 0} e^{-\alpha t} u(t) - e^{\alpha t} u(-t). \\ &= u(t) - u(-t) = \text{sgn}(t). \end{aligned}$$

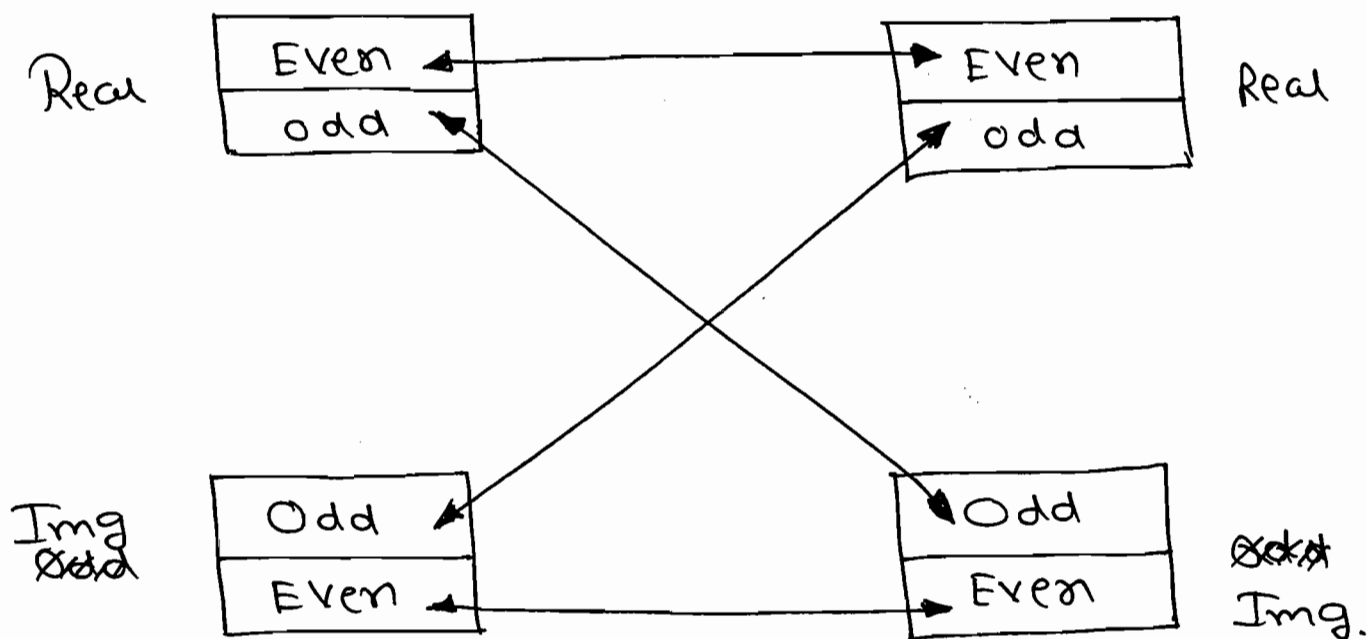
⇒



Real & odd

Imag & odd.

*



* Properties Of F.T.:

① Duality:

⇒ $x(t) \longleftrightarrow X(\omega).$

$X(t) \longleftrightarrow 2\pi x(-\omega).$

⇒ $x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) \cdot e^{j\omega t} \cdot d\omega.$

replace t by $-t$.

∴ $x(-t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) \cdot e^{-j\omega t} \cdot d\omega.$

$$\therefore 2\pi x(-t) = \int_{-\infty}^{+\infty} X(\omega) \cdot e^{-j\omega t} \cdot d\omega.$$

$$t \leftrightarrow \omega$$

$$\therefore 2\pi x(-\omega) = \int_{-\infty}^{\infty} X(t) \cdot e^{-j\omega t} \cdot dt.$$

$$\boxed{2\pi x(-\omega) = X(t).}$$

egs:

$$i) \quad e^{3t} u(-t) \longleftrightarrow \frac{1}{3-j\omega}$$

$$\frac{1}{3-jt} \xleftrightarrow{t=-\omega} 2\pi e^{3(-\omega)} \cdot u(\omega).$$

ii)

$$e^{-|t|} \longleftrightarrow \frac{2}{t^2+1}$$

$$\frac{2}{t^2+1} \longleftrightarrow 2\pi e^{-|\omega|}$$

$$\Rightarrow 2\pi e^{-|\omega|} //$$

iii)

$$\delta(t) \longleftrightarrow 1$$

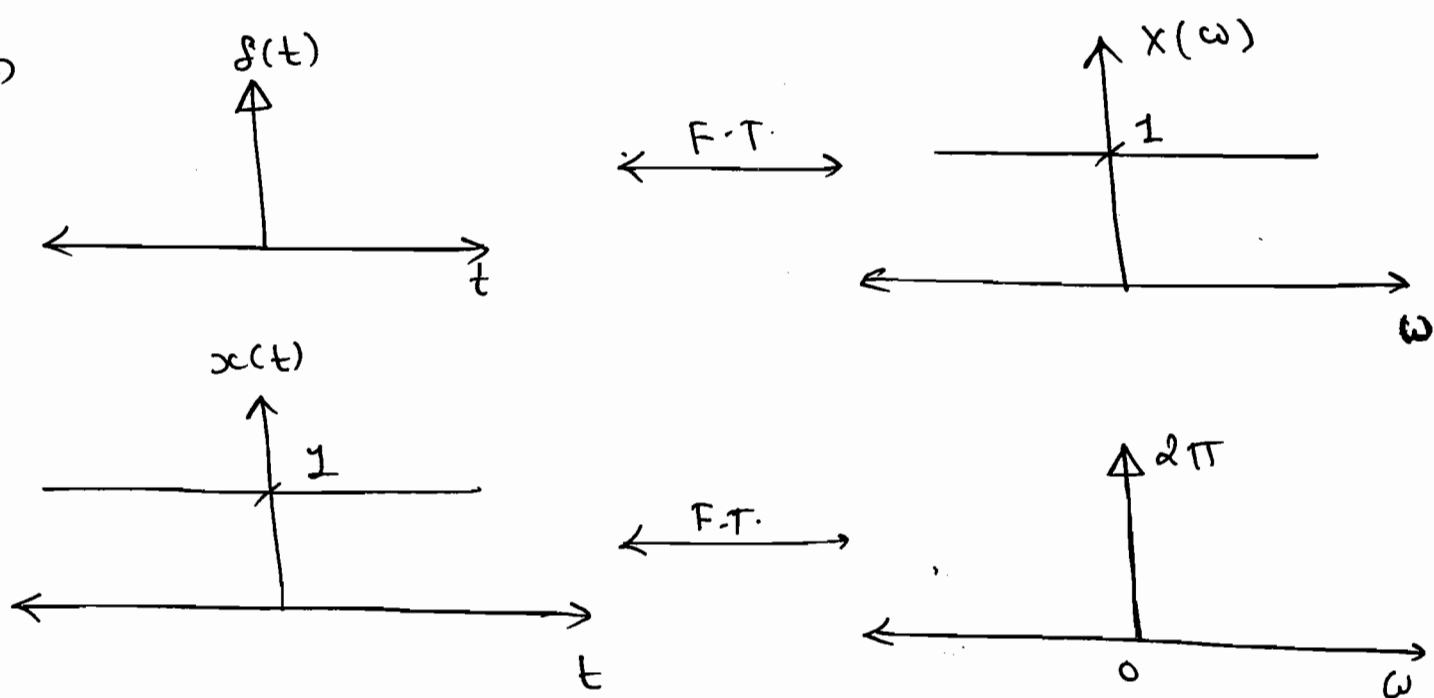
$$1 \longleftrightarrow 2\pi \delta(-\omega)$$

$$= \frac{2\pi}{|-1|} \cdot \delta(\omega)$$

$$= 2\pi \cdot \delta(\omega).$$

$$= \delta(f).$$

⇒



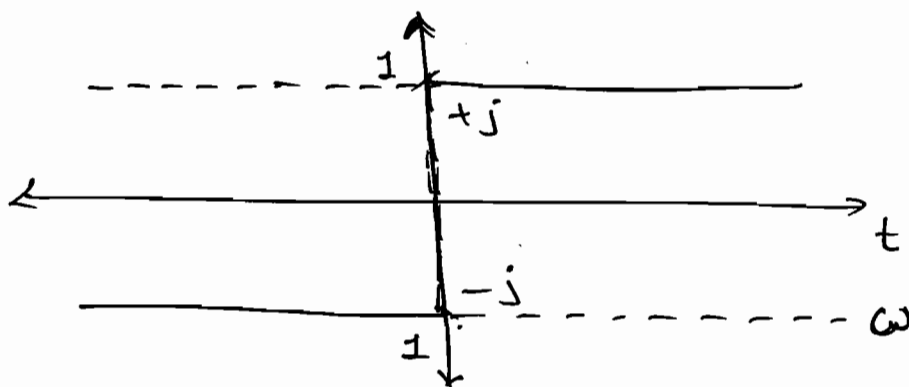
(iv)

$$\text{Sgn}(t) \xleftrightarrow{\text{F.T.}} \frac{2}{j\omega}$$

$$\frac{2}{jt} \xleftrightarrow{\text{F.T.}} 2\pi \text{Sgn}(-\omega)$$

$$\frac{1}{jt} \xleftrightarrow{\text{F.T.}} -\pi \text{Sgn}(\omega)$$

$$\therefore \boxed{\frac{1}{\pi t} \xleftrightarrow{\text{F.T.}} -j \text{Sgn}(\omega)}$$



⇒ Impulse response of Hilbert Transform.

⇒ To set the additional $\pi/2$ phase angle we have to design $\frac{1}{\pi t}$ system in time domain.

$$\Rightarrow \text{Sgn}(t) = 2u(t) - 1.$$

$$\therefore u(t) = \frac{1 + \text{Sgn}(t)}{2}$$

$$\therefore u(t) \xleftrightarrow{\text{F.T.}} \frac{2\pi\delta(\omega) + \frac{2}{j\omega}}{2}$$

$$\Rightarrow \boxed{u(t) \xleftrightarrow{\text{F.T.}} \frac{1}{j\omega} + \pi\delta(\omega).} \quad \checkmark$$

$\Rightarrow$ rect in time domain $\longleftrightarrow$ Sa in freq.

$$\text{rect}\left(\frac{t}{2a}\right) \longleftrightarrow \int_{-a}^a du \, \text{Sa}\left(\frac{\omega u}{2}\right).$$

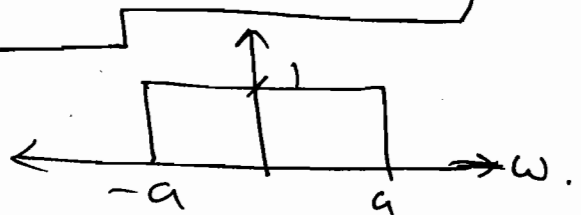
$$\text{rect}\left(\frac{t}{2a}\right) \longleftrightarrow 2a \cdot \text{Sa}(\omega a).$$

Duality

$$2a \cdot \text{Sa}(\omega a) \longleftrightarrow 2\pi \cdot \text{rect}\left(-\frac{\omega}{2a}\right).$$

$$a \cdot \frac{\sin(\omega a)}{\omega} \longleftrightarrow \pi \cdot \text{rect}\left(\frac{\omega}{2a}\right). \quad (\text{even}).$$

$$\therefore \boxed{\frac{\sin(\omega a)}{\pi \omega} \longleftrightarrow \text{rect}\left(\frac{\omega}{2a}\right).} \quad \checkmark$$



② Time Scaling:-

$$\Rightarrow \text{If } x(t) \longleftrightarrow X(\omega).$$

$$x(\alpha t) \longleftrightarrow \frac{1}{|\alpha|} \cdot X(\omega/\alpha).$$

Compression $\longleftrightarrow$ Expansion.

e.g.

$$\text{let, } x(t) = A \text{ rect}(t/T).$$

$$\therefore A \text{ rect}(t/T) \longleftrightarrow AT \text{ sa}\left(\frac{\omega T}{2}\right).$$

$$\text{Now, } y(t) = A \text{ rect}\left(\frac{2t}{T}\right).$$

$$y(t) = X(2t).$$

$$\therefore Y(\omega) = \frac{1}{2} X(\omega/2).$$

$$= \frac{AT}{2} \text{ sa}\left(\frac{\frac{\omega}{2} \cdot T}{2}\right).$$

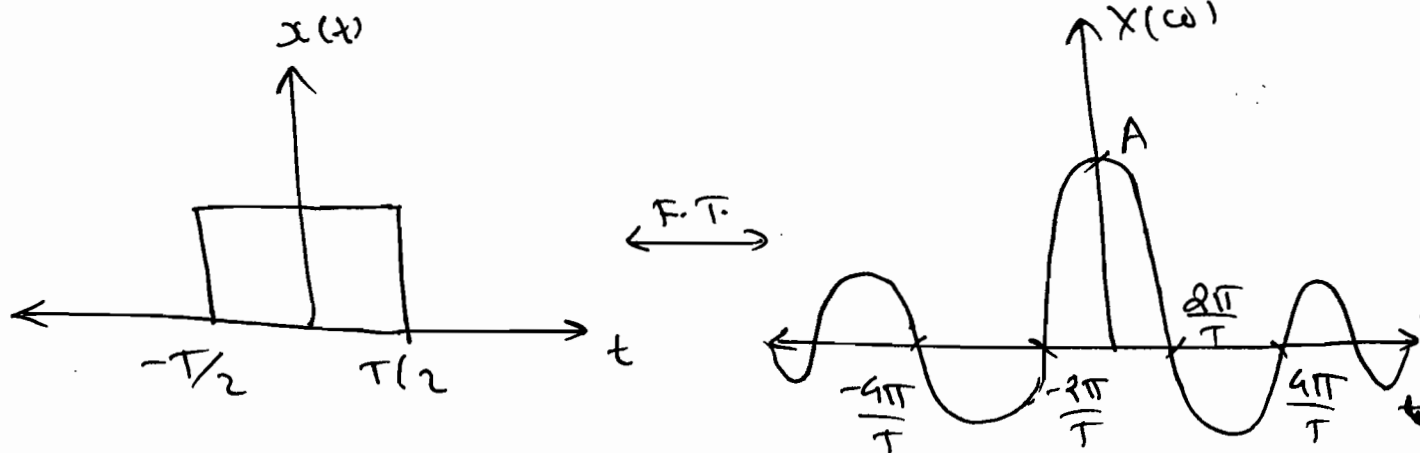
$$Y(\omega) = \frac{AT}{2} \text{ sa}\left(\frac{\omega T}{4}\right).$$

$$\therefore \frac{\omega T}{4} = \pm n\pi \Rightarrow \omega = \pm \frac{4n\pi}{T}.$$

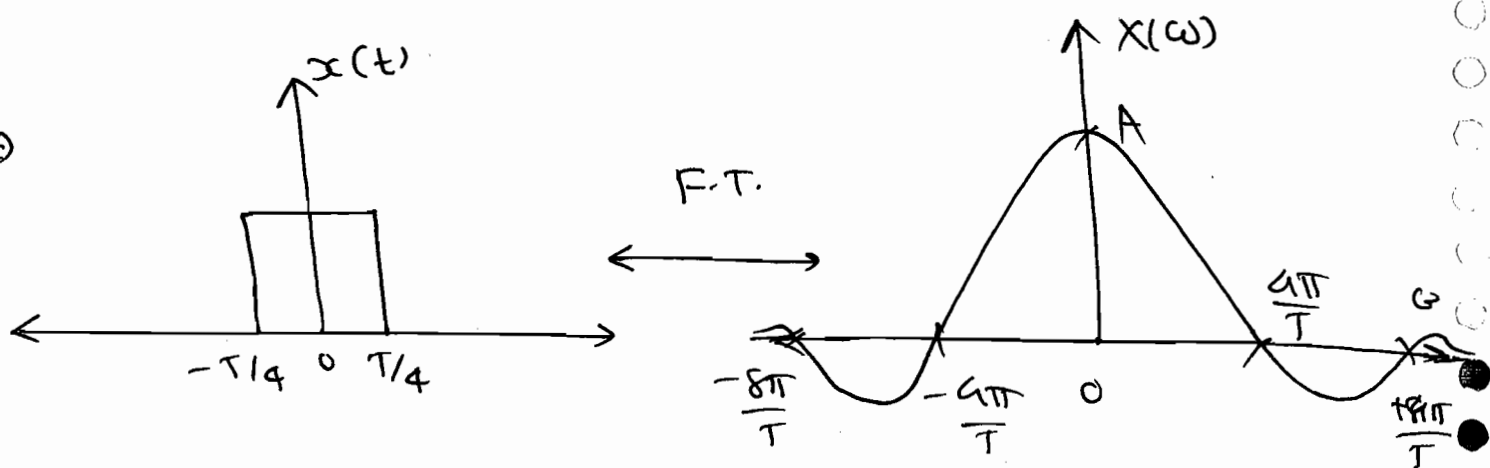
$$\therefore Y(\omega) = \frac{AT}{2} \text{ sinc}\left(\frac{\omega T}{4\pi}\right).$$

$$\omega = \pm \frac{4n\pi}{T}.$$

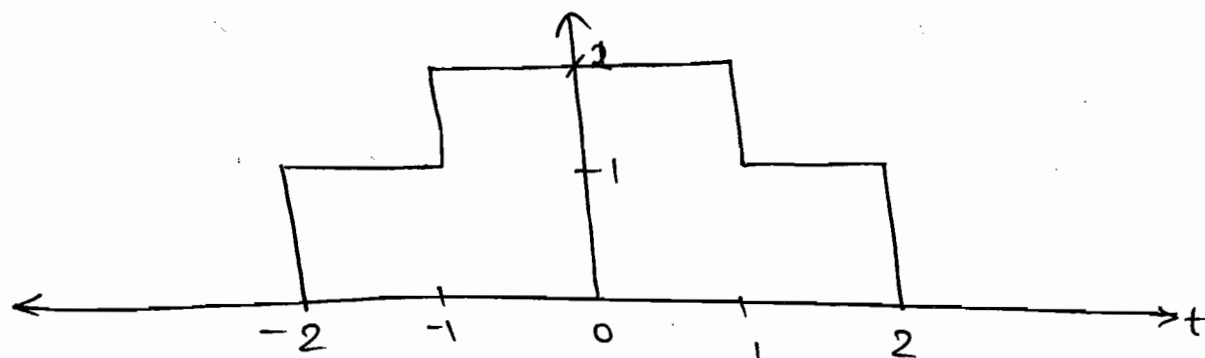
⇒



⇒

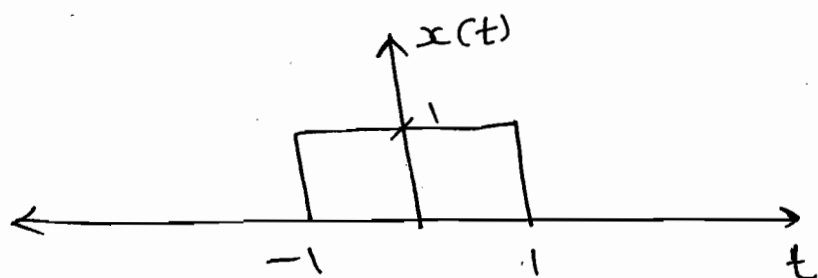


P4.2.4. Find the F.T. of the signal shown in fig?



Soln:

let, $x(t) = 1 \cdot \text{rect}(t/2)$.



∴ $y(t) = 2x(t) + x(t/2)$.

$$\therefore 1. \text{rect}(t/2) \longleftrightarrow 2 \text{sinc}\left(\frac{\omega}{2}\right) \\ \Rightarrow 2 \text{sinc}(\omega).$$

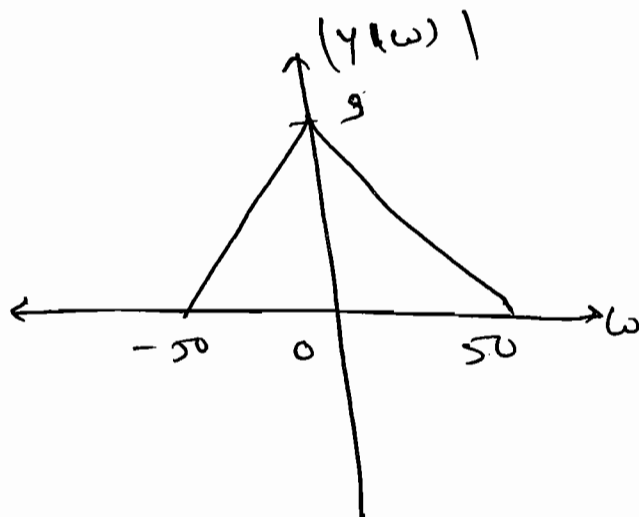
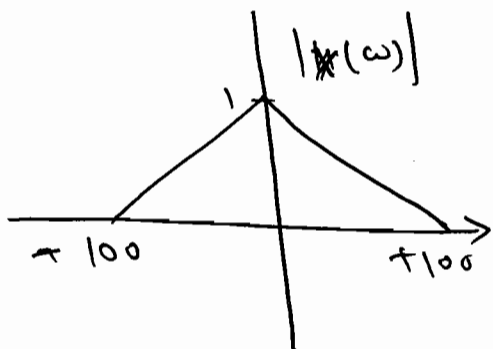
$$\therefore y(t) = x(t) + x(t/2).$$

$$\therefore Y(\omega) = 2 \text{sinc}(\omega) + \frac{1}{|1/2|} \cdot X(2\omega/2).$$

$$\therefore Y(\omega) = 2 \text{sinc}(\omega) + 2 \text{sinc}(2\omega/2).$$

$$\therefore Y(\omega) = 2 \text{sinc}(\omega) + 4 \text{sinc}(2\omega).$$

P4.2.5 The magnitude of F.T. $X(\omega)$ of a function in fig (a) the magnitude of F.T. $Y(\omega)$ of other function $y(t)$ is shown below in fig (b). The phases $X(\omega)$ and $Y(\omega)$ are zero for all ω . The magnitude and frequency units are identical in both the figures. The fn $y(t)$ can be expressed in terms of $x(t)$ as _____



Soln:

$$|Y(\omega)| = 3|x(2\omega)|$$

$$= 3 \cdot x(\omega/2)$$

$$= 3 \cdot \frac{1}{2} \cdot \frac{1}{\gamma_2} x(\omega/2)$$

$$\therefore \boxed{y(t) = \frac{3}{2} x(t/2)}$$

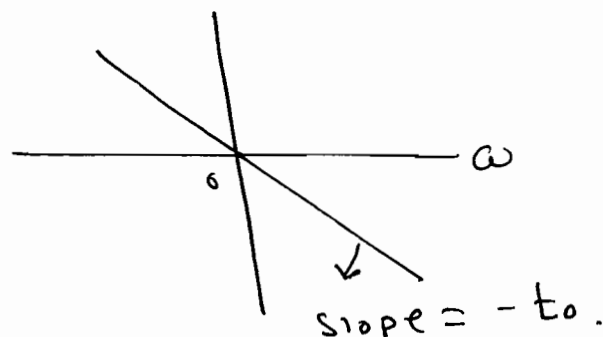
③ Time - Shifting:

$$\Rightarrow \text{If } x(t) \xleftrightarrow{\text{F.T.}} X(\omega)$$

$$\text{then } \boxed{x(t-t_0) \xleftrightarrow{\text{F.T.}} e^{-j\omega t_0} X(\omega)}$$

$\Rightarrow$ Time-delay in a signal causes a linear phase shift in its spectrum. Shifting in time doesn't alter the amplitude spectrum of signal.

$$\therefore \theta(\omega) = -\omega t_0$$



e.g. ① $y(t) = e^{2t} \cdot u(t) \cdot u(-t+3)$

Soln: $y(t) = e^{2(t-3)+6} \cdot u(-(t-3))$

$$\therefore Y(\omega) = e^6 \left[\frac{e^{-j\omega(3)}}{2 - j\omega} \right]$$

$$(2) \quad y(t) = \text{rect} \left(\frac{t+1}{4} \right)$$

Soln:

$$\text{let, } x(t) = \text{rect} \left(\frac{t+1}{4} \right), \quad A=1, \quad T=4.$$

$$\therefore y(t) = x(t+1). \quad \text{where,}$$



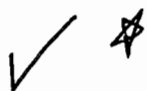
$$t_0 = -1.$$

F.T.

$$Y(\omega) = e^{j\omega} \cdot X(\omega).$$

$$\& \quad X(\omega) = 4 \cdot \text{sinc} \left(\frac{4\omega}{2} \right).$$

$$\therefore \boxed{Y(\omega) = 4 e^{j\omega} \cdot \text{sinc}(2\omega)}.$$



Q

$$\text{given } h(\omega) = \frac{4 \sin 2\omega \cdot \cos \omega}{\omega}, \text{ find } h(\omega).$$

Soln:

$$h(\omega) = \frac{4 \sin 2\omega \cdot \cos \omega}{\omega}$$

$$= 2 \left[\frac{2 \sin 2\omega}{\omega} \right] \cdot \cos \omega \times 2$$

$$= 2 \left[\frac{2 \sin \omega \cdot \cos \omega \cdot \cos \omega}{\omega} \right] \times 2$$

$$= 2 \left[\frac{2 \sin \omega}{\omega} \right] \cos^2 \omega \times 2$$

$$= 2 \left[\frac{2 \sin \omega}{\omega} \right] \cdot \left[\frac{1 + \cos 2\omega}{2} \right] \times 2$$

$$= \frac{2 \sin \omega}{\omega} \times 2 + 2 \left[\frac{2 \sin \omega}{\omega} \right] \times \left[\frac{e^{-j2\omega} + e^{j2\omega}}{2} \right]$$

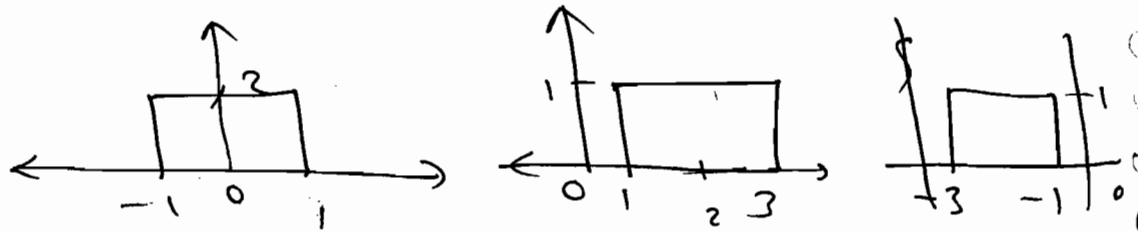
let, $x(t) = \text{rect}(t/2)$

$$\Rightarrow X(\omega) = \frac{2 \sin \omega}{\omega}$$

$$\therefore h(\omega) = 2X(\omega) + \frac{1}{2} X(\omega) e^{-j\omega 2} + \frac{1}{2} X(\omega) e^{j\omega 2}$$

↓ IFT

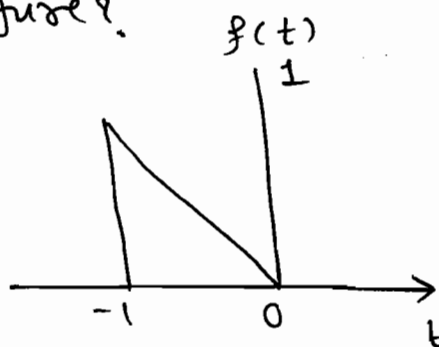
$$\therefore h(t) = 2x(t) + x(t-2) + x(t+2)$$



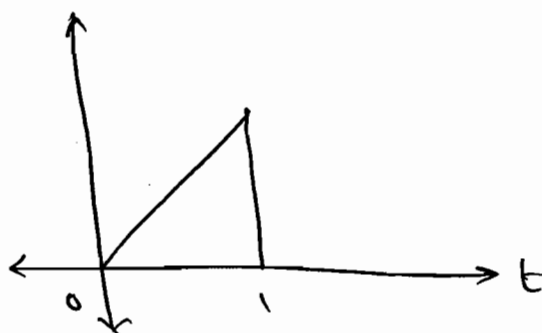
$$\therefore \boxed{h(\omega) = 2}$$

P4.2.11 : The F.T. of a triangular pulse $f(t)$ shown in figure $F(\omega) = \frac{e^{j\omega} - j\omega e^{-1}}{\omega^2}$

using this find the F.T. of the signals shown in figure.



Solⁿ: ① $f_1(t)$



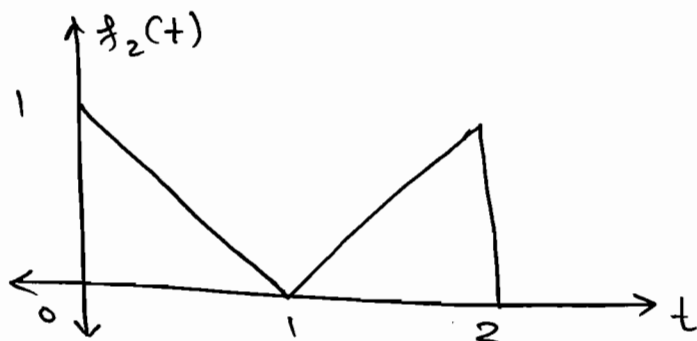
$\Rightarrow$

$$f_1(t) = f(-t).$$

$$\downarrow$$

$$F_1(\omega) = F(-\omega) = \frac{e^{-j\omega} + j\omega e^{-j\omega} - 1}{\omega^2}.$$

(2)



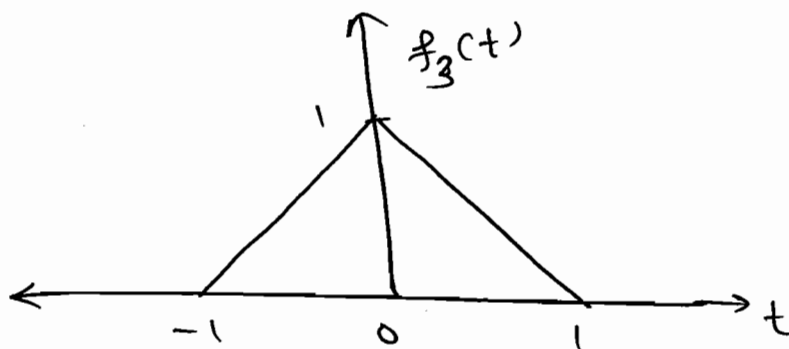
Solⁿ:

$$f_2(t) = f_1(t-1) + f(t-1).$$

$\downarrow$ F.T.

$$\therefore F_2(\omega) = e^{-j\omega} F_1(\omega) + e^{-j\omega} F_2(\omega).$$

(3)

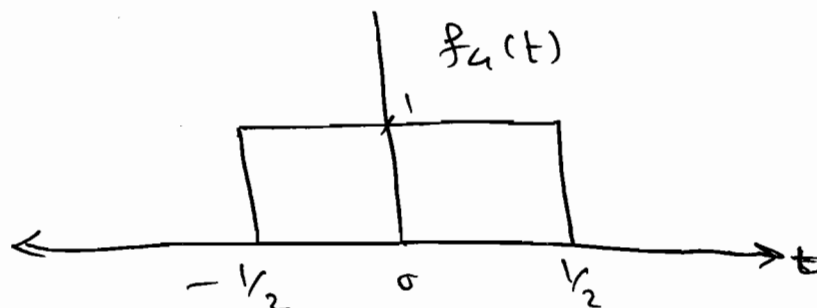


Solⁿ:

$$f_3(t) = f_1(t+1) + f(t-1).$$

$$F_3(\omega) = e^{j\omega} F_1(\omega) + e^{-j\omega} F(\omega).$$

(4)

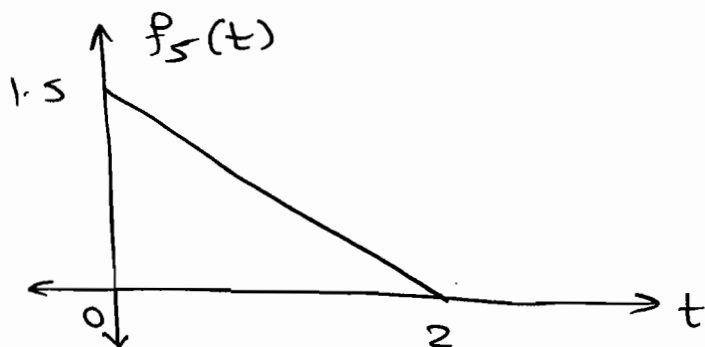


Soln:

$$f_4(t) = f(t - \frac{1}{2}) + f_1(t + \frac{1}{2}).$$

$$\therefore F_4(\omega) = e^{-j\frac{1}{2}\omega} \cdot F(\omega) + e^{+j\frac{\omega}{2}} \cdot F_1(\omega).$$

⑤



Soln:

$$f_5(t) = 1.5 f\left(\frac{t}{2} - 1\right).$$

$$= 1.5 f\left(\frac{t-2}{2}\right) \quad \begin{matrix} \nearrow t_0 = 2. \\ \downarrow \alpha = \frac{1}{2} \end{matrix}$$

$$\therefore F_5(\omega) = \frac{1.5}{\frac{1}{2}} \cdot e^{-j2\omega} \cdot F(\omega/\frac{1}{2}).$$

$$\therefore \boxed{F_5(\omega) = 3 \cdot e^{-j2\omega} \cdot F(2\omega).}$$

④ Frequency Shifting:

$$\Rightarrow \text{If } x(t) \longleftrightarrow X(\omega).$$

$$\text{then } x(t) \cdot e^{j\omega_c t} \xrightarrow{\text{F.T.}} X(\omega - \omega_c).$$

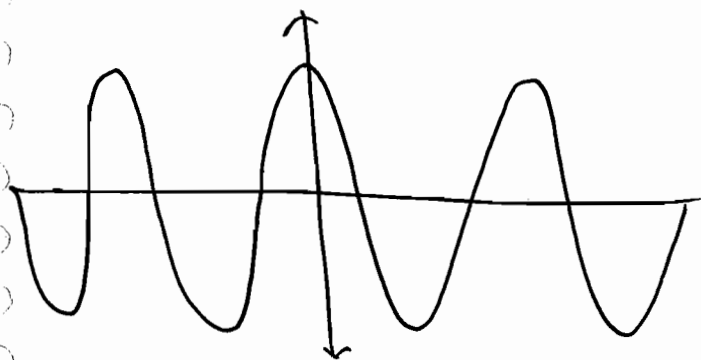
e.g.

$$\cos \omega_0 t = \frac{1 \cdot e^{+j\omega_0 t} + 1 \cdot e^{-j\omega_0 t}}{2}$$

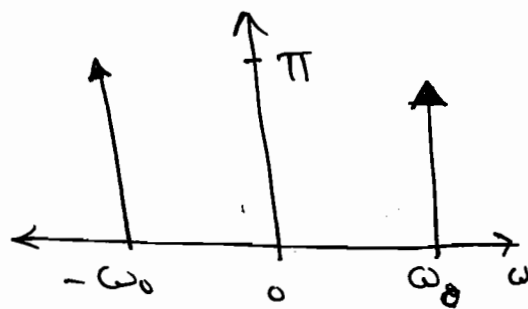
$$\xrightarrow{\text{F.T.}} = \frac{2\pi \delta(\omega - \omega_0) + 2\pi \delta(\omega + \omega_0)}{2}$$

$$\therefore \cos \omega_0 t \xleftrightarrow{F.T.}$$

$$\frac{\delta(f - f_c) + \delta(f + f_c)}{2}$$



$\xleftrightarrow{F.T.}$



$$\Rightarrow e^{-3t} \cdot \sin 6t \cdot u(t) \Rightarrow \text{damped oscillation.}$$

reference signal.

$$\Rightarrow \text{rect}(t/4) \cdot \cos 6t \leftarrow \text{reference pulse.}$$

Q F.T. of $y(t) = \text{sinc}(t) \cdot \cos 10\pi t$.

Soln:

$$y(t) = \underset{\downarrow F.T.}{\text{sinc}(t)} \cdot \underset{\downarrow x(t)}{\left[\frac{e^{j10\pi t} + e^{-j10\pi t}}{2} \right]}$$

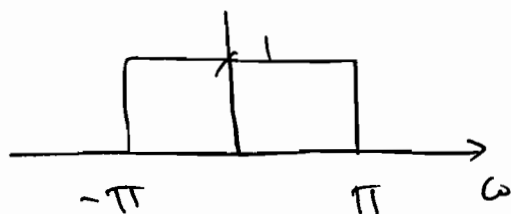
$$Y(\omega) = \frac{X(\omega - 10\pi) + X(\omega + 10\pi)}{2}$$

$$x(t) = \text{sinc}(t) = \frac{\sin \pi t}{\pi t} \quad (a = \pi)$$

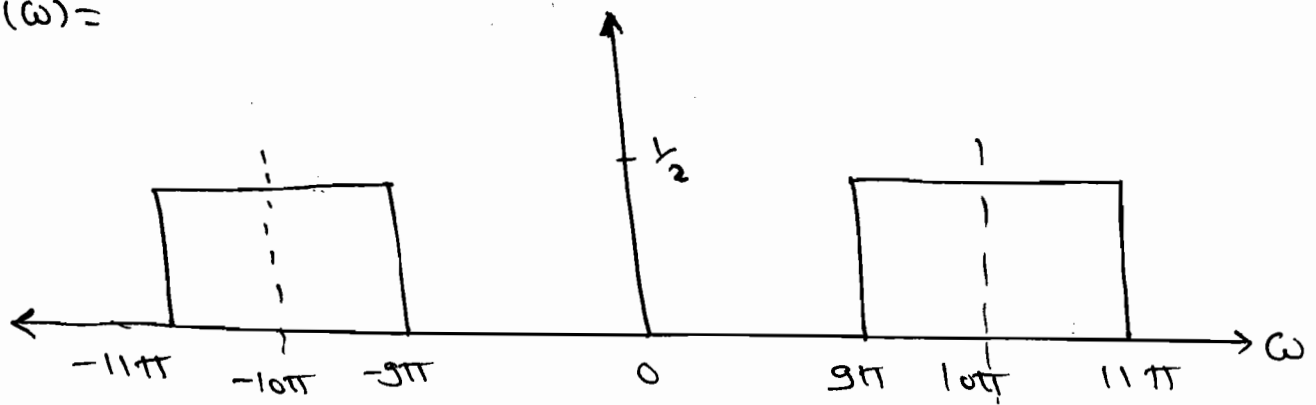
$$\Rightarrow X(\omega) = \text{rect}(\omega/2\pi)$$

$$X(\omega) = \text{rect}(\omega/2\pi)$$

$$\therefore X(\omega) \Rightarrow$$



$$\therefore Y(\omega) =$$



Q I.F.T. of $X(4\omega + 3)$.

Soln:

$$Y(\omega) = X(4(\omega + 3/4)).$$

$$= \frac{1}{4} \cdot \frac{1}{|3/4|} \cdot X(\omega/1/4).$$

$$Y(t) = \frac{1}{4} \cdot x(t/4) \cdot e^{-j(3/4)t}$$

Note:

$\Rightarrow$ When we perform time differentiation $S(\omega)$ component is lost since $j\omega S(\omega) = 0$ and the original spectrum magnitudes are increased by the factor $|\omega|$ i.e. high freq. components are more amplified.

⑤ Differentiation in time:

$$\Rightarrow \text{If } x(t) \xleftrightarrow{\text{F.T.}} X(\omega)$$

$$\text{then } \frac{d}{dt} x(t) \xleftrightarrow{\text{F.T.}} (j\omega) X(\omega).$$

but, $X(\omega) \neq \frac{F.T. \left\{ \frac{d}{dt} x(t) \right\}}{j\omega}$.

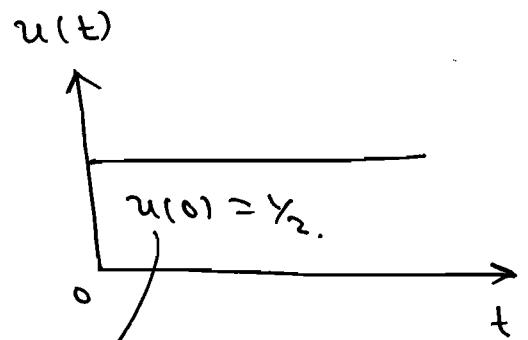
e.g. ① $x(t) = u(t)$.

$$\frac{d}{dt} x(t) = \delta(t).$$

$$\therefore j\omega X(\omega) = 1.$$

$$X(\omega) = \frac{1}{j\omega} + \pi \delta(\omega).$$

(missed by differentiation)



$$\Rightarrow j\omega \delta(\omega) = j(0) \cdot \delta(\omega) = 0.$$

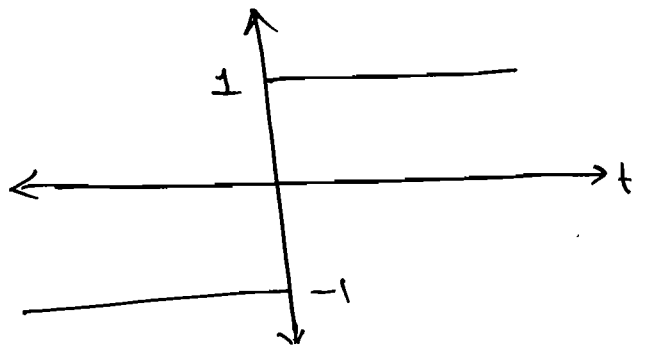
② $x(t) = \text{Sgn}(t)$

$$x(t) = 2u(t) - 1$$

$$\therefore \frac{d}{dt} x(t) = 2\delta(t)$$

$$\therefore j\omega X(\omega) = 2.$$

$$\boxed{X(\omega) = 2/j\omega.} \quad \checkmark$$



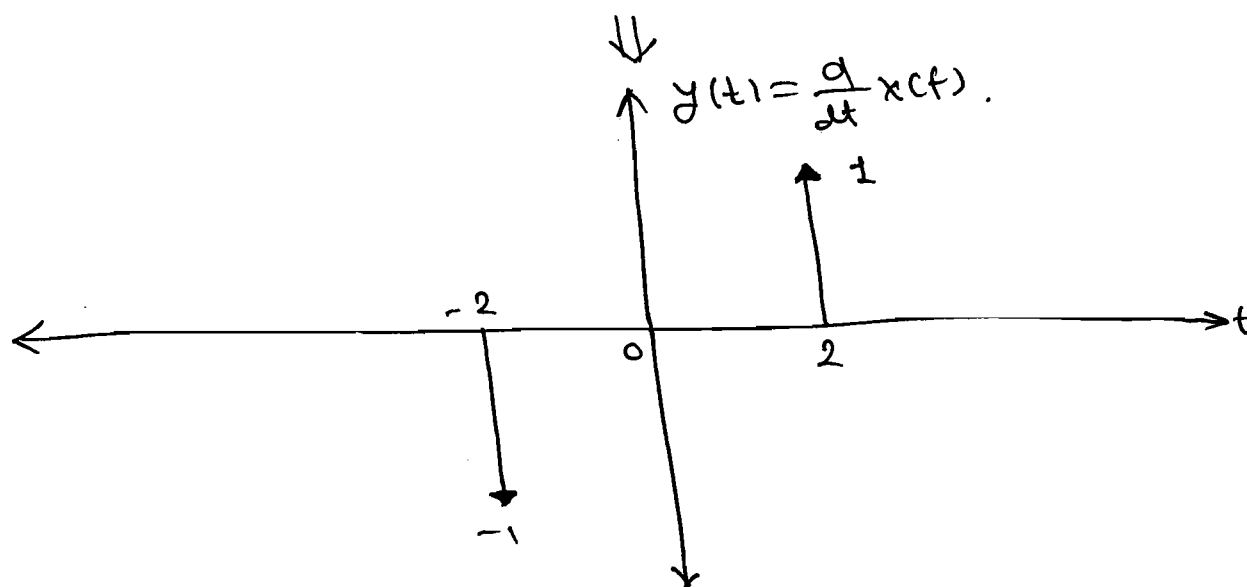
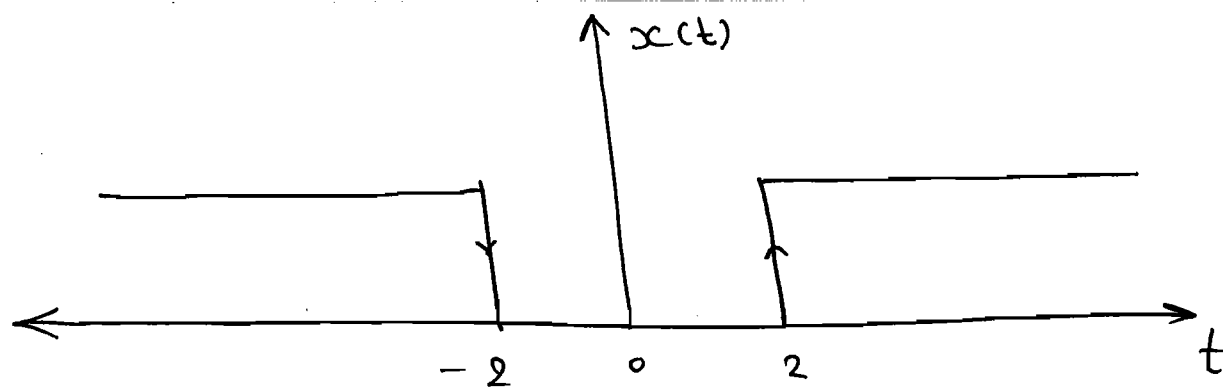
P. 4.2.16 Find the F.T. of the signal

$$y(t) = \frac{d}{dt} [u(t-2) + u(-t-2)].$$

Soln: $y(t) = \frac{d}{dt} [u(t-2) + u(-t-2)].$

$$y(t) = \delta(t-2) - \delta(t+2).$$

⇒



$$\therefore y(t) = -1 \cdot \delta(t+2) + \delta(t-2).$$

$$Y(\omega) = -e^{j2\omega} \cdot (1) + e^{-j2\omega} \cdot (1).$$

$$= -\frac{1}{2j} \left[\frac{e^{+j2\omega}}{2j} - \frac{e^{-j2\omega}}{2j} \right].$$

$$= -\frac{1}{2j} \times \sin(2\omega).$$

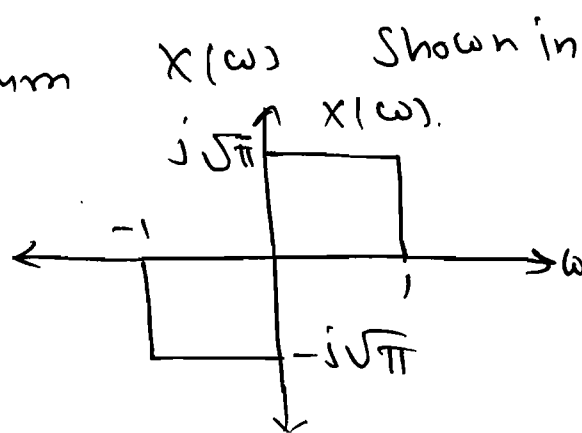
$$Y(\omega) = \frac{j \sin(2\omega)}{2}$$

★

P 4.2.17

For the Spectrum $X(\omega)$ shown in figure,

find $\frac{d}{dt} x(t)$ at $t=0$?



Soln:

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} x(\omega) \cdot e^{j\omega t} \cdot d\omega.$$

$$\therefore \frac{dx(t)}{dt} = \frac{1}{2\pi} \int_{-\infty}^{\infty} (j\omega) x(\omega) \cdot e^{j\omega t} \cdot d\omega.$$

$$\left. \frac{d}{dt} x(t) \right|_{t=0} = \frac{j\omega}{2\pi} \int_{-\infty}^{\infty} x(\omega) \cdot d\omega.$$

$$= \frac{1}{2\pi} \int_{-\infty}^{+\infty} (j\omega) x(\omega) \cdot d\omega.$$

$$= \frac{1}{2\pi} \left[\int_{-1}^0 (j\omega) (-j\sqrt{\pi}) (j\omega) d\omega + \int_0^1 (j\sqrt{\pi}) (j\omega) d\omega \right].$$

$$= \frac{1}{2\pi} \left[\sqrt{\pi} \left(\frac{\omega^2}{2} \right)_{-1}^0 - \sqrt{\pi} \left(\frac{\omega^2}{2} \right)_0^1 \right].$$

$$= \frac{1}{2\pi} \left[-\frac{\sqrt{\pi}}{2} - \frac{\sqrt{\pi}}{2} \right].$$

$$= -\frac{\sqrt{\pi}}{2\pi}$$

$$\therefore \boxed{\left. \frac{d}{dt} x(t) \right|_{t=0} = -\frac{1}{2\sqrt{\pi}}}$$

⑥ Frequency Differentiation:

$\Rightarrow$ Diffⁿ w.r.t. one Variable corresponds to multiplication by other Variable.

$$-jt x(t) \xleftrightarrow{\text{F.T.}} \frac{d}{d\omega} x(\omega).$$

e.g. ① $y(t) = t \cdot e^{-at} \cdot u(t).$

$$\therefore y(t) = \frac{-j}{-j} \cdot t \cdot e^{-at} \cdot u(t).$$

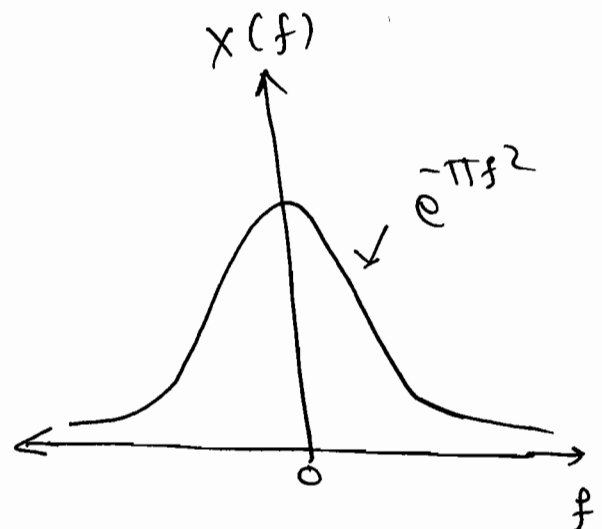
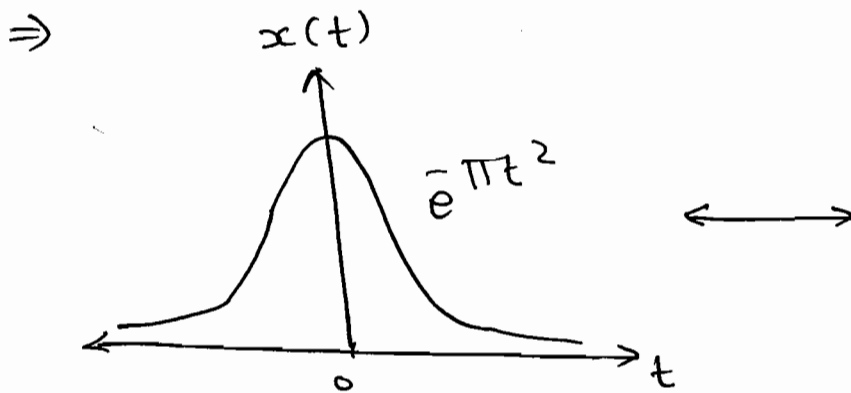
$$= \frac{-1}{j} \cdot (-jt \cdot e^{-at} \cdot u(t)).$$

$$= +j \left[\frac{d}{d\omega} \times \frac{1}{a+j\omega} \right].$$

$$= +j \frac{-1}{(a+j\omega)^2} x(j)$$

$$\therefore Y(\omega) = \frac{1}{(a+j\omega)^2}$$

* Gaussian function:



let, $x(t) = e^{-\pi t^2}$

$$\therefore \frac{d}{dt} x(t) = -e^{-\pi t^2} (2\pi t) = -2\pi t x(t)$$

$$\therefore \frac{d}{dt} x(t) = -2\pi f x(t) \quad \text{--- (I)}$$

$$\therefore j 2\pi f x(t) = -2\pi t \cdot e^{-\pi t^2}$$

$$j(j2\pi f x(t)) = -j2\pi f \cdot e^{-\pi t^2}$$

$$\therefore -2\pi f \cdot x(t) = \frac{d}{dt} x(t).$$

$$\therefore \boxed{\frac{d}{df} x(f) = -2\pi f x(f)} \quad \text{--- (2)}$$

$\Rightarrow$ From eq I & II looking in similar manner $x(f)$ is same as $x(t)$.

$\Rightarrow$ In general,

$$e^{-at^2} \quad (a > 0) \xleftrightarrow{\text{F.T.}} \sqrt{\frac{\pi}{a}} \cdot e^{-\omega^2/4a}$$

P 4.2-20 Given $x(t) \longleftrightarrow X(\omega)$, express the F.T. of the following signals in terms of $X(\omega)$?

(i) $x_1(t) = x(2-t) + x(-t-2)$.

Solⁿ: $x_1(t) = x(-t-2) + x(-(t+2))$.

$$X_1(\omega) = \frac{e^{-j2\omega}}{2} X(-\omega) + \frac{e^{j2\omega}}{2} X(-\omega).$$

$$= \frac{X(-\omega)}{2} \left[\frac{e^{j2\omega}}{2} + \frac{e^{-j2\omega}}{2} \right].$$

$$\therefore \boxed{X_1(\omega) = 2 X(-\omega) \cdot \cos 2\omega}$$

② $x_2(t) = x(3t + 5)$

Sum:
 $x_2(t) = x(3(t-2))$

$$\therefore \boxed{X_2(\omega) = \frac{1}{3} \cdot e^{-j2\omega} \cdot X(\omega/3)}$$

③ $x_3(t) = \frac{d^2}{dt^2} x(t-3)$

Sum:
 $x_3(t) = \frac{d^2}{dt^2} x(t-3)$

$$X_3(\omega) = (j\omega)^2 \cdot e^{-j3\omega} \cdot X(\omega)$$

$$\boxed{X_3(\omega) = -\omega^2 \cdot e^{-j3\omega} \cdot X(\omega)}$$

 ④ $x_4(t) = t \frac{dx(t)}{dt}$

Sum:
 $x_4(t) = \underbrace{t}_{j \frac{d}{d\omega}} \cdot \underbrace{\frac{dx(t)}{dt}}_{X(\omega)}$

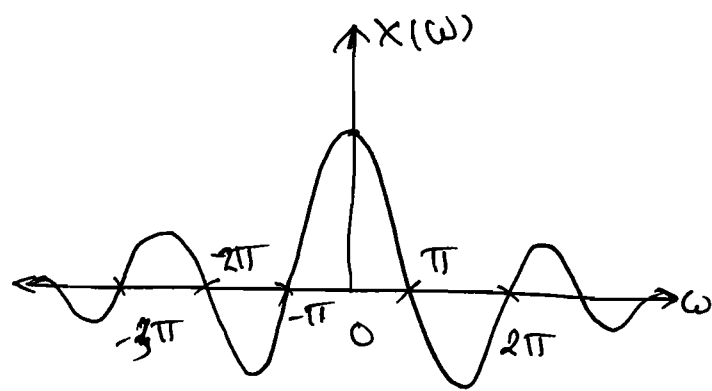
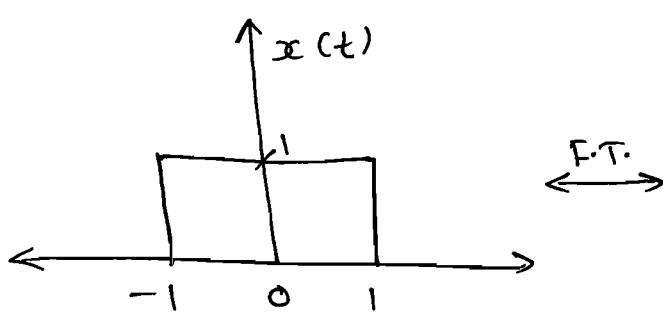
$$X_4(\omega) = j \frac{d}{d\omega} (j\omega \cdot X(\omega))$$

$$\therefore \boxed{X_4(\omega) = - \left(X(\omega) + \omega \frac{dX(\omega)}{d\omega} \right)}$$

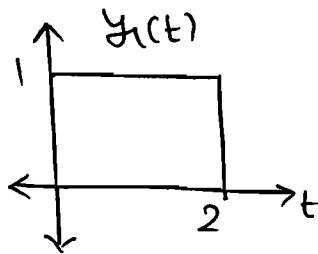
P4.2.21 Given $x(t) = \begin{cases} 1; & |t| < 1 \longleftrightarrow \frac{\sin \omega}{\omega} \\ 0; & \text{elsewhere} \end{cases}$ find

the F.T. of the following signals?

$\Rightarrow$



(a)

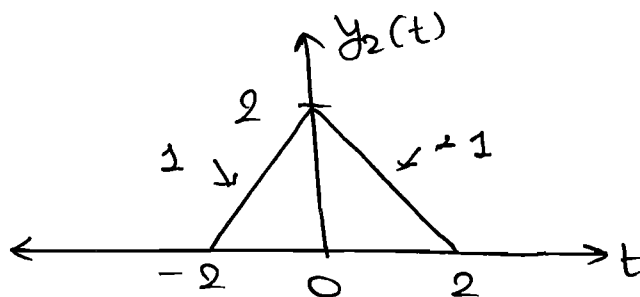


Soln:

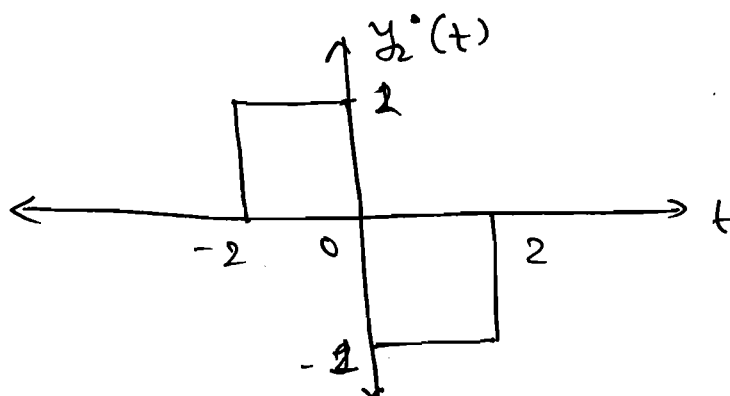
$$y_1(t) = x(t-1).$$

$$\therefore Y_1(\omega) = e^{-j\omega} \cdot X(\omega).$$

(b)



Soln:

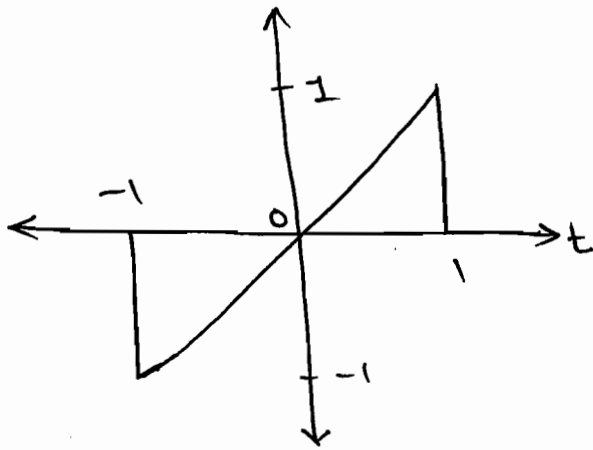


$$\therefore y_2^*(t) = y_1(-t) - y_1(t).$$

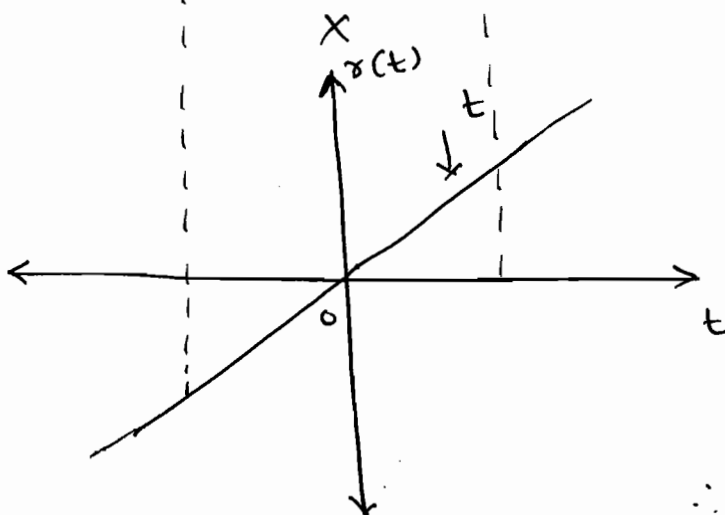
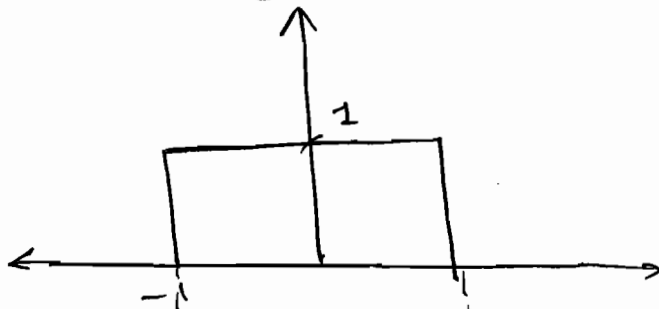
$$j\omega Y_2(\omega) = Y_1(-\omega) - Y_1(\omega).$$

$$\therefore Y_2(\omega) = \frac{1}{j\omega} [Y_1(-\omega) - Y_1(\omega)].$$

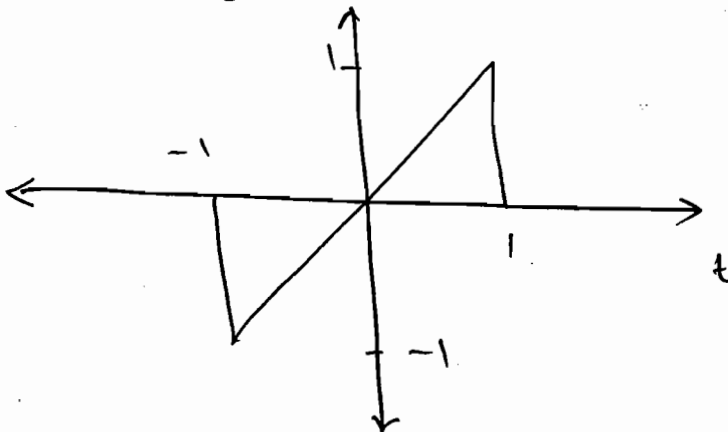
(c)



Soln: method I



$y_3(t)$



$$\text{Sol } y_3(t) = t \cdot x(t).$$

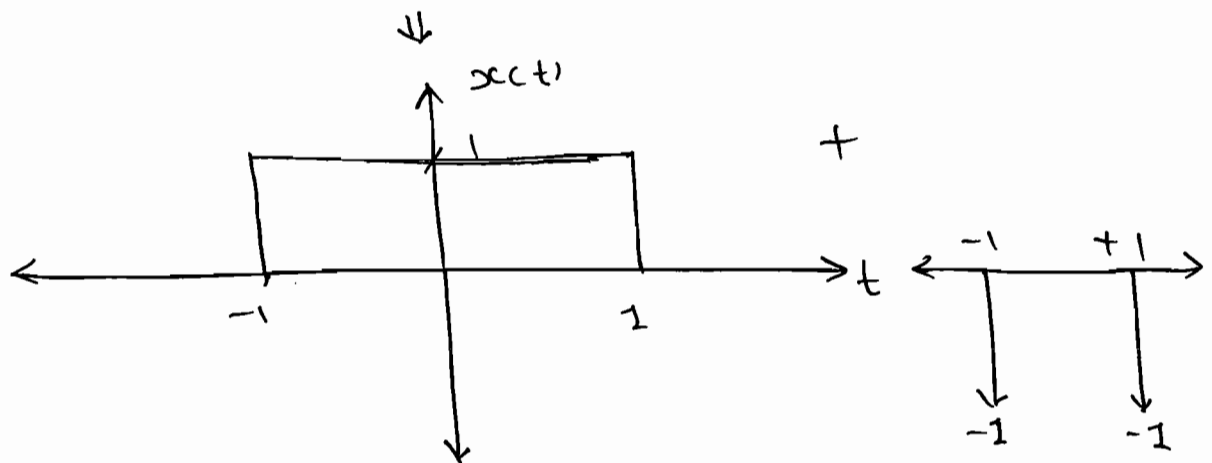
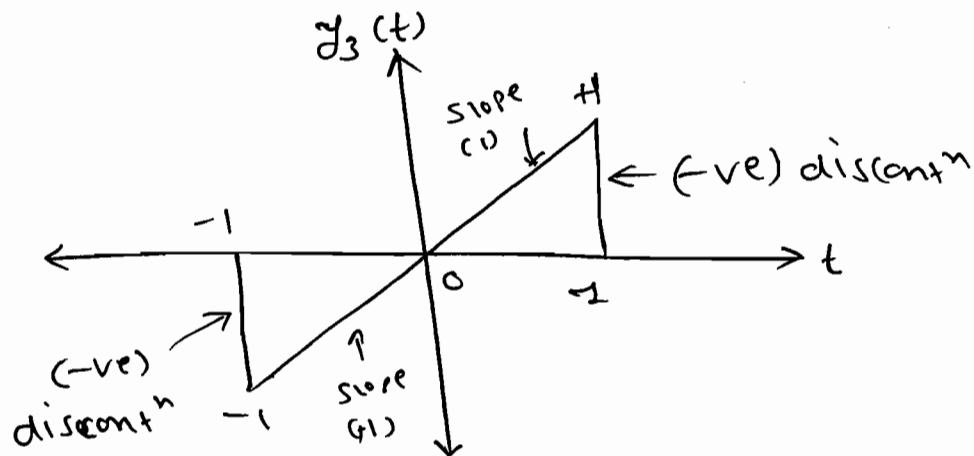
$$\therefore Y_3(\omega) = j \cdot \frac{dX(\omega)}{d\omega}$$

$$\therefore Y_3(\omega) = j \frac{d}{d\omega} \left(2 \frac{\sin \omega}{\omega} \right)$$

$$= 2j \left[\frac{\omega \cos \omega - \sin \omega}{\omega^2} \right]$$

$$\therefore Y_3(\omega) = \frac{2j}{\omega^2} [\omega \cos \omega - \sin \omega]$$

Method - II : By differentiation,



$$\therefore \frac{dy_3(t)}{dt} = x(t) + \delta(t-1) + \delta(t+1).$$

$$\therefore (j\omega) Y_3(\omega) = X(\omega) + \frac{e^{-j\omega} + e^{j\omega}}{1}.$$

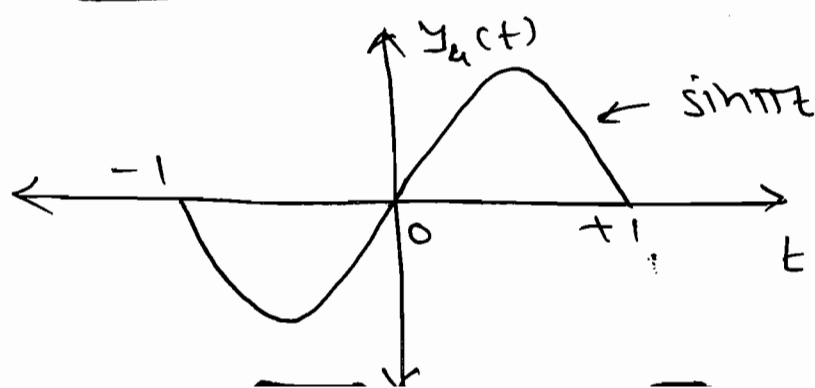
$$\therefore Y_3(\omega) = \frac{X(\omega)}{j\omega} + \frac{2 \cos \omega}{j\omega}.$$

$$= \frac{1}{j\omega} \left[\frac{2 \sin \omega}{\omega} + 2 \cos \omega \right]$$

$$= \frac{j}{j^2 \omega^2} [2 \sin \omega - 2 \omega \cos \omega].$$

$$Y_3(\omega) = \frac{2}{j\omega^2} [2 \omega \cos \omega - 2 \sin \omega]$$

(d)



Soln:

$$Y_u(t) = \sin \pi t \cdot x(t).$$

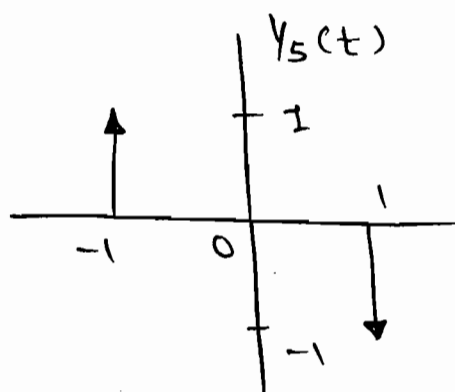
$$\therefore Y_u(\omega) \neq j \frac{d}{d\omega} (X(\omega)).$$

$$\therefore Y_u(t) = \frac{e^{j\pi t} - e^{-j\pi t}}{2j} \times x(t).$$

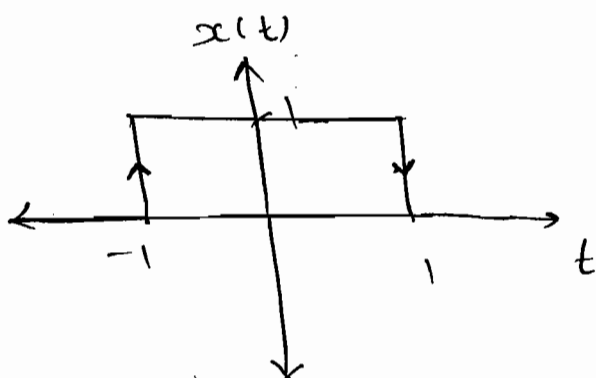
$$Y_u(t) = \frac{1}{2j} \left[e^{+j\pi t} \cdot x(t) - e^{-j\pi t} \cdot x(t) \right].$$

$$\Rightarrow \boxed{Y(\omega) = \frac{1}{2j} [X(\omega - \pi) - X(\omega + \pi)]}$$

(e)



Soln:

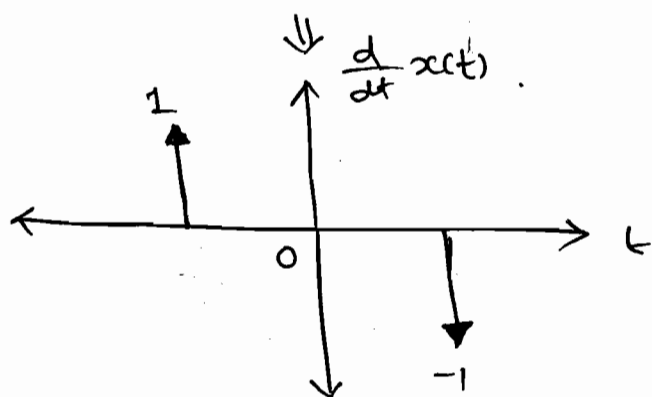


$$y_s(t) = \frac{d}{dt} x(t).$$

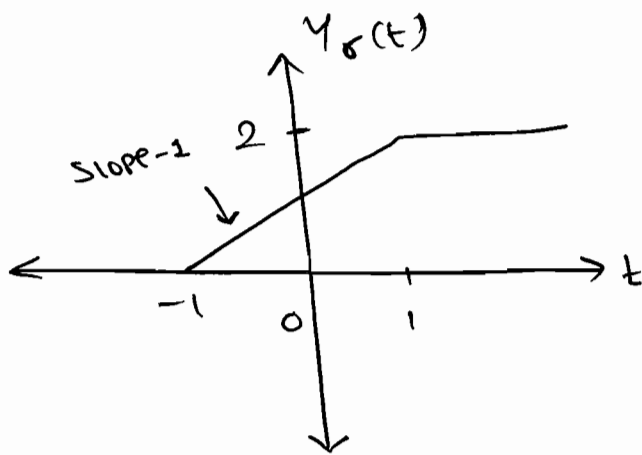
$$\therefore Y_s(\omega) = j\omega [X(\omega)].$$

$$\therefore Y_s(\omega) = j\omega \left[\frac{2 \sin \omega}{\omega} \right]$$

$$\boxed{Y_s(\omega) = 2j \sin \omega}$$



(F)

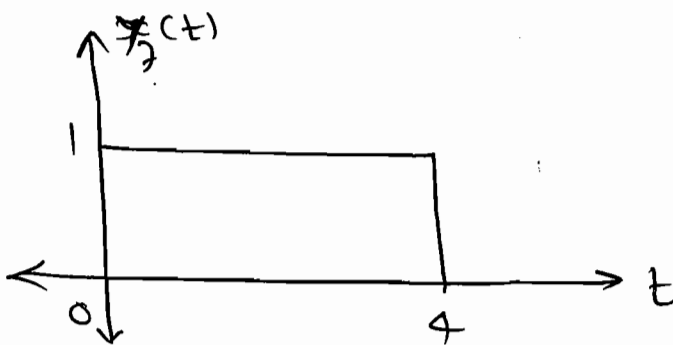


Solⁿ: $Y_6(t) = (t+1)x(t) + 2u(t-1).$

$\therefore Y_6(t) = tx(t) + x(t) + 2u(t-1).$
 $\downarrow$ F.T.

$$\therefore Y_6(\omega) = j \frac{d}{d\omega} (X(\omega)) + X(\omega) + 2 \left[\frac{1}{j\omega} + \pi\delta(\omega) \right] e^{-j\omega}.$$

(g)

Solⁿ:

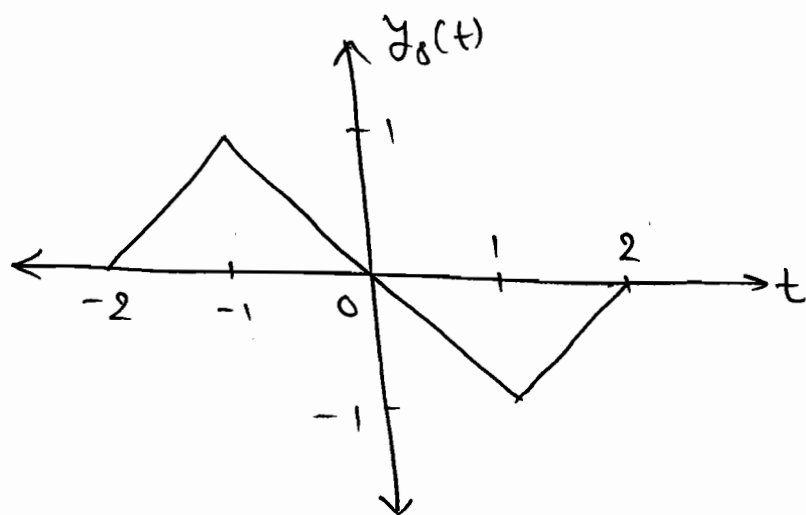
$$Y_7(t) = x\left(\frac{t}{4} - 1\right).$$

$$Y_7(t) = x\left(\frac{t-4}{4}\right).$$

$$\therefore Y_7(\omega) = \frac{1}{\frac{1}{4}} \cdot X\left(\omega/\frac{1}{4}\right) \cdot e^{-j4\omega}.$$

$$\therefore Y_7(\omega) = 4 \cdot e^{-j4\omega} \cdot X(4\omega).$$

(h)



Soln:

$$y_8(t) = y_2(2(t+1)) - y_2(2(t-1))$$

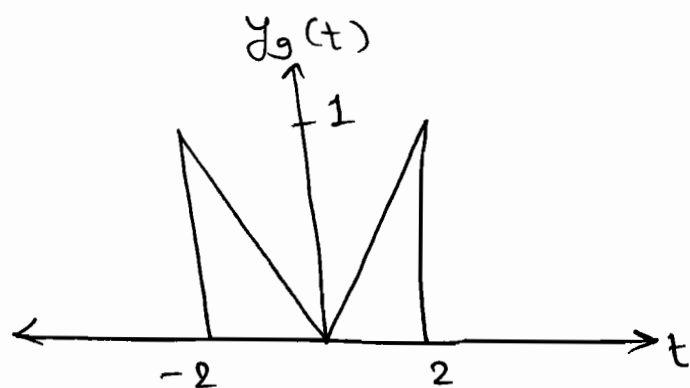
$$y_8(t) = y_2(2(t+1)) - y_2(2(t-1))$$

$$Y_8(\omega) = \left(\frac{1}{2}\right) e^{+j\omega} Y_2(\omega/2) - \left(\frac{1}{2}\right) e^{-j\omega} Y_2(\omega/2)$$

$$= 2e^{j\omega} Y_2(2\omega) - 2e^{-j\omega} Y_2(2\omega)$$

$$= 2 \times 2j \times Y_2(2\omega) \left[\frac{e^{j\omega} - e^{-j\omega}}{2j} \right]$$

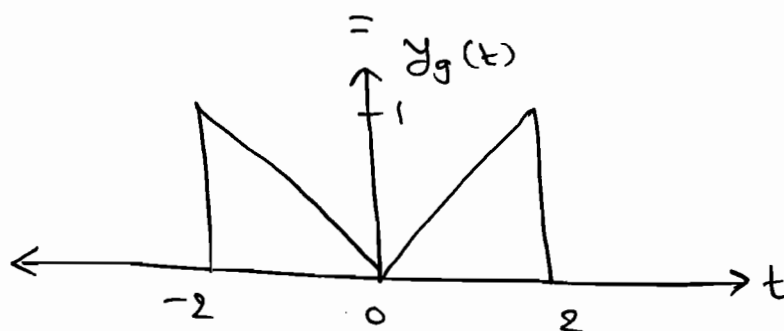
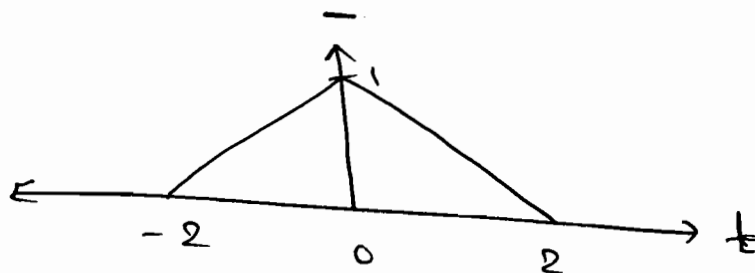
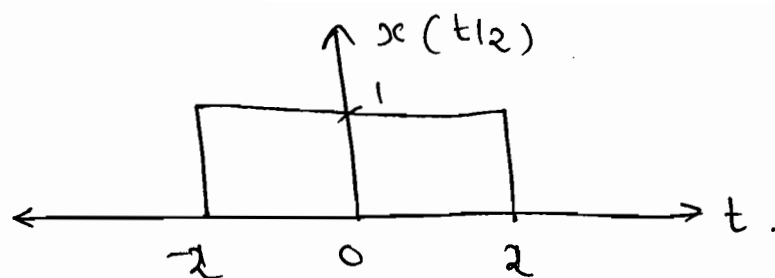
$$\therefore Y_8(\omega) = 4j Y_2(2\omega) \cdot \sin \omega$$

★★
(i)

Soln:

$$y_9(t) = x(t/2) - y_2(t)$$

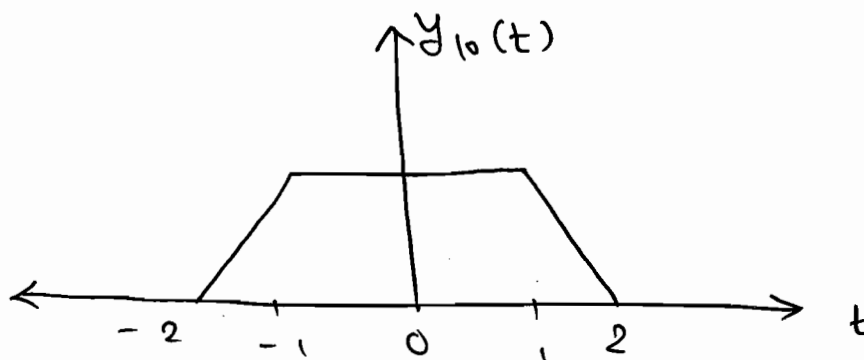
⇒



$$\therefore y_g(t) = x(t/2) - y_2(t).$$

$$\therefore Y_g(\omega) = 2X(2\omega) - Y_2(\omega).$$

(j)

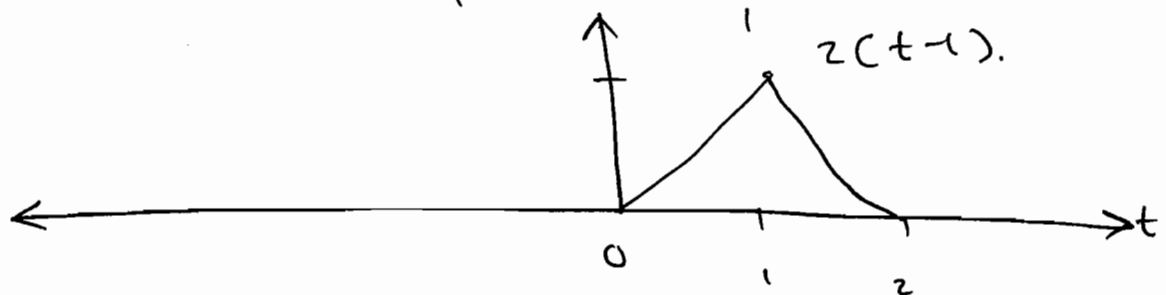
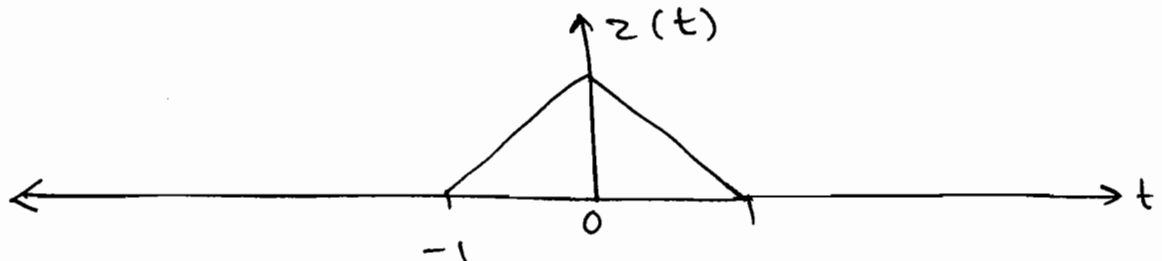
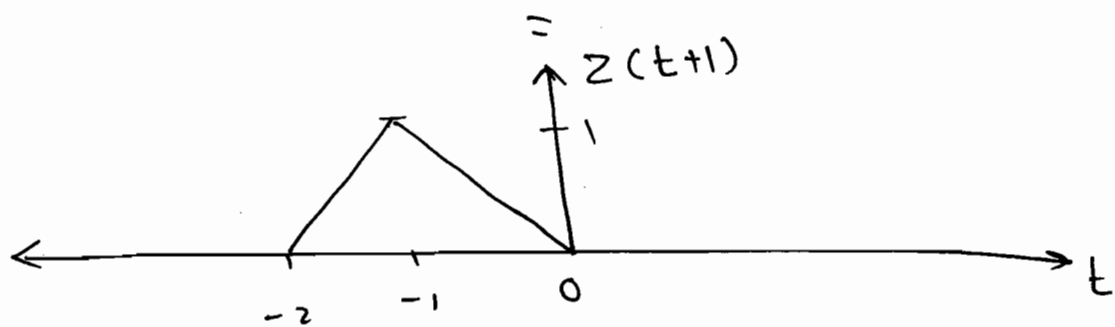
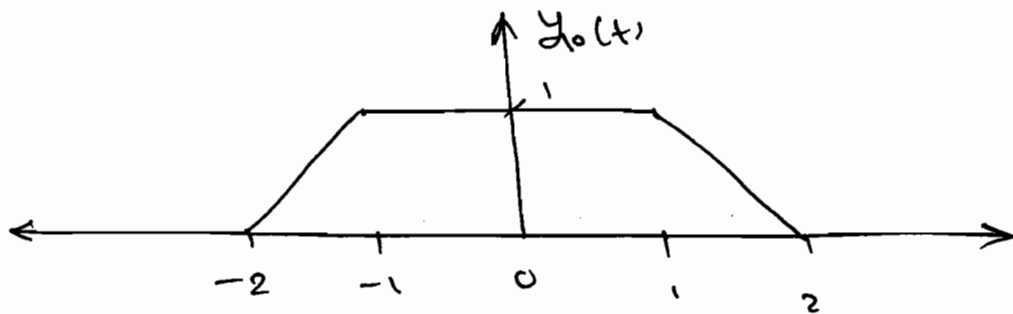


||
50m:

$$\text{let, } z(t) = \frac{1}{2} y_2(2t).$$

$$\therefore y_{10}(t) = z(t+1) + z(t) + z(t-1).$$

$$\therefore y_{10}(t) = \frac{1}{2} [y_2(2t+2)] + \frac{1}{2} [y_2(2t)] + \frac{1}{2} [y_2(2t-2)].$$



$$\therefore Y_{10}(\omega) = \frac{1}{2} \left[\frac{1}{2} e^{j\omega} Y_2(\omega/2) + \frac{1}{2} Y_2(\omega/2) + \frac{1}{2} Y_2(\omega/2) \cdot e^{-j\omega} \right]$$

$$Y_{10}(\omega) = \frac{Y_2(\omega/2)}{4} [1 + 2\cos\omega]$$

⑦ Convolution in time:-

$\Rightarrow$ If $x(t) \longleftrightarrow X(\omega)$ & $h(t) \longleftrightarrow H(\omega)$.

then, $x(t) * h(t) \longleftrightarrow X(\omega) \cdot H(\omega)$.

$\Rightarrow$ Convolution in time corresponds to multiplication in frequency domain.

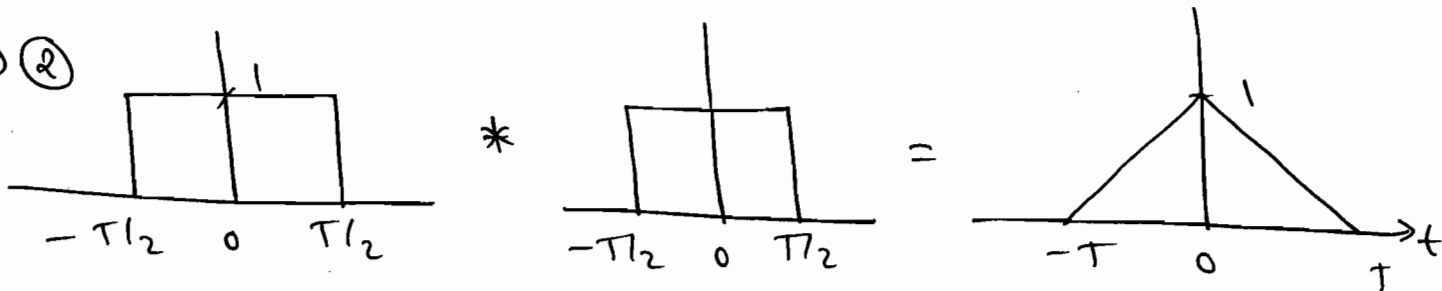
$\Rightarrow$ F.T. of impulse response, $h(t)$ is known as frequency response, $H(\omega)$.

e.g.

$$\textcircled{1} \quad e^{-at} \cdot u(t) * e^{-at} \cdot u(t) \xrightarrow{\text{F.T.}} \frac{1}{(a+j\omega)^2}$$

$$= t \cdot e^{-at} \cdot u(t)$$

$\Rightarrow \textcircled{2}$

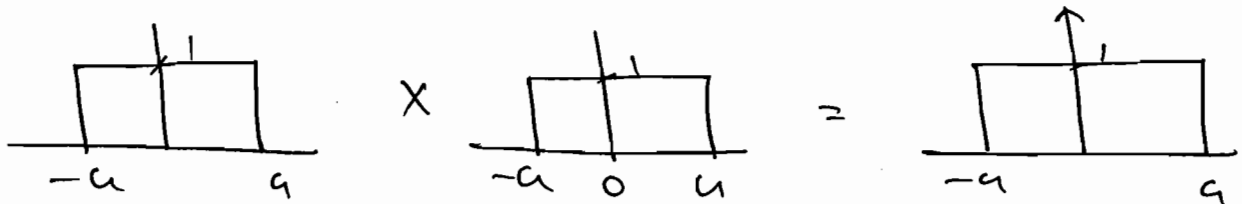


$$\therefore \text{rect}(t/T) * \text{rect}(t/T) \xrightarrow{\text{F.T.}} T^2 \text{sinc}^2\left(\frac{\omega T}{2}\right).$$

$$T \text{sinc}\left(\frac{\omega T}{2}\right) \times T \text{sinc}\left(\frac{\omega T}{2}\right)$$

$\textcircled{3}$

$$\frac{\sin \pi t}{\pi t} * \frac{\sin \pi t}{\pi t} = \frac{\sin \pi t}{\pi t} \quad \nwarrow \text{I.F.T.}$$

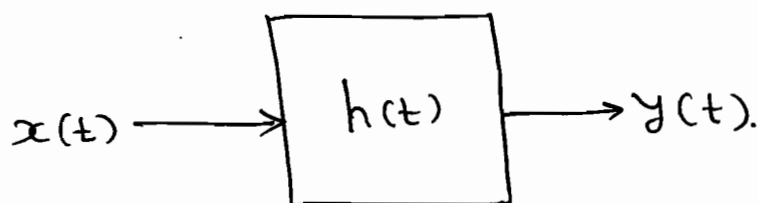


$\Rightarrow$

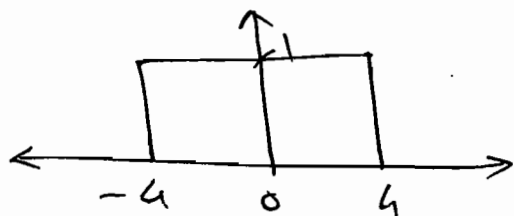
Gaussian * Gaussian = Gaussian.

P4.2.23 An L-T-I. system is having I.R. $h(t) = \frac{\sin 4t}{\pi t}$ for which the input applied is $x(t) = \cos 2t + \sin 2t$, find the o/p.

Solⁿ:



$$\therefore h(\omega) = \text{rect}(t/4)$$



← Ideal LPF.

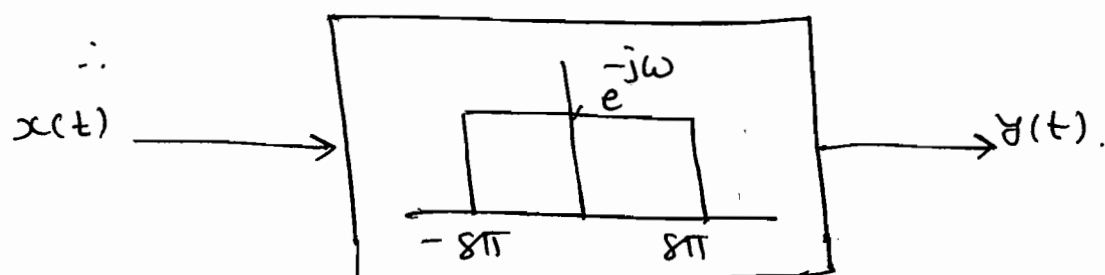
$$\text{So, o/p} = \cos 2t$$

*
**

P4.2.26 (a) Find the o/p of a system having impulse response $h(t) = 8 \text{sinc}[8(t-1)]$ When the input applied is $x(t) = \cos \pi t$.

Solⁿ: $h(t) = 8 \text{sinc}[8(t-1)]$

$$h(t) = \frac{8 \sin[8\pi(t-1)]}{8\pi(t-1)} \Rightarrow h(\omega) = e^{-j\omega} \cdot \text{rect}\left(\frac{t}{16\pi}\right)$$

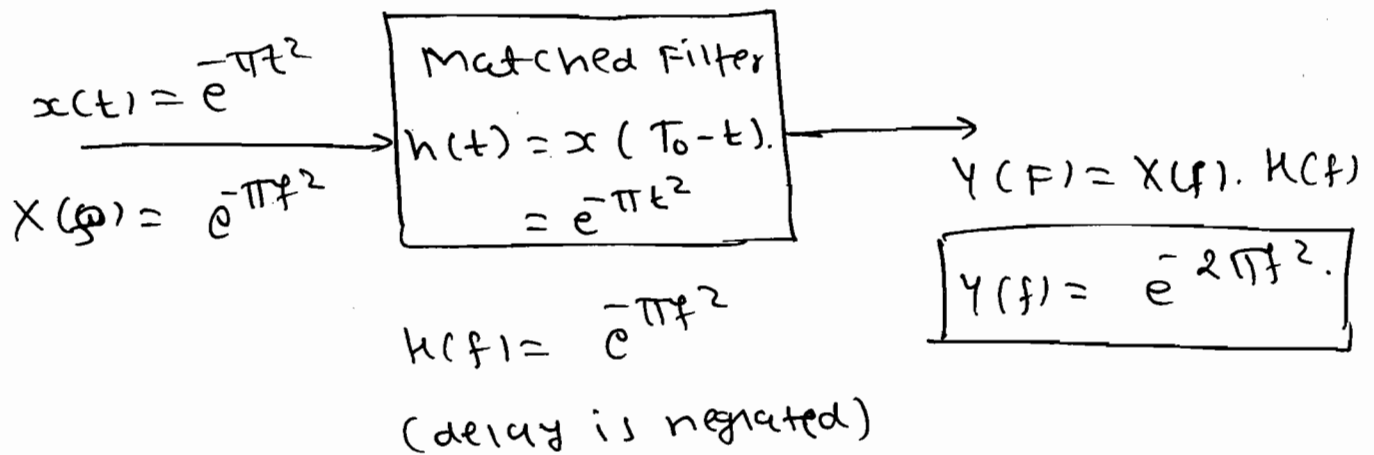


$$\Rightarrow y(t) = \cos \pi(t-1) \leftarrow \text{delay because of } e^{-j\omega}$$

b) Let $g(t) = e^{-\pi t^2}$, and $h(t)$ is a filter matched to $g(t)$. If $g(t)$ is applied as input to $h(t)$, then the Fourier transform of the output is,

(a) $e^{-\pi f^2}$ (b) $e^{-\pi f^2/2}$ (c) $e^{-\pi |f|}$ (d) $e^{-2\pi f^2}$

Soln:



P 4.2.25 Using Convolution Property of F.T.

find the Convolution of following signals.

(a) $y(t) = \text{rect}(t) * \cos(\pi t)$

Soln: $Y(\omega) = X(\omega) \cdot h(\omega)$

$$\therefore Y(\omega) = \text{sinc}\left(\frac{\omega T}{2}\right) \cdot \left[\pi [\delta(\omega - \pi) + \delta(\omega + \pi)] \right]$$

$$= \frac{\sin(\omega/2)}{(\omega/2)} \left[\pi [\delta(\omega - \pi) + \delta(\omega + \pi)] \right]$$

$$= \frac{\sin(\pi/2)}{(\pi/2)} \cdot \pi \cdot \delta(\omega - \pi) + \frac{\sin(-\pi/2)}{(-\pi/2)} \cdot \pi \cdot \delta(\omega + \pi)$$

$$= \frac{1}{1} \cdot \pi \cdot \delta(\omega - \pi) + \frac{1}{1} \cdot \pi \cdot \delta(\omega + \pi)$$

$$\therefore Y(\omega) = \cancel{\pi} \times \frac{\cancel{\sin \frac{\pi}{2}}^2}{\cancel{\pi/2}} \delta(\omega - \pi) + \cancel{\pi} \times \frac{\cancel{\sin(-\frac{\pi}{2})}^{-1}}{(-\cancel{\pi/2})} \delta(\omega + \pi).$$

$$\therefore Y(\omega) = 2 [\delta(\omega - \pi) + \delta(\omega + \pi)].$$

$$\text{IFT} \downarrow = \frac{2}{\pi} \{ \pi [\delta(\omega - \pi) + \delta(\omega + \pi)] \}$$

$$\therefore Y(t) = \frac{2}{\pi} \cos \pi t.$$

$$(b) Y_3(t) = \cancel{\text{sinc}(t)} \ast \cancel{\text{rect}(t)} \ast \cos(2\pi t).$$

$$\Rightarrow Y_3(t) = \text{rect}(t) \ast \cos(2\pi t).$$

$$= \frac{\sin(\frac{\omega}{2})}{(\omega/2)} \times \left\{ \pi [\delta(\omega - 2\pi) + \delta(\omega + 2\pi)] \right\}$$

$$= \frac{\pi \cdot \cancel{\sin(\frac{2\pi}{2})}^0}{(\frac{2\pi}{2})} \delta(\omega - 2\pi) + \frac{\pi \cdot \cancel{\sin(-\frac{2\pi}{2})}^0}{(-\frac{2\pi}{2})} \delta(\omega + 2\pi)$$

$$= 0 + 0$$

$$Y_3(t) = 0$$

$$(c) Y_3(t) = \text{sinc}(t/2) \ast \sin(t/2).$$

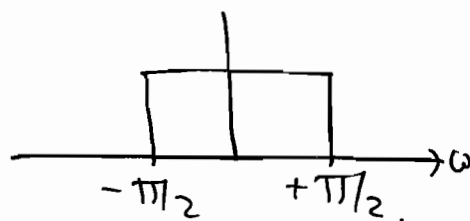
Solⁿ:

$$y_3(t) = \text{sinc}(t) * \text{sinc}(t/2).$$

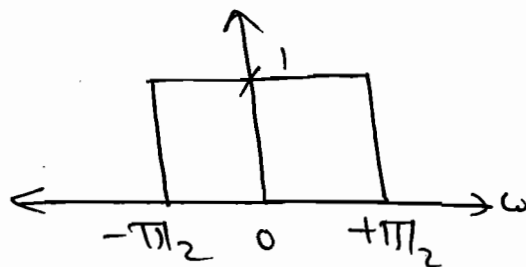
$$Y_3(\omega) = X_1(\omega) \cdot X_2(\omega) = \text{rect}(\omega/2) \times \text{rect}(\omega/2).$$



x



=



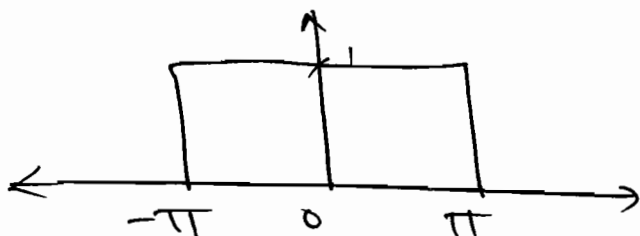
$$Y_3(\omega) = \left[\frac{\sin(\pi t)}{(\pi t)} \right] * \left[\frac{\sin(\frac{\pi t}{2})}{(\frac{\pi t}{2})} \right].$$

$$\boxed{y_3(t) = \text{sinc}(t/2)}.$$

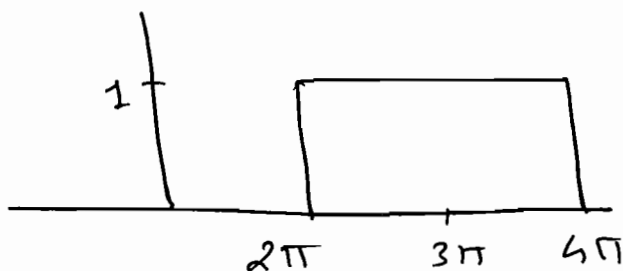
$$(d) y_4(t) = \text{sinc}(t) * e^{j3\pi t} \cdot \text{sinc}(t).$$

Solⁿ:

$$y_4(t) = \left[\frac{\sin \pi t}{\pi t} \right] * \left[e^{j3\pi t} \cdot \frac{\sin \pi t}{\pi t} \right].$$



x



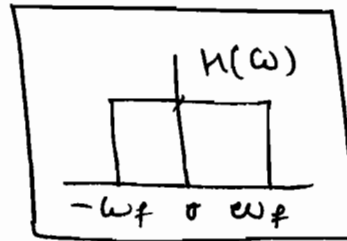
= 0.

So,

$$\boxed{y_4(t) = 0}$$

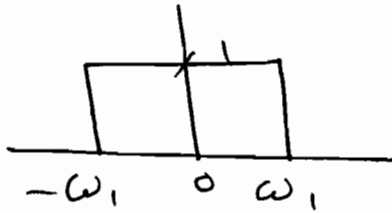


$$I/P: \frac{\sin \omega_1 t}{\pi t} + \frac{\sin \omega_2 t}{\pi t}$$

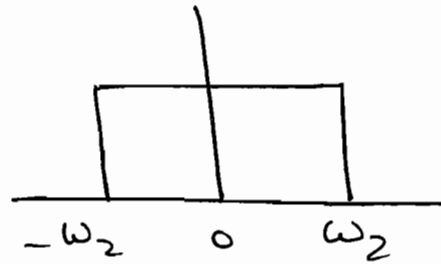


→ O/P = ?

⇒ ① $\omega_f < \omega_1$



+



let, $\omega_f = 0.5$

$$O/P = \frac{\sin \omega_f t}{\pi t} + \frac{\sin \omega_f t}{\pi t}$$

$$O/P = \frac{2 \sin \omega_f t}{\pi t}$$

② $\omega_1 < \omega_f < \omega_2$

let, $\omega_f = 1.5$

$1 < 1.5 < 2$

$$O/P = \frac{\sin \omega_1 t}{\pi t} + \frac{\sin \omega_f t}{\pi t}$$

③ $\omega_f > \omega_2$; $\omega_f = 2.5$

∴ $O/P = I/P$

P 4.2.22 Given $y(t) = x(t) * h(t)$ and

$g(t) = x(3t) * h(3t)$ such that $g(t) = Ay(Bt)$,
find A & B ?

Solⁿ: $y(t) = x(t) * h(t).$

$$\Rightarrow Y(\omega) = X(\omega) \cdot H(\omega).$$

$$\rightarrow g(t) = x(3t) * h(3t).$$

$$G(\omega) = \frac{1}{3} X\left(\frac{\omega}{3}\right) \cdot \frac{1}{3} H\left(\frac{\omega}{3}\right).$$

$$G(\omega) = \frac{1}{9} H\left(\frac{\omega}{3}\right) \cdot X\left(\frac{\omega}{3}\right). \quad \text{--- (1)}$$

$$\rightarrow g(t) = Ay(Bt).$$

$$G(\omega) = \frac{A}{B} Y\left(\frac{\omega}{B}\right). \quad \text{--- (2)}$$

Compare eqⁿ (1) & (2).

$$\frac{A}{B} = \frac{1}{9}, \quad \& \quad B \neq \frac{1}{B}. \quad B \neq \frac{1}{3}$$

$$\boxed{B=3}$$

$$\Rightarrow A = 3/9$$

$$\boxed{A = 1/3}$$

P 4.2.24 Let $x(t)$ be a signal whose F.T. is $X(\omega) = \delta(\omega) + \delta(\omega - \pi) + \delta(\omega - 5)$ & Let

$$h(t) = u(t) - u(t-2).$$

(a) is $x(t)$ periodic?

(b) is $x(t) * h(t)$ is periodic?

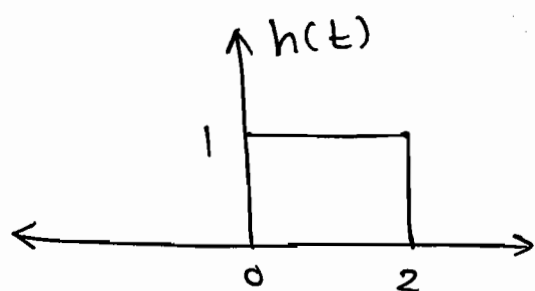
Soln: (a) $X(\omega) = \delta(\omega) + \delta(\omega - \pi) + \delta(\omega - 5)$.

$$x(t) = \frac{1}{2\pi} + \frac{e^{-j\pi t}}{2\pi} \cdot 1 + \frac{1}{2\pi} e^{-j5t} \cdot 1.$$

So, G.C.D. ($\pi, 5$) $\neq$

So, Not periodic signal.

(b) $h(t) = u(t) - u(t-2)$



$$\xleftrightarrow{\text{F.T.}} e^{-j\omega} \cdot 2 \text{sinc}\left(\frac{\omega \cdot 2}{2}\right)$$

$$= e^{-j\omega} \frac{2 \sin \omega}{\omega}$$

$$= \frac{2 \sin \omega}{\omega} \cdot e^{-j\omega}$$

$$\therefore Y(\omega) = X(\omega) \cdot H(\omega)$$

$$\therefore Y(\omega) = [\delta(\omega) + \delta(\omega - \pi) + \delta(\omega - 5)] \times \left[\frac{2 \sin \omega}{\omega} \cdot e^{-j\omega} \right]$$

$$= \frac{e^{-j\omega}}{\omega} \cdot 2 \sin \omega \cdot \delta(\omega) + \frac{e^{-j\omega}}{\omega} \cdot 2 \sin \omega \delta(\omega - \pi)$$

$$+ \frac{e^{-j\omega}}{\omega} \cdot 2 \sin \omega \cdot \delta(\omega - 5)$$

$$Y(\omega) = 2\delta(\omega) + 0 + \frac{1}{\omega} \cdot 2 \sin 5 \cdot \delta(\omega - 5)$$

$$\therefore \boxed{Y(\omega) = 2\delta(\omega) + \frac{1}{\omega} \cdot 2 \sin 5 \delta(\omega - 5)}$$

So, ϕ_p is periodic. ($\because \text{Geo}(0, 5) = 5$).

(8) Frequency Convolution:

$\Rightarrow$ If $x_1(t) \longleftrightarrow X_1(\omega)$ and $x_2(t) \longleftrightarrow X_2(\omega)$ then

$$x_1(t) \cdot x_2(t) \xleftrightarrow{\text{F.T.}} \frac{1}{2\pi} [X_1(\omega) * X_2(\omega)]$$

* Application:

① Modulator

② Samples in freq. domain.

$$\begin{aligned} \text{e.g.: } x(t) \cdot \cos \omega_c t &\xleftrightarrow{\text{F.T.}} \frac{1}{2\pi} [X(\omega) * [\delta(\omega - \omega_c) + \delta(\omega + \omega_c)]] \\ &= \frac{X(\omega - \omega_c) + X(\omega + \omega_c)}{2} \end{aligned}$$

P 4.2.27 Find the F.T. of

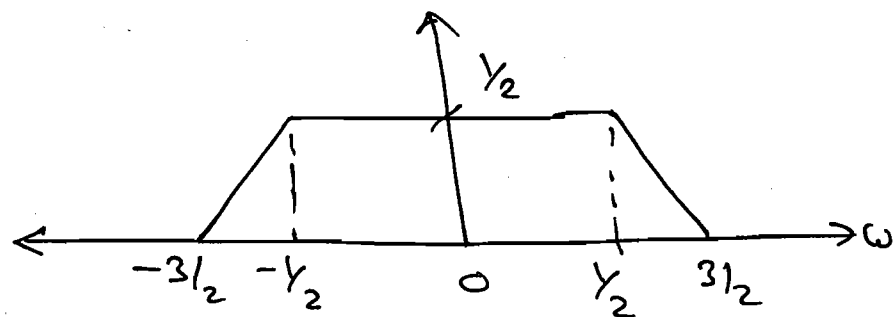
$$(b) \quad x(t) = \frac{\sin t \cdot \sin(t/2)}{\pi t^2}$$

$$\text{Sol}^n: \quad x(t) = \frac{\sin t}{\pi t} \times \frac{\sin(t/2)}{\frac{\pi t}{2}} \times \pi$$

$$\therefore X(\omega) = \frac{1}{2\pi} \times \pi \left[\text{rect}(t/2) * \text{rect}(\omega) \right]$$

$$X(\omega) = \frac{1}{2} \left[\text{rect}\left(\frac{\omega}{2}\right) * \text{rect}(\omega) \right]$$

$$\therefore X(\omega) =$$



(g) Integration in Time:

$$\Rightarrow \text{If } x(t) \longleftrightarrow X(\omega)$$

$$\text{Then } \int_{-\infty}^t x(\tau) d\tau \longleftrightarrow \frac{X(\omega)}{j\omega} + \pi X(0) \delta(\omega).$$

P. 4. 2. 28

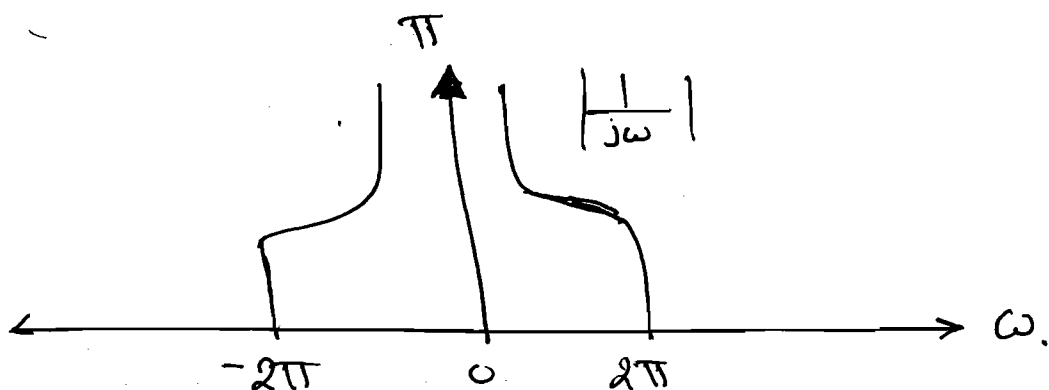
$$\text{Find the F.T. of } \int_{-\infty}^t \frac{\sin 2\pi\tau}{\pi\tau} d\tau.$$

Soln:

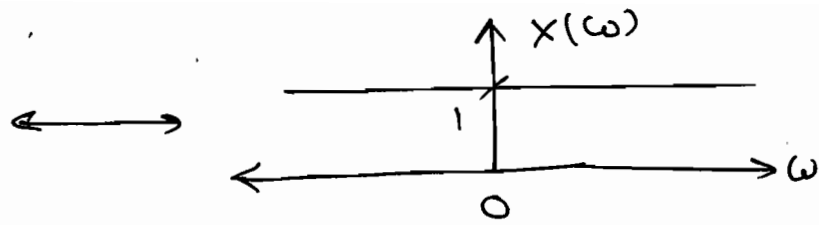
$$x(t) = \int_{-\infty}^t \frac{\sin 2\pi\tau}{\pi\tau} d\tau$$

$$X(\omega) = \frac{X_1(\omega)}{j\omega} + \pi X(0) \delta(\omega).$$

$$X(\omega) = \frac{\text{rect}(\omega/4\pi)}{j\omega} + \pi(1) \cdot \delta(\omega).$$



$$\Rightarrow x(t) = \delta(t)$$

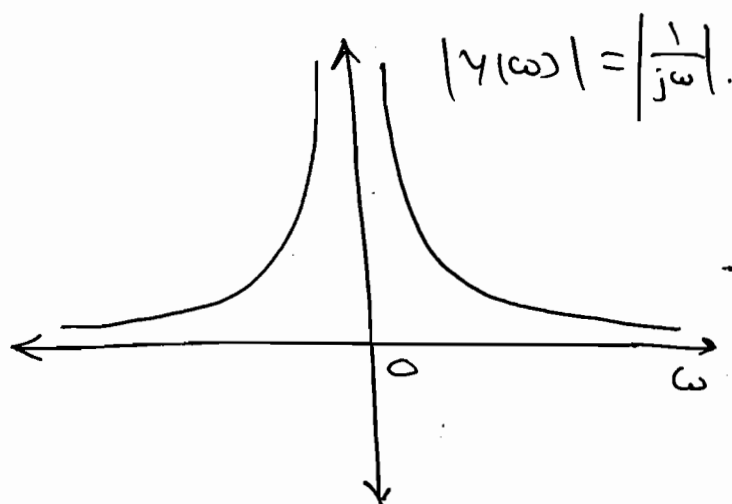


$$\int_{-\infty}^t \delta(\tau) d\tau \longleftrightarrow \frac{1}{j\omega} + \pi(1) \delta(\omega).$$

$\xleftarrow{\quad} = u(t) \quad \xrightarrow{\quad} Y(\omega)$

i.e. $u(t) \xleftrightarrow{FT} \frac{1}{j\omega} + \pi \delta(\omega).$

$$|Y(\omega)| = \left| \frac{1}{j\omega} \right|.$$



$\Rightarrow$ Differentiation gives only $\frac{1}{j\omega}$ terms, $\pi \delta(\omega)$ [oc term] is missing there.

★ Rayleigh's Energy theorem (or)
Parseval's Power theorem:-

$\Rightarrow$ Area under Spectral density represents energy (or) power in the signal.

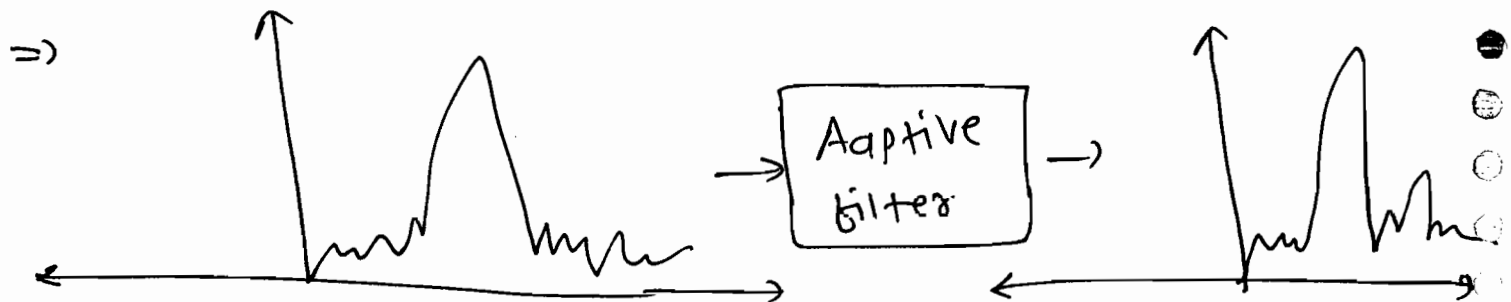
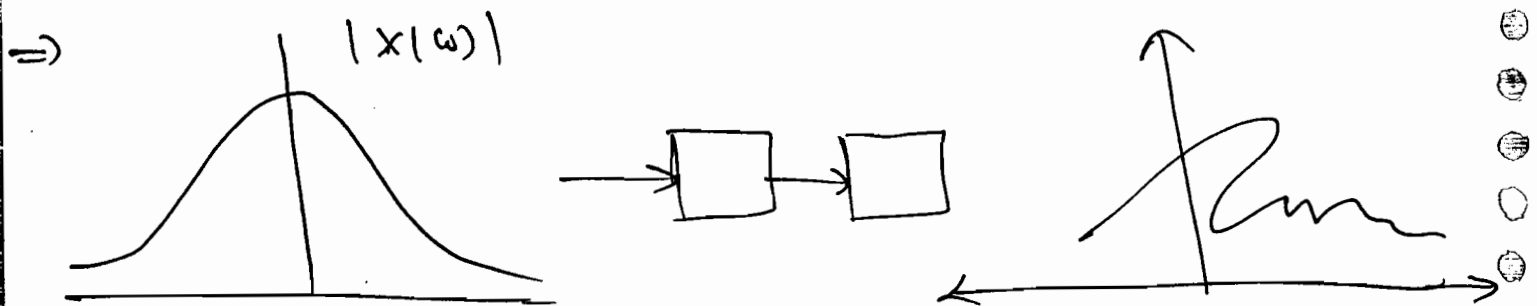
$\Rightarrow$ When a signal is added with noise by comparing the noise spectral density with signal spectral density we can suppress the noise component by

designing an 'adaptive Filter'. [Adjustable coefficient].

$\Rightarrow$ IR $\rightarrow$ LTI filter.

Adaptive filter $\rightarrow$ LTI filter.

$$\Rightarrow \int_{-\infty}^{+\infty} |x(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{+\infty} |X(\omega)|^2 d\omega.$$



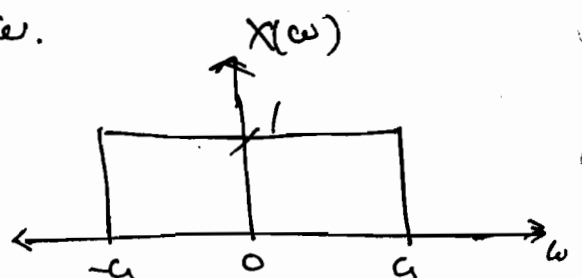
P 4. 2.29 Find the energy in the signal

$$x(t) = \frac{\sin \pi t}{\pi t}.$$

Soln:

$$E_{x(t)} = \frac{1}{2\pi} \int_{-\infty}^{\infty} |X(\omega)|^2 d\omega.$$

$$x(t) = \frac{\sin \pi t}{\pi t} \xleftrightarrow{\text{F.T.}}$$

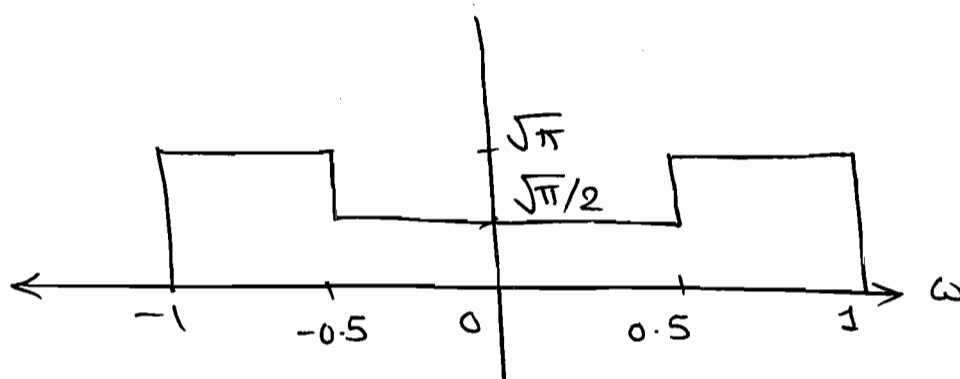


$$\therefore E_{x(t)} = \frac{1}{2\pi} \int_{-a}^a c|\beta|^2 d\omega.$$

$$= \frac{2a}{2\pi}$$

$$\therefore \boxed{E_{x(t)} = \frac{a}{\pi}}$$

P 4.2. 30 Find the energy in the spectrum shown in fig.



soln:

$$E_{x(t)} = \frac{1}{2\pi} \int_{-\infty}^{\infty} |x(\omega)|^2 d\omega.$$

$$= \frac{1}{2\pi} \times 2 \times \int_0^1 |x(\omega)|^2 d\omega$$

$$= \frac{1}{\pi} \times \left[\int_0^{0.5} \left(\frac{\sqrt{\pi}}{2}\right)^2 d\omega + \int_{0.5}^1 (\sqrt{\pi})^2 d\omega \right].$$

$$= \frac{1}{\pi} \left[\frac{\pi}{4} \times \frac{1}{2} + \frac{\pi}{2} \right].$$

$$= \frac{1}{8} + \frac{1}{2}$$

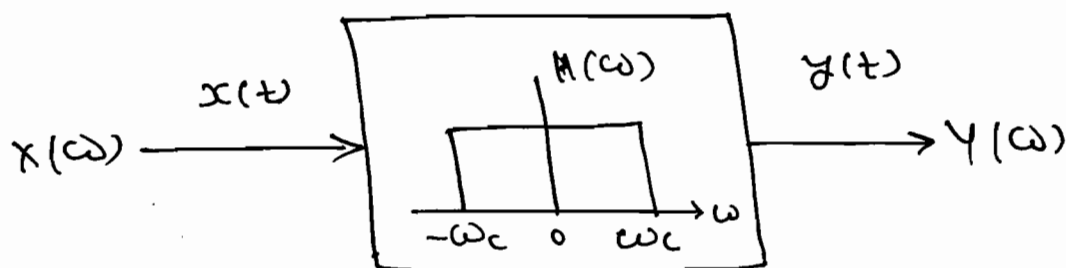
$$\boxed{E_{x(t)} = 5/8}$$

P4.3.21

An input signal $x(t) = e^{-2t} u(t)$ is applied to an ideal L.P.F. with freq. response char. $H(\omega) = 1$; $|\omega| < \omega_c$
 $= 0$; $|\omega| > \omega_c$.

Find ω_c , such that energy in the

Soln:



→ slp: $x(t) = e^{-2t} u(t)$.

$$X(\omega) = \frac{1}{2 + j\omega}$$

$$|X(\omega)|^2 = \frac{1}{4 + \omega^2}$$

$$\begin{aligned} \rightarrow E_{x(t)} &= \int_{-\infty}^{\infty} |x(t)|^2 dt \\ &= \int_0^{\infty} e^{-4t} dt. \end{aligned}$$

$$\boxed{E_{x(t)} = \frac{1}{4}}$$

Now, given that

$$E_{y(t)} = \frac{1}{2} \times E_{x(t)}.$$

$$\therefore E_{y(t)} = \frac{1}{8}.$$

Now, $Y(\omega) = X(\omega) \cdot H(\omega).$

$$Y(\omega) = \frac{1}{\sqrt{\omega^2 + 4}} \quad (1).$$

$$\therefore E_y(t) = \frac{1}{2\pi} \int_{-\omega_c}^{\omega_c} \frac{1}{\omega^2 + 4} \cdot d\omega.$$

$$= \frac{2}{2\pi} \times \int_0^{\omega_c} \frac{1}{\omega^2 + 4} \cdot d\omega.$$

$$\therefore \frac{1}{8} = \frac{1}{\pi} \times \frac{1}{2} \times \left[\tan^{-1}(\omega/2) \right]_0^{\omega_c}$$

$$\therefore \frac{\pi}{4} = \tan^{-1}(\omega_c/2).$$

$$\therefore \omega_c = 2 \tan \frac{\pi}{4}.$$

$$\therefore \boxed{\omega_c = 2 \text{ rad/sec.}}$$

P4.2.32 Consider $x(t) \longleftrightarrow X(\omega)$. Suppose

we are given the following facts

(i) $x(t)$ is real and non negative.

(ii) $F^{-1}\{(1+j\omega)X(\omega)\} = A \cdot e^{-2t} u(t)$, where 'A' is independent of t .

(iii) $\int_{-\infty}^{+\infty} |X(\omega)|^2 \cdot d\omega = 2\pi$ find a closed-form expression for $x(t)$.

Soln:

$$F^{-1} \{ (1+j\omega) X(\omega) \} = A e^{-2t} \cdot u(t).$$

$$\therefore (1+j\omega) X(\omega) = F \{ e^{-2t} \cdot u(t) \}.$$

$$\therefore (1+j\omega) X(\omega) = \frac{1}{2+j\omega}.$$

$$\therefore X(\omega) = \frac{1}{(1+j\omega)(2+j\omega)}.$$

$$\therefore X(\omega) = A \left[\frac{1}{1+j\omega} - \frac{1}{2+j\omega} \right]$$

$$\therefore x(t) = A [e^{-t} - e^{-2t}] u(t).$$

$$\text{Now, } \int_{-\infty}^{+\infty} |X(\omega)|^2 d\omega = 2\pi$$

$$\Rightarrow \boxed{E_{x(t)} = 1} = \frac{1}{2\pi} \int_{-\infty}^{+\infty} |X(\omega)|^2 d\omega.$$

$$\therefore 1 = \int_{-\infty}^{\infty} |x(t)|^2 dt.$$

$$\therefore 1 = A^2 \left[\int_0^{\infty} [e^{-2t} - 2e^{-3t} + e^{-4t}] dt \right].$$

$$\therefore 1 = A^2 \left[\left[\frac{e^{-2t}}{-2} - \frac{2}{-3} e^{-3t} + \frac{e^{-4t}}{-4} \right]_0^{\infty} \right].$$

$$\therefore 1 = A^2 \left[\frac{1}{2} + \frac{2}{3} + \frac{1}{4} \right].$$

$$\therefore \frac{6}{8} = A^2 \quad 1 = A^2 \left[\frac{6-8+3}{12} \right].$$

$$\Rightarrow \boxed{A = \sqrt{12}}$$

$$\therefore \boxed{x(t) = \sqrt{12} \left[e^{-t} - e^{-2t} \right] u(t)}$$

P 4.2.33 Find the value of the integral

$$\int_{-\infty}^{+\infty} \frac{8}{(\omega^2 + 4)^2} d\omega.$$

Soln:

~~XXXXXX~~
$$\int_{-\infty}^{+\infty} \frac{8}{(\omega^2 + 4)^2} d\omega$$

$$\rightarrow \frac{-d(t)}{e} \longleftrightarrow \frac{2d}{\omega^2 + d^2}.$$

~~XXXXXX~~
$$\Rightarrow \frac{1}{2} \int_{-\infty}^{+\infty} \left(\frac{2(z)}{\omega^2 + d^2} \right)^2 d\omega.$$

$$= \frac{1}{2} \times 2\pi \times \int_{-\infty}^{\infty} e^{-4|t|} dt.$$

$$= \pi \times 2 \times \int_0^{\infty} e^{-4t} dt.$$

$$= 2\pi \times \frac{1}{4}.$$

$$= \frac{\pi}{2}.$$

$$\therefore \text{Sol, } \int_{-\infty}^{+\infty} \frac{8}{(\omega^2 + 4)^2} d\omega = \pi/2.$$

Q Using Parseval's theorem find the signal energy in $x(t) = 4 \operatorname{sinc}(t/5)$.

Soln:

$$x(t) = 4 \operatorname{sinc}(t/5).$$

$$A = 4, \quad T = 5.$$

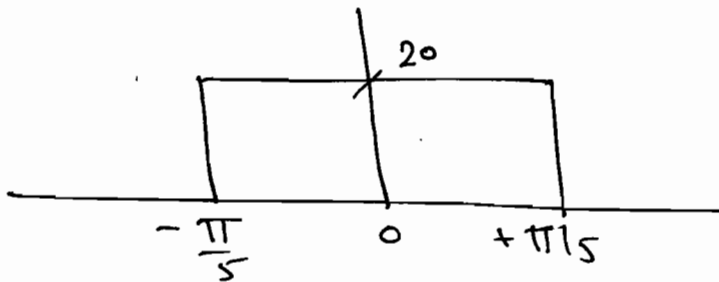
$$\therefore X(\omega) = AT \operatorname{rect}(\omega/2a).$$

$$x(t) = \frac{4 \sin(\pi t/5)}{\pi t/5}$$

$$x(t) = 20 \frac{\sin(\frac{\pi t}{5})}{\pi t}$$

↓ F.T.

$$X(\omega) = 20 \cdot \operatorname{rect}(\omega/2(\frac{\pi}{5})).$$



$$\therefore E_{x(t)} = \frac{1}{2\pi} \int_{-\infty}^{+\infty} |X(\omega)|^2 d\omega.$$

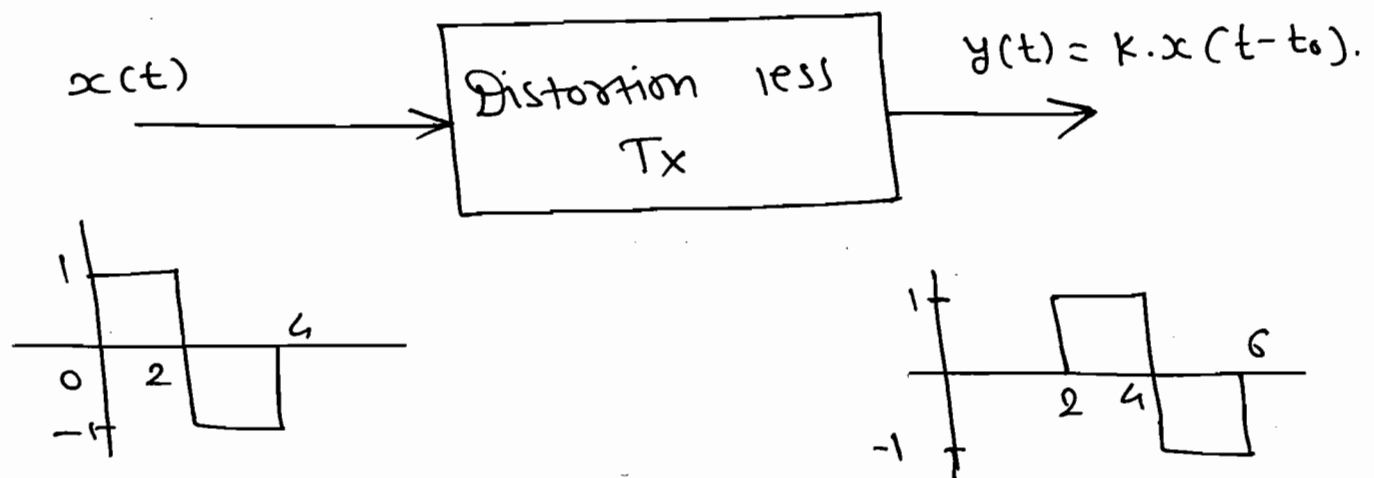
$$= \frac{1}{2\pi} \times 2 \times \int_0^{\pi/5} (400) d\omega.$$

$$= \frac{1}{\pi} \times 400 \times \frac{\pi}{5}$$

$$\therefore \boxed{E_{x(t)} = 80}$$

* Applications:

① Distortionless Transmission:-



⇒ For distortionless transmission, output is replica of the input which scaling in its amplitude and possible delay.

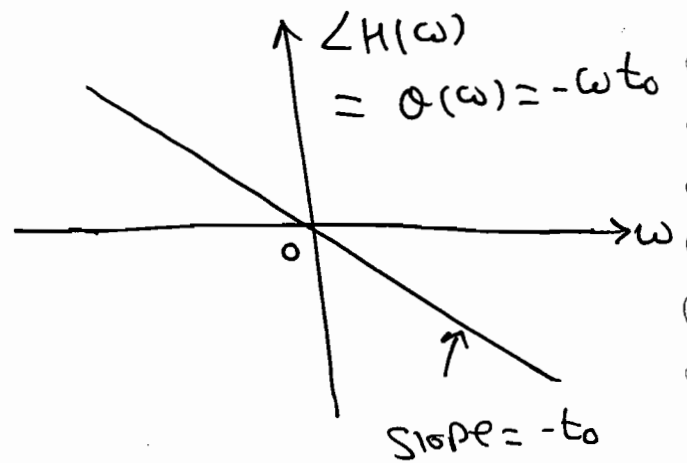
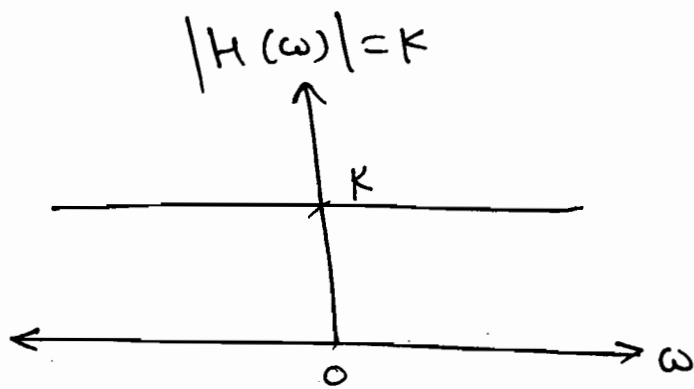
⇒ For Distortion less transmission, magnitude response must be a constant, phase response must be linear function of ω with slope $-t_0$, where t_0 is delay in output with respect to input.

$$y(t) = K x(t - t_0).$$

$$\therefore Y(\omega) = K \cdot e^{-j\omega t_0} \cdot X(\omega).$$

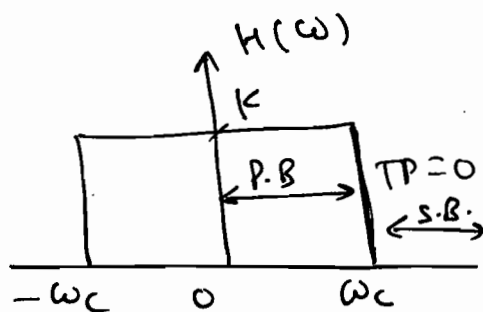
$$\therefore Y(\omega) = |H(\omega)| \cdot e^{j\theta(\omega)}$$

$$\Rightarrow |H(\omega)| = K, \quad \boxed{\theta(\omega) = -\omega t_0}$$

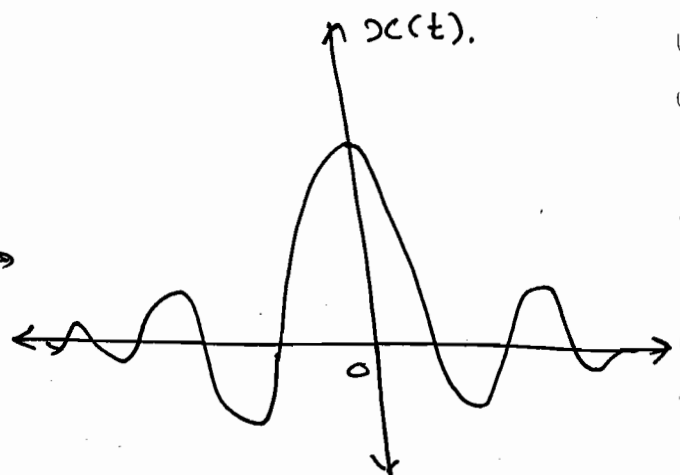


⇒ According to Rayleigh's theorem for a distortionless condition we require infinite energy which is impractical so we are limiting the range of freq. from 0 to ω_c i.e. Ideal filter (IFT) of rectangular spectrum is a S.F. which extends for all time.).

⇒ All ideal filters are non-causal and unstable.



IFT



⇒ Transition width is deciding the order of the filter (no. of energy storing elements).

⇒ Most of the Practical Systems we are designing as non-linear phase response. To make it as linear we are defining two parameters.

① Phase delay:

⇒ It is the delay i.e. occurring at a single freq. which is due to carrier

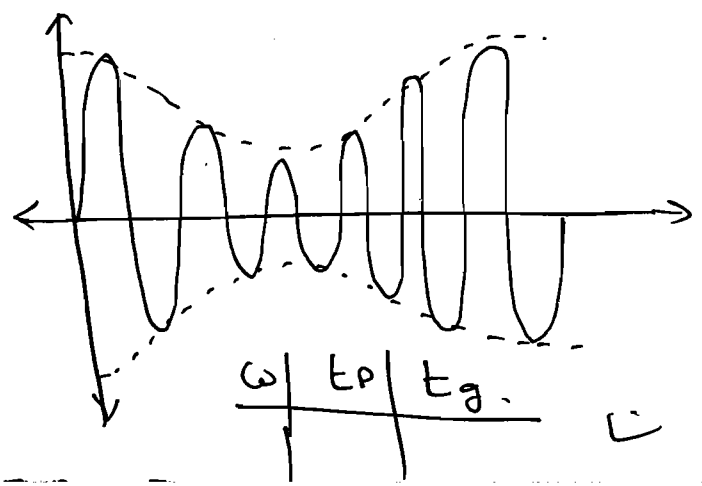
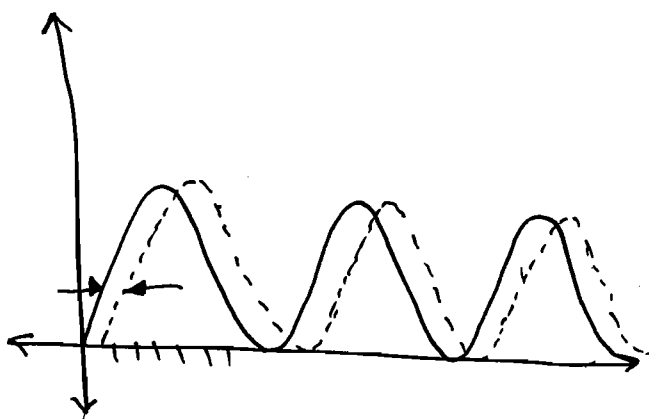
$$t_p(\omega) = - \frac{\theta(\omega)}{\omega}$$

② Group delay:

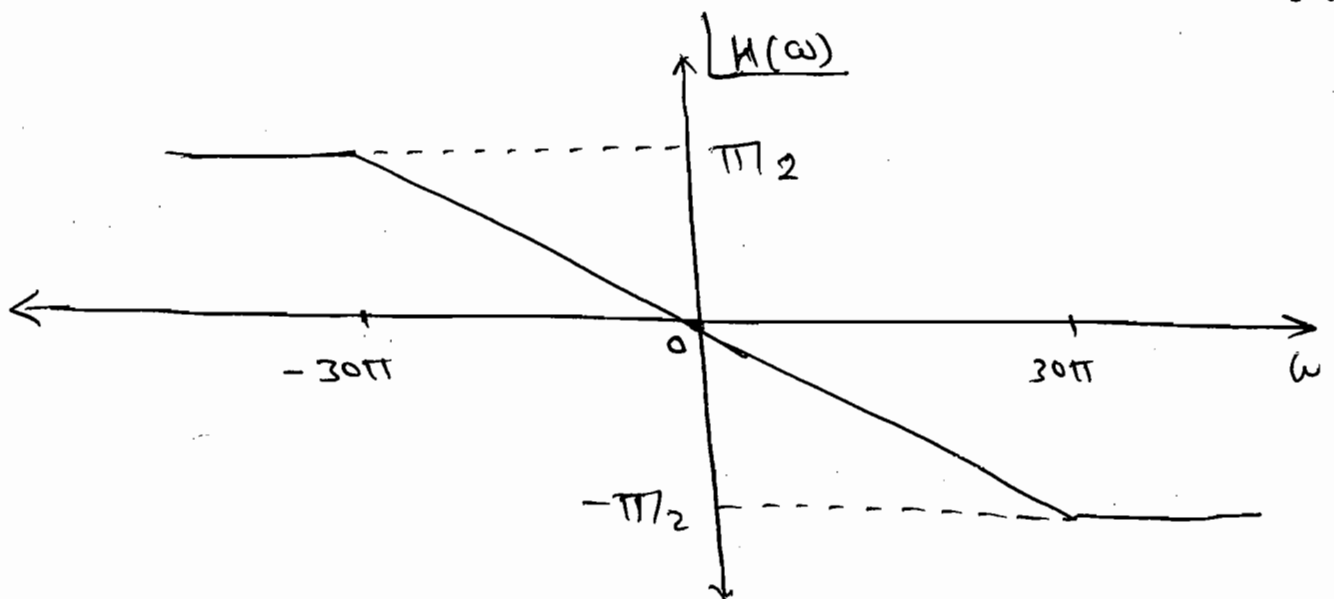
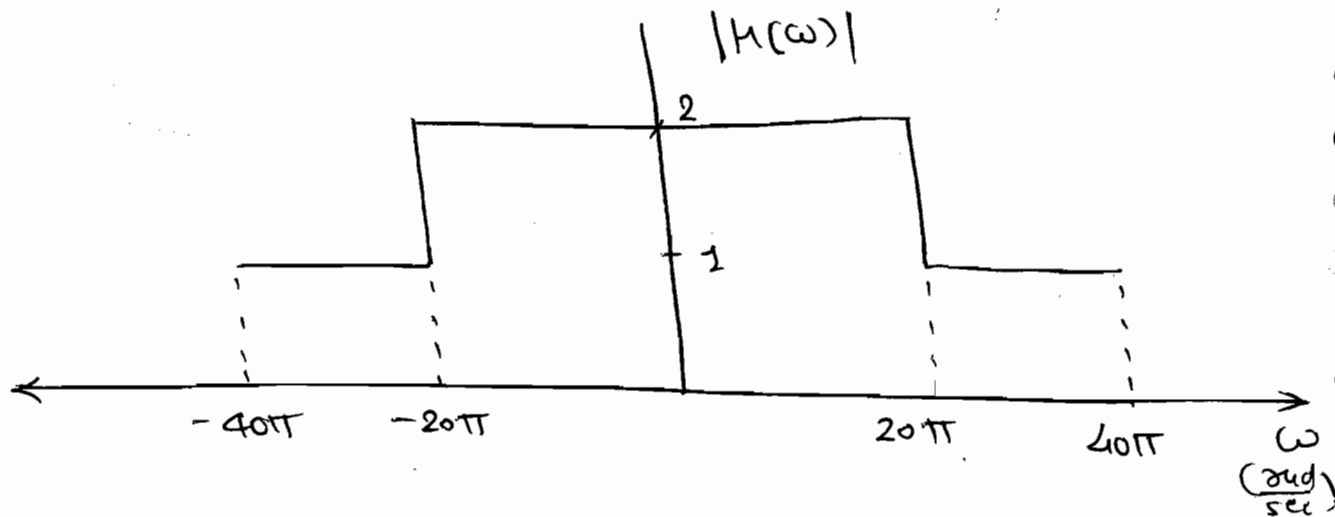
⇒ It is the delay i.e. occurring at a group (or) narrow band of freq. which is due to envelope of the msg signal.

$$t_g(\omega) = - \frac{d\theta(\omega)}{d\omega}$$

⇒ ∴ indicates the phase lag present in the ~~system~~ system.



P4.3-1 Consider a transmission system $H(\omega)$ with magnitude and phase response as shown in figure. If an input $x(t) = 2 \cos 10\pi t + \sin 20\pi t$ is given to the system the output will be ____.



Soln: $x(t) = 2 \cos 10\pi t + \sin 20\pi t$

① $\cos 10\pi t$

$\omega = \pm 30\pi \quad m = 1$

$\phi \Rightarrow \pm \pi/2$

So, $30\pi \quad -\pi/2$

$10\pi \quad (?)$

$\Rightarrow \phi = -\pi/2 \times 1/3 = -\pi/6$

So, at 10π , $m \Rightarrow 2$
 $\phi \rightarrow -\pi/6$.

② $\sin 26\pi t$.

m at $26\pi \Rightarrow 2$.

$\phi \Rightarrow 30\pi \rightarrow \pi/2$

$26\pi \rightarrow (?)$

$$\Rightarrow \phi = -\frac{13}{26\pi} \times \pi/2$$

$$\phi = -\frac{13\pi}{30}$$

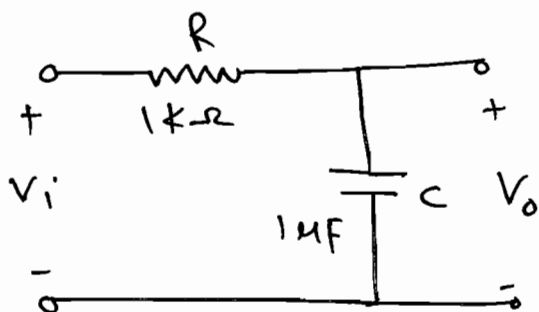
So, Ans: $(2)(2) \cos(10\pi t - \pi/6)$
 $+ \sin(26\pi t - \frac{13\pi}{30})$.

$$y(t) = 4 \cos(10\pi t - \pi/6) + \sin(26\pi t - \frac{13\pi}{30})$$

Q The System under consideration is an RC LPF with $R = 1k\Omega$ & $C = 1\mu F$

a) Let $H(f)$ denote the frequency response of an RC LPF with let f_1 be the highest freq. component such that $0 \leq |f| \leq f_1$, $\left| \frac{H(f_1)}{H(0)} \right| \geq 0.95$ then f_1 (in Hz) is _____.

Soln:



$$H(f) = \frac{1}{1 + j2\pi fRC}$$

$$|H(f)| = \frac{1}{\sqrt{1 + (2\pi fRC)^2}}$$

Now, given that

$$|H(f, \omega)| \geq 0.95 |H(0)|.$$

$$\text{So, } \frac{1}{\sqrt{1 + (2\pi f_1 RC)^2}} \geq 0.95 \times \frac{1}{\sqrt{1+0}}.$$

$$\Rightarrow \frac{1}{1 + (2\pi f_1 RC)^2} = 0.9025.$$

$$\Rightarrow 1 + (2\pi f_1 RC)^2 = 1.108$$

$$\therefore (2\pi f_1 RC)^2 = 0.108$$

$$(f_1 \times 10^{-6} \times 10^3)^2 = \frac{0.108}{4 \times \pi^2}$$

$$\Rightarrow \boxed{f_1 = 52.2 \text{ Hz}}$$

b) Let $t_g(f)$ denote the group delay of RC LPF and $f_2 = 100 \text{ Hz}$, then $t_g(f_2)$ in msec, is _____.

Soln:

$$\angle H(f) = -\tan^{-1}(2\pi f RC) = \phi(f).$$

$$\therefore t_g = -\frac{d\phi(f)}{df}$$

$$= + \frac{1}{1 + (2\pi f RC)^2}$$

$$= \frac{1}{1 + (2\pi \times 100 \times 10^{-6} \times 10^3)^2}$$

$$\boxed{t_g = 0.717 \text{ sec}}$$

P. 4.3.5 The input to a Channel is a band-pass signal. It is obtained by linearly modulating a sinusoidal Carrier with a single-tone signal. The output of the Channel due to this input is given by $y(t) = \frac{1}{100} \cos(100t - 10^{-6}) \cos(10^6 t - 1.56)$. The group delay (t_g) & the phase delay (t_p) in seconds, of the Channel are, —?

Solⁿ: $y(t) = \frac{1}{100} \cos(100(t - 10^{-8})) \cdot \cos(10^6(t - 1.56 \times 10^{-6}))$

$\downarrow$ msg signal $\downarrow$ carrier.

So, $t_g = 10^{-8}$ $t_p = 1.56 \times 10^{-6}$

$\Rightarrow$ Message signal gives t_g &
Carrier signal gives t_p .

Q Which of the following below is distortion less?

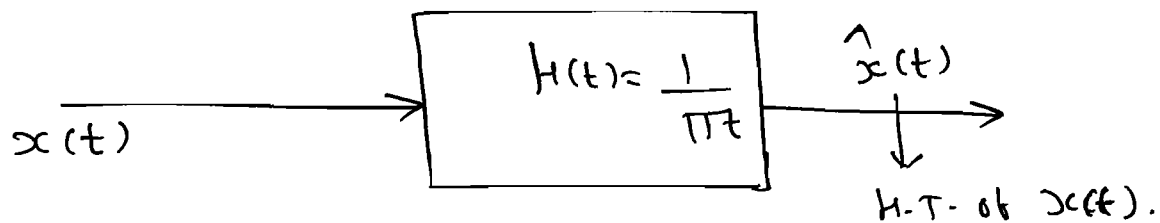
- ~~Solⁿ~~
- (A) $Q(\omega) = -\omega^2 + \omega^3$
 (B) $Q(\omega) = \ln \omega$
 (C) $Q(\omega) = e^\omega$
 (D) $Q(\omega) = -3\omega \rightarrow \text{Linear}$
- Non-linear

Solⁿ: Ans - (D) $\rightarrow Q(\omega) = -3\omega$
 $\downarrow$
 Linear.

2 Hilbert Transform:-

$\Rightarrow$ The Hilbert Transform is an operation that shifts the phase of $x(t)$ by $-\pi/2$, while the amplitude spectrum of the signal remains unaltered.

$\Rightarrow$



$$\Rightarrow \hat{x}(t) = x(t) * \frac{1}{\pi t}$$

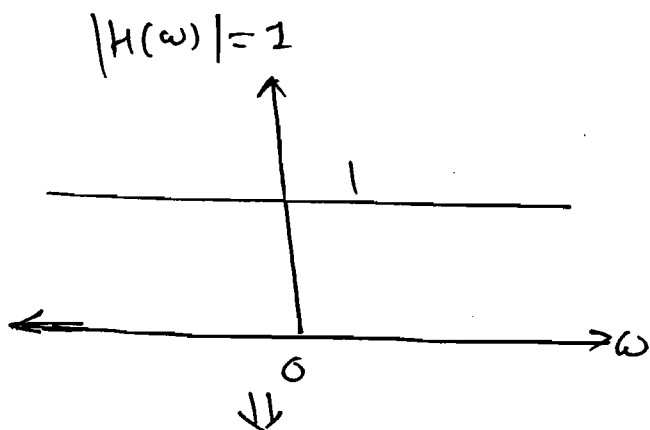
$\downarrow$ F.T.

$$\hat{X}(\omega) = X(\omega) \cdot [-j \operatorname{sgn}(\omega)]$$

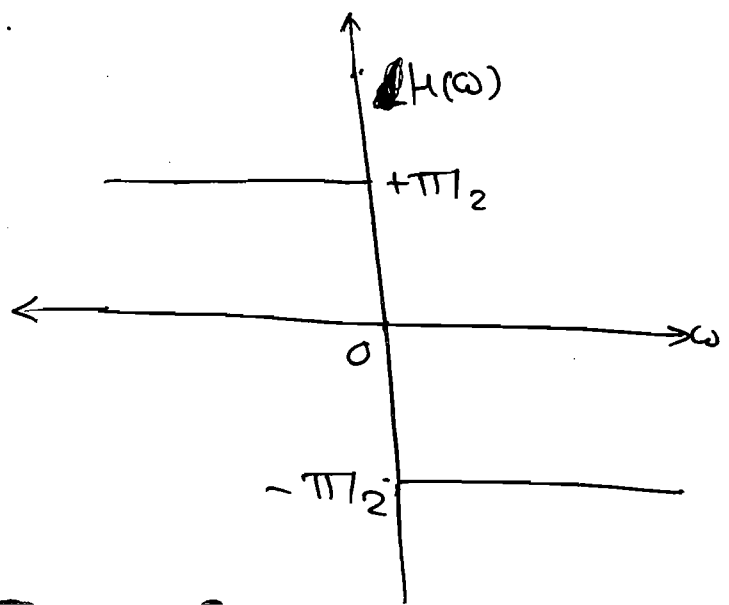
$\therefore$ freq. response
of H.T.

$$H(\omega) = \frac{\hat{X}(\omega)}{X(\omega)} = -j \operatorname{sgn}(\omega)$$

$$\Rightarrow H(\omega) = -j; \quad \omega > 0$$
$$= +j; \quad \omega < 0$$



All pass filter



$\Rightarrow$ An ideal H.T. is an all pass 90° phase shifter.

$\Rightarrow$ It is obeying orthogonality,

Area under two signals must be zero.

i.e.
$$\int_{t_1}^{t_2} x(t) \cdot \hat{x}(t) \cdot dt = 0.$$

* Properties of H.T.

1) H.T. doesn't change the domain of a signal.

2) H.T. doesn't alter the amplitude spectrum of a signal.

3) If $\hat{x}(t)$ is H.T. of $x(t)$, then H.T. of $\hat{x}(t)$ is $-x(t)$.

4) $x(t)$ and $\hat{x}(t)$ are orthogonal to each other.

P4.4.1 Find the H.T. of

(1) $x(t) = \cos \omega_0 t$

(2) $x(t) = \sin \omega_0 t.$

Soln:

$$\begin{aligned} x(t) = \cos \omega_0 t &\xrightarrow{\text{H.T.}} \cos(\omega_0 t - \pi/2) \\ &= \cos(\pi/2 - \omega_0 t) \\ &= \sin \omega_0 t. \end{aligned}$$

$$\begin{aligned} x(t) = \sin \omega_0 t &\xrightarrow{\text{H.T.}} \sin(\omega_0 t - \pi/2) \\ &= -\sin(\pi/2 - \omega_0 t) \\ &= -\cos \omega_0 t. \end{aligned}$$

$$\Rightarrow \text{H.T. of } e^{j\omega_0 t} (\omega_0 > 0) = -j e^{j\omega_0 t}$$

$$\downarrow$$

$$e^{j(\omega_0 t - \pi/2)} = e^{j\omega_0 t} \cdot e^{-j\pi/2}$$

$$= e^{j\omega_0 t} \cdot (-j)$$

$$= (-j) \cdot e^{j\omega_0 t}$$

$\Rightarrow$ H.T. of $\delta(t)$ is _____.

$$\Rightarrow \delta(t) * \frac{1}{\pi t} = \frac{1}{\pi t}$$

$\Rightarrow$ H.T. of $\frac{1}{\pi t}$ is _____.

$$\begin{array}{c} \text{---} \rightarrow \boxed{\text{H.T.}} \rightarrow \boxed{\text{H.T.}} \rightarrow \text{---} \\ (-j \operatorname{sgn} \omega)^2 = j^2 c(\omega) \\ = -1. \end{array}$$

$$\begin{aligned} & \text{(or)} \\ & = \cos(180^\circ) + \sin(180^\circ) \\ & = -1 + 0 \\ & = -1. \end{aligned}$$

* CORRELATION: - (correlogram).

$$x(t), x(t-\tau)$$

A.C.F

Auto Correlation fn

Energy

Power

$$x(t), y(t-\tau)$$

C.C.F

Cross Correlation fn.

Energy

Power.

⇒ It provide a measure of the similarity between 2 waveforms as the function of Search Parameter (τ).

⇒ An application of correlation to signal detection in a radar, when a signal pulse is transmitted in order to detect a suspect target. If a target is present, the pulse will be reflected by it. If the target is not present, there will be no reflection pulse, just noise. By detecting the presence (or) absence of the reflected pulse we confirm the presence (or) absence of target.

⇒

	A.C.F.
Energy	$R_x(\tau) = \int_{-\infty}^{+\infty} x(t) \cdot x(t-\tau) dt.$
Power	$R_x(\tau) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T x(t) \cdot x(t-\tau) dt.$

Lag (or)
Searching Parameter

* Properties of ACF:-

1) ACF is an even function of τ

$$\text{i.e. } R_x(\tau) = R_x(-\tau).$$

2) ACF at origin indicates either energy (or) power in the signal.

3) Max. value of ACF is at origin,

$$\text{i.e., } |R_x(\tau)| \leq |R_x(0)| \quad \forall \tau.$$

$$4) R_x(\tau) = x(\tau) * x(-\tau).$$

$$x(\tau) * x(-\tau) = \int_{-\infty}^{\infty} x(t) \cdot x(-(\tau-t)) \cdot dt.$$

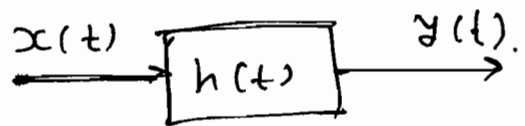
$$= \int_{-\infty}^{+\infty} x(t) \cdot x(t-\tau) \cdot dt = R_x(\tau).$$

5) F.T. of ACF is known as ESD (or) PSD

$$R_x(\tau) \xleftrightarrow{\text{F.T.}} S_x(\omega) \quad \text{ESD / PSD.}$$

6) For an LTI system

$$\therefore Y(\omega) = X(\omega) \cdot H(\omega).$$



$$\therefore |Y(\omega)|^2 = |X(\omega)|^2 \cdot |H(\omega)|^2.$$

$$\therefore |Y(\omega)|^2 = |X(\omega)|^2 \cdot |H(\omega)|^2.$$

$$\therefore S_y(\omega) = S_x(\omega) \cdot |H(\omega)|^2.$$

output spectral density = [input spectral density] $\times [|H(\omega)|^2]$.

P4.5.1 Find the Auto correlation and Power in the signal.

$$x(t) = 6 \cos(6\pi t + \frac{\pi}{3}).$$

Solⁿ:

$$P_{avg} = \frac{A^2}{2} = \frac{36}{2} = 18 \text{ W.}$$

$$\rightarrow R_x(\tau) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T 6 \cos(6\pi t + \frac{\pi}{3}) \cdot 6 \cos(6\pi t - 6\pi\tau + \frac{\pi}{3}) dt$$

$$= \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T \frac{36}{2} \cdot [\cos(12\pi t - 6\pi\tau + \frac{\pi}{3}) + \cos(6\pi\tau)] dt.$$

$$= \lim_{T \rightarrow \infty} \frac{18}{2T} \int_{-T}^T \cos(6\pi\tau) dt.$$

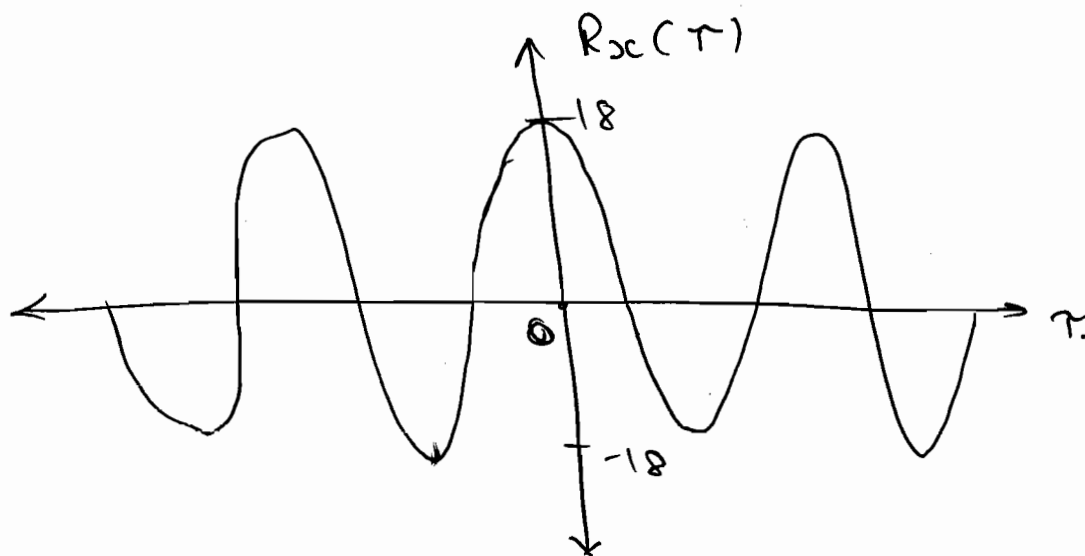
$$= \lim_{T \rightarrow \infty} \frac{18 \cos(6\pi\tau)}{2T} \times \int_{-T}^T dt.$$

$$= \lim_{T \rightarrow \infty} \frac{18 \cos(6\pi\tau)}{2T} \times 2T$$

$$\Rightarrow R_x(\tau) = 18 \cos(6\pi\tau).$$

(or) Power = $R_x(0) = 18 \text{ W.}$

$$\left. \begin{array}{l} A \cos(\omega_0 t + \theta) \\ A \sin(\omega_0 t + \theta) \end{array} \right\} \rightarrow \frac{A^2}{2} \cos(\omega_0 \tau) \leftarrow \text{ACF is fixed.}$$



P 4.5.2. Find the ACF of $x(t) = e^{-3t} u(t)$.

Soln:

$$R_x(t) = \int_{-\infty}^{\infty} x(t) \cdot x(t-\tau) \cdot d\tau.$$

energy signal.

Wrong

$$= \int_0^{\infty} e^{-3t} \cdot e^{-3(t-\tau)} \cdot d\tau$$

$$= e^{-3\tau} \int_0^{\infty} e^{-6t} \cdot d\tau$$

$$= \frac{e^{-3\tau}}{6} [0 - 1] = \frac{e^{-3\tau}}{6}.$$

$\Rightarrow x(t) = e^{-3t} \cdot u(t)$ is energy signal.

$$\therefore R_x(\tau) = \int_{-\infty}^{\infty} x(t) \cdot x(t-\tau) dt.$$

$$\therefore R_x(\tau) = \int_{-\infty}^{\infty} e^{-3t} \cdot u(t) \cdot e^{-3(t-\tau)} \cdot u(t-\tau) \cdot dt$$

$$u(t) \cdot u(t-\tau)$$

$$t > \tau$$

$$\& \quad t < \tau.$$

$$(OR)$$

$$\Rightarrow R_x(\tau) = x(\tau) * x(-\tau).$$

$$= e^{-3\tau} \cdot u(\tau) * e^{3\tau} \cdot u(-\tau).$$

F.T. $\downarrow$

$$= \left[\frac{1}{3+j\omega} \right] \times \left[\frac{1}{3-j\omega} \right].$$

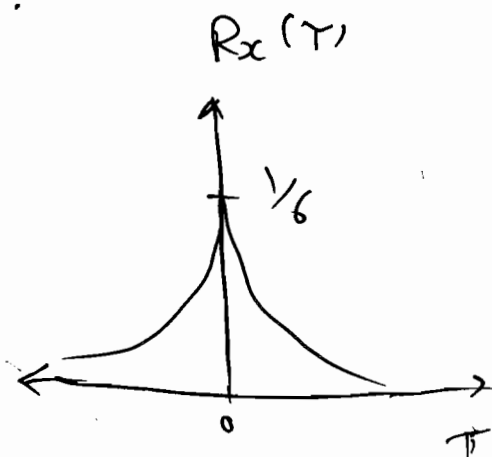
$$= \left(\frac{1}{\omega^2 + 9} \right)$$

$$= \frac{1}{6} \left(\frac{2(3)}{\omega^2 + (3)^2} \right).$$

$\downarrow$ I.F.T

$$\therefore R_x(\tau) = \frac{1}{6} e^{-3|\tau|}$$

$$\therefore R_x(0) = \text{Energy} = \frac{1}{6}.$$



Q P. 4.5.3

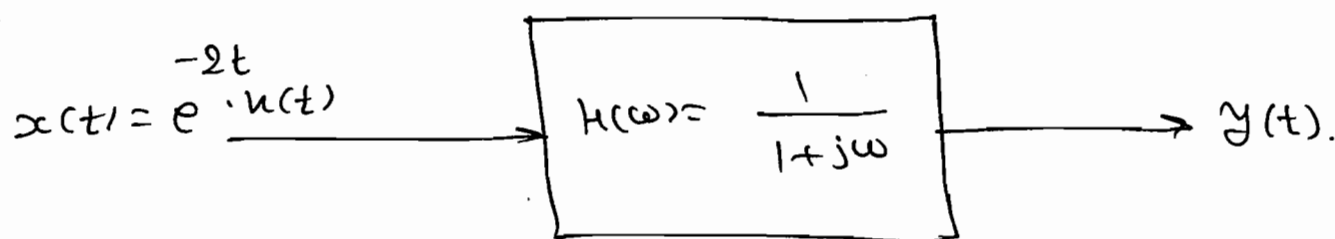
Consider a filter with $H(\omega) = \frac{1}{1+j\omega}$

and input $x(t) = e^{-2t} \cdot u(t)$.

(a) Find the ESD of the output?

(b) Show that total energy in the o/p is one-third of the input energy?

Soln:



$$\therefore x(t) = e^{-2t} \cdot u(t)$$

↓ F.T.

$$\therefore X(\omega) = \frac{1}{2+j\omega}$$

$$Y(\omega) = X(\omega) \cdot H(\omega)$$

$$|Y(\omega)|^2 = |X(\omega)|^2 \cdot |H(\omega)|^2$$

$$\therefore S_Y(\omega) = |H(\omega)|^2 \cdot S_X(\omega)$$

$$S_X(\omega) = |X(\omega)|^2 = \frac{1}{4+\omega^2}$$

$$\therefore |H(\omega)|^2 = \frac{1}{1+\omega^2}$$

$$\therefore S_Y(\omega) = \left(\frac{1}{1+\omega^2} \right) \times \left(\frac{1}{4+\omega^2} \right)$$

ESD at o/p.

(b) Energy = Area under ESD.

$$\therefore E_Y = \frac{1}{2\pi} \int_{-\infty}^{\infty} S_Y(\omega) \cdot d\omega$$

$$\begin{aligned}
 \therefore E_y(\omega) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{1}{(\omega^2+1)} \cdot \frac{1}{(\omega^2+4)} \cdot d\omega \\
 &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{\frac{1}{3}}{\omega^2+1} - \frac{\frac{1}{3}}{\omega^2+4} \cdot d\omega \\
 &= \frac{1}{2\pi} \times \frac{1}{3} \left[\tan^{-1}(\omega) - \frac{1}{2} \tan^{-1}(\omega/2) \right]_{-\infty}^{\infty} \\
 &= \frac{1}{6\pi} \left[\frac{\pi}{2} - \frac{\pi}{4} - \frac{\pi}{2} - \frac{\pi}{4} \right] \\
 &= \frac{1}{6\pi} \left[-\frac{\pi}{2} \right]
 \end{aligned}$$

$$\therefore E_y(\omega) = \frac{1}{12}$$

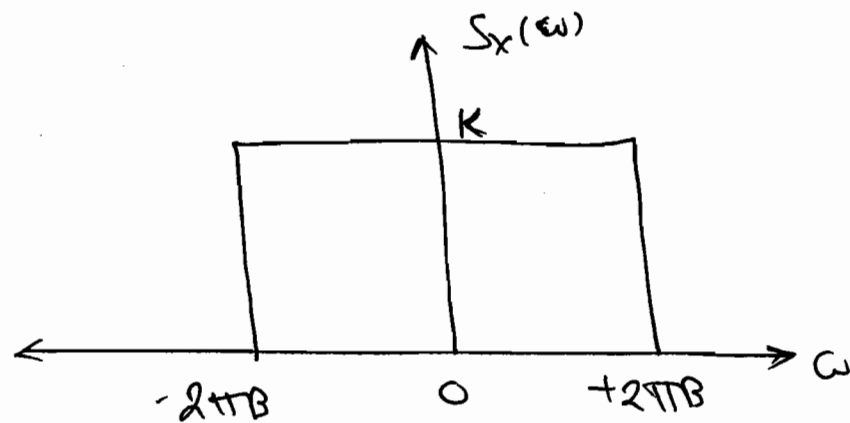
$$\begin{aligned}
 \Rightarrow \text{I/P } x(t) &= e^{-2t} u(t) \\
 E_x &= \int_0^{\infty} (e^{-2t})^2 \cdot dt \\
 &= \int_0^{\infty} e^{-4t} \cdot dt
 \end{aligned}$$

$$E_x = \frac{1}{4}$$

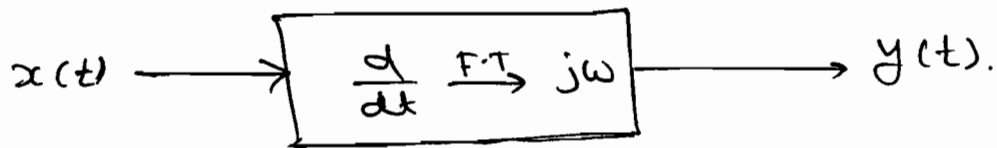
$$\text{So, } E_{O/P} = \frac{1}{3} E_{I/P}$$

P 4.5.4 A power signal whose p.s.d. is shown in fig. is applied to an ideal

differentiator, find the mean square value of the o/p of the differentiator.



Soln:



$\Rightarrow$ mean square value of o/p

= Power = Area under o/p PSD

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} S_y(\omega) d\omega.$$

Now, $S_y(\omega) = |H(\omega)|^2 S_x(\omega).$

So, $|H(\omega)|^2 = \omega^2.$

$$\therefore \text{M.S.V. of o/p} = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \omega^2 S_x(\omega) d\omega.$$

$$= \frac{1}{2\pi} \int_{-\infty}^{+\infty} \omega^2 S_x(\omega) d\omega.$$

$$= \frac{1}{2\pi} \int_{-2\pi B}^{2\pi B} \omega^2 \cdot K d\omega.$$

$$= \frac{1}{2\pi} \times 2 \times k \times \int_0^{2\pi B} \omega^2 \cdot d\omega$$

$$= \frac{k}{\pi} \times \left[\frac{\omega^3}{3} \right]_0^{2\pi B}$$

$$= \frac{k}{\pi} \times \frac{8 \times \pi^3 \times B^3}{3}$$

$$\boxed{\text{M.S.V. of } \sigma_P = \frac{8\pi^2 B^3 K}{3}}$$

P4.5.5 Find the C.C.F of $x(t) = e^{-t} u(t)$
and $y(t) = e^{-3t} u(t)$?

Soln:

$$\stackrel{=}{\text{ACF}} \Rightarrow R_x(\tau) = x(\tau) * x(-\tau).$$

$$\text{CCF} \Rightarrow R_{xy}(\tau) = x(\tau) * y(-\tau).$$

$$\neq R_{yx}(\tau) = y(\tau) * x(-\tau).$$

$$\therefore \boxed{R_{yx} = R_{xy}}$$

$$\text{So, } R_{xy}(\tau) = x(\tau) * y(-\tau).$$

$$\text{F.T.} \downarrow \Rightarrow \left[e^{-t} u(t) \right] * \left[e^{+3t} u(t) \right].$$

$$= \frac{1}{+1 + j\omega} \times \frac{1}{3 - j\omega}$$

$$= \frac{1}{(1 + j\omega)(3 - j\omega)}$$

$$= \frac{1}{4} \left[\frac{1}{1+j\omega} + \frac{1}{3-j\omega} \right].$$

↓ I.F.T.

$$R_x(t) = \frac{1}{4} \left[e^{-t} \cdot u(t) + e^{3t} \cdot u(-t) \right].$$

* F.T. of Periodic Signals :-

⇒ Periodic and discrete in one domain is corresponds to discrete & periodic in other domain.

$$\Rightarrow 1 \xrightarrow{\text{F.T.}} 2\pi \delta(\omega).$$

$$1. e^{j\omega_0 t} \xrightarrow{\text{F.T.}} 2\pi \delta(\omega - \omega_0)$$

$$\Rightarrow \cos \omega_0 t = \frac{1. e^{j\omega_0 t} + 1. e^{-j\omega_0 t}}{2}$$

$$\downarrow \text{F.T.} \quad = \frac{1}{2} \cdot e^{j(\omega - \omega_0)t} + \frac{1}{2} \cdot e^{j(-1)(\omega_0)t}$$

$$= \frac{2\pi}{2} \delta(\omega - \omega_0) + \frac{2\pi}{2} \delta(\omega + \omega_0).$$

$$\cos \omega_0 t \xrightarrow{\text{F.T.}} = 2\pi \left[\frac{\delta(\omega - \omega_0) + \delta(\omega + \omega_0)}{2} \right].$$

Rect	$\xleftrightarrow{\text{F.T.}}$	Sa (or) sinc
Δt	$\xleftrightarrow{\text{F.T.}}$	Sa ² (or) sinc ²

Impulse $\xleftrightarrow{\text{F.T.}}$ Constant

Impulse train $\xleftrightarrow{\text{F.T.}}$ Impulse train

Gaussian $\xleftrightarrow{\text{F.T.}}$ Gaussian.

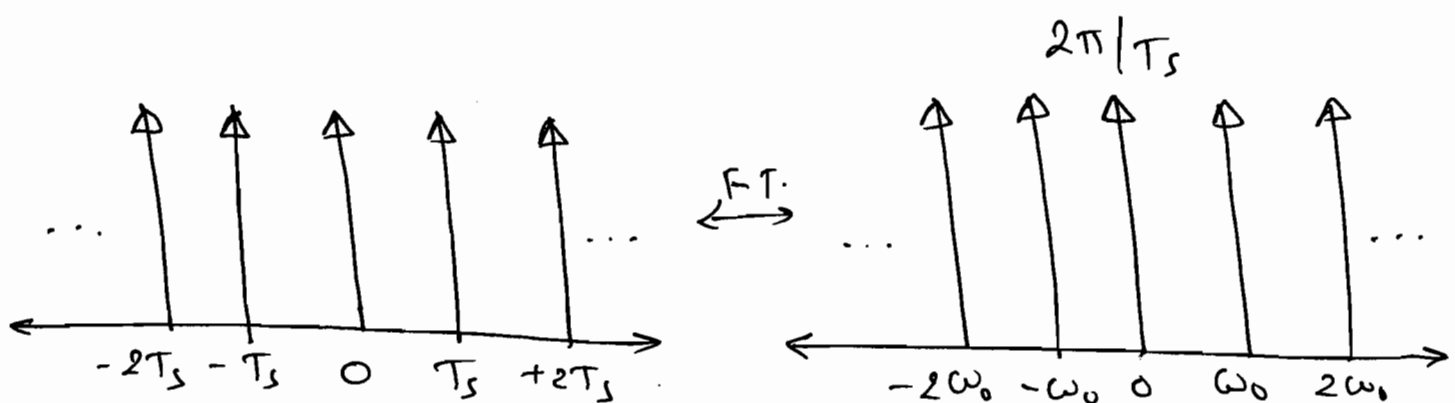
$\Rightarrow$

$$x_p(t) = \sum_{n=-\infty}^{\infty} C_n \cdot e^{jn\omega_0 t}$$

$\downarrow \text{F.T.}$

$$X_p(\omega) = 2\pi \sum_{n=-\infty}^{\infty} C_n \cdot \delta(\omega - n\omega_0).$$

$\Rightarrow$ F.T. of a Periodic signal consist of a sequence of equidistant impulse located at harmonic frequencies of the signal.



$\Rightarrow$

$$\sum_{n=-\infty}^{+\infty} \delta(t - nT_s) \leftrightarrow \frac{2\pi}{T_s} \sum_{n=-\infty}^{+\infty} \delta(\omega - n\omega_0).$$

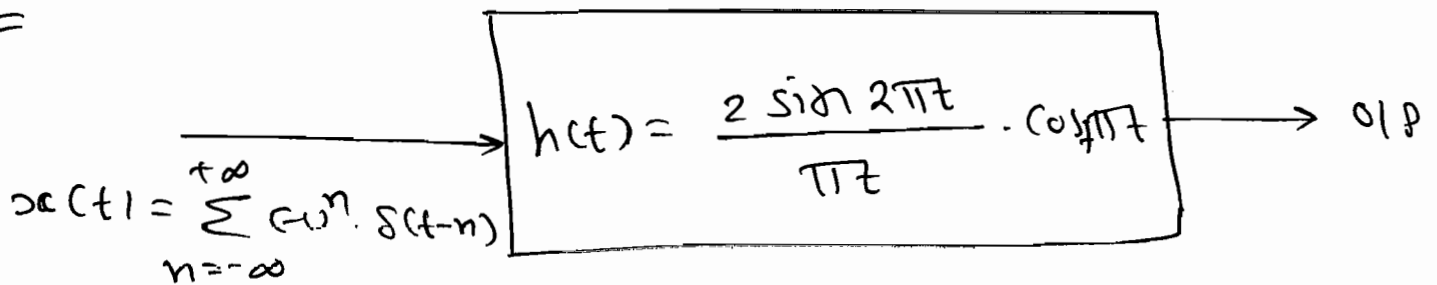
[Q] An L.T.I. sys. is having Impulse Response $h(t) = 2 \frac{\sin 2\pi t}{\pi t} \cdot \cos 7\pi t$ for

which the I/P applied is

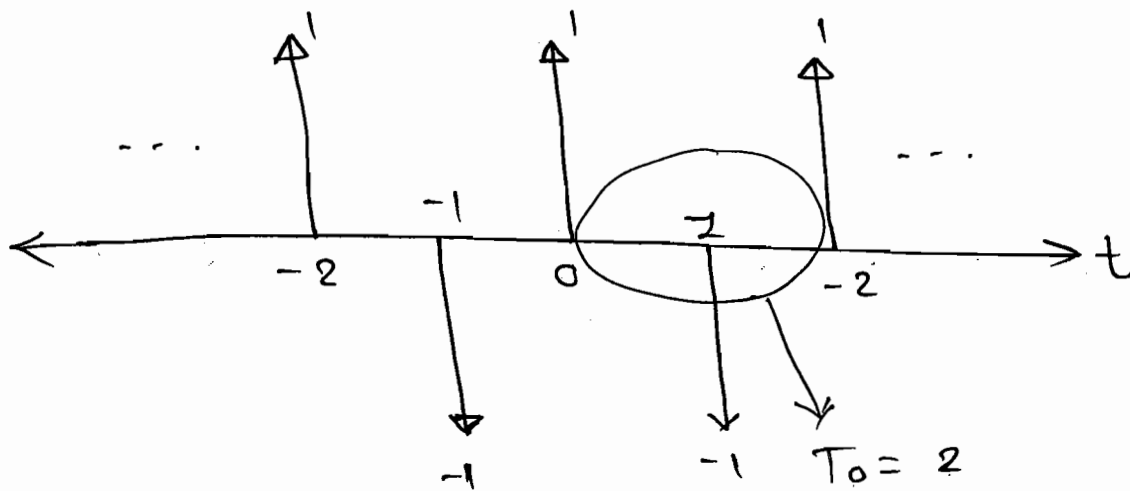
$$x(t) = \sum_{n=-\infty}^{+\infty} (-1)^n \delta(t-n), \text{ find the}$$

O/P.

Soln:



$$\Rightarrow x(t) = \sum_{n=-\infty}^{\infty} (-1)^n \delta(t-n).$$



$$\omega_0 = \frac{2\pi}{T} \Rightarrow \boxed{\omega_0 = \pi}$$

$\Rightarrow$ Now,

$$X_p(\omega) = 2\pi \sum_{n=-\infty}^{+\infty} C_n \delta(\omega - n\omega_0).$$

$$\text{So, } C_n = \frac{1}{T} \int_0^T x(t) \cdot e^{-j\omega_0 n t} dt.$$

$$\Rightarrow C_n = \frac{1}{2} \int_0^2 [\delta(t) - \delta(t-1)] e^{-jn\pi t} dt.$$

$$= \frac{1}{2} \left[\int_0^2 \delta(t) e^{-jn\pi t} dt - \int_0^2 \delta(t-1) e^{-jn\pi t} dt \right]$$

$\uparrow$ $t=0$ $\uparrow$ $t=1$
 Shifting property of impulse.

$$\Rightarrow C_n = \frac{1}{2} \left[e^{-jn\pi(0)} - e^{-jn\pi(1)} \right]$$

$$= \frac{1}{2} [1 - e^{-jn\pi}]$$

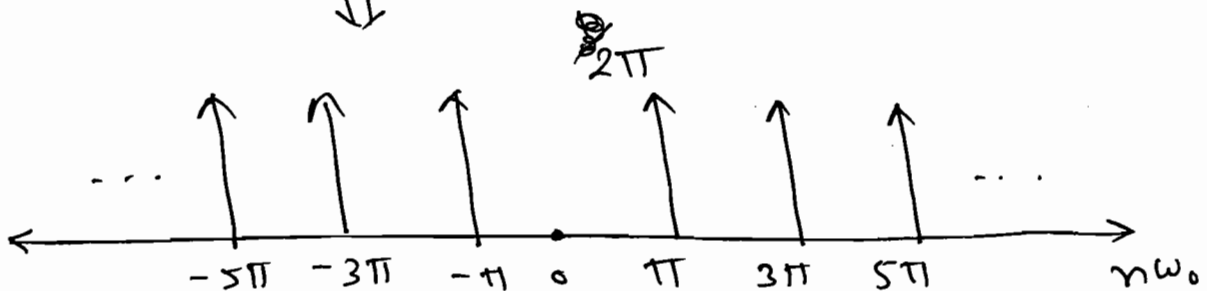
$$C_n = \frac{1}{2} [1 - (-1)^n]$$

$$\Rightarrow C_n = 1 \quad ; \quad n = \text{odd.}$$

$$= 0 \quad ; \quad n = \text{even.}$$

$$\therefore X_p(\omega) = \sum_{n=-\infty}^{+\infty} (1) \cdot \delta(\omega - n\pi) \quad (\because \omega_0 = \pi)$$

(odd n) $X_p(\omega)$

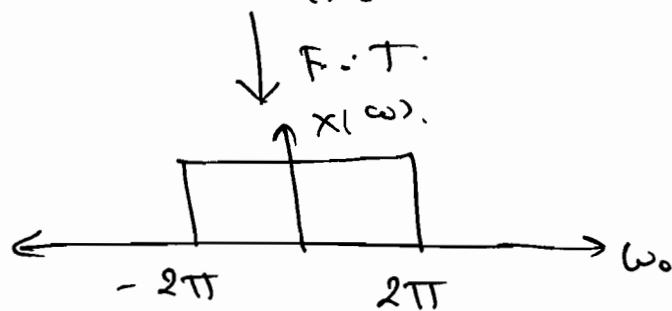


Now, $h(t) = \frac{2 \sin 2\pi t}{\pi t} \cdot \cos^2 \pi t$

$$= \frac{2 \sin 2\pi t}{\pi t} \cdot \left[\frac{e^{-j\pi t} + e^{j\pi t}}{2} \right]$$

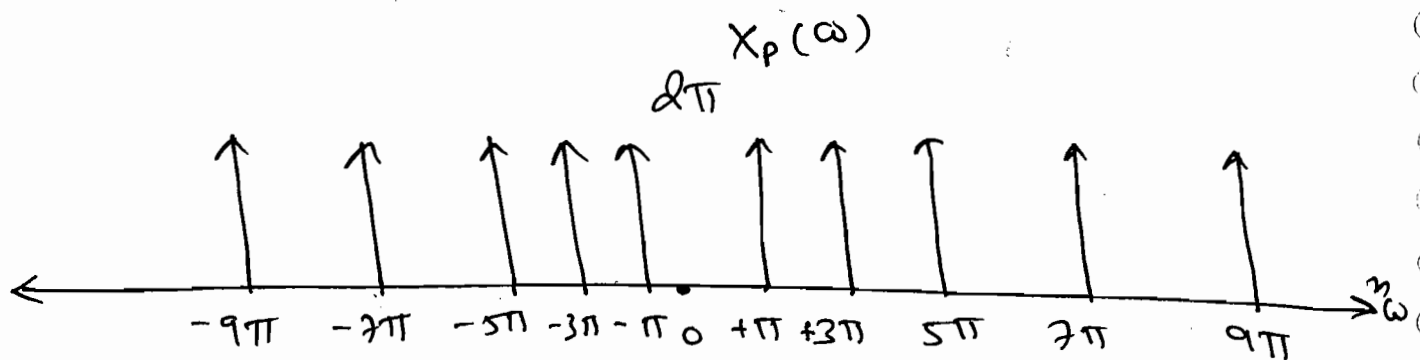
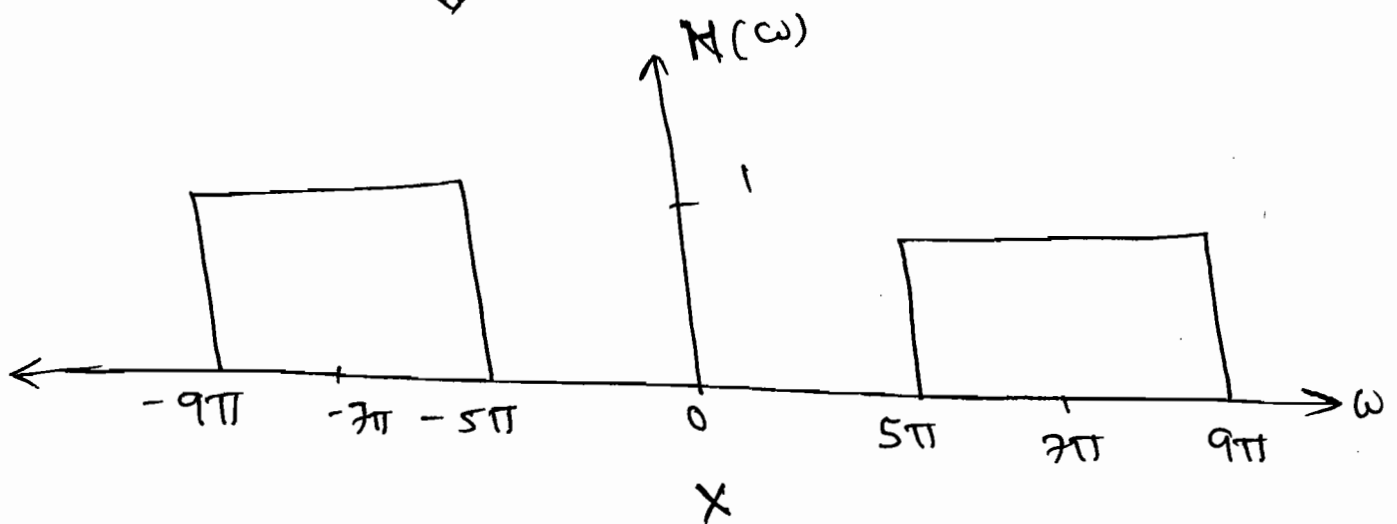
$$h(t) = \frac{\sin 2\pi t}{\pi t} \cdot \left[\frac{e^{-j\pi t} + e^{j\pi t}}{1} \right]$$

$$\text{i.e., } x(t) = \frac{\sin 2\pi t}{\pi t}$$

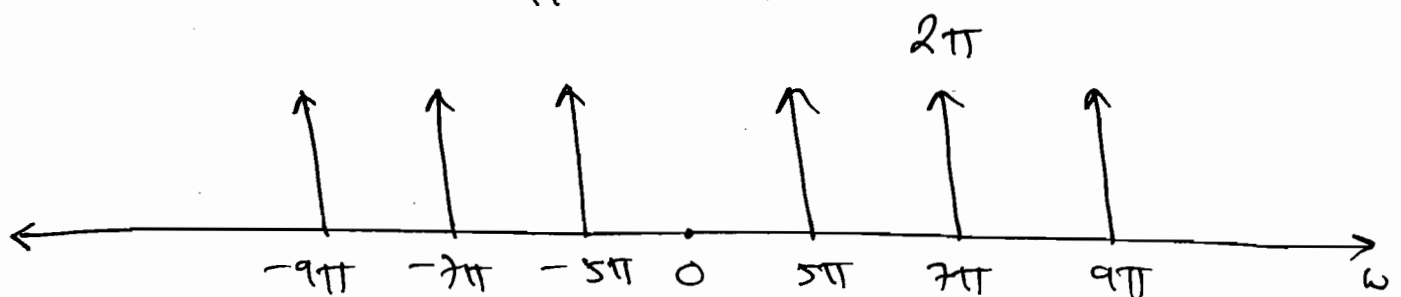


$$\therefore H(\omega) = X(\omega - 7\pi) + X(\omega + 7\pi)$$

⇓



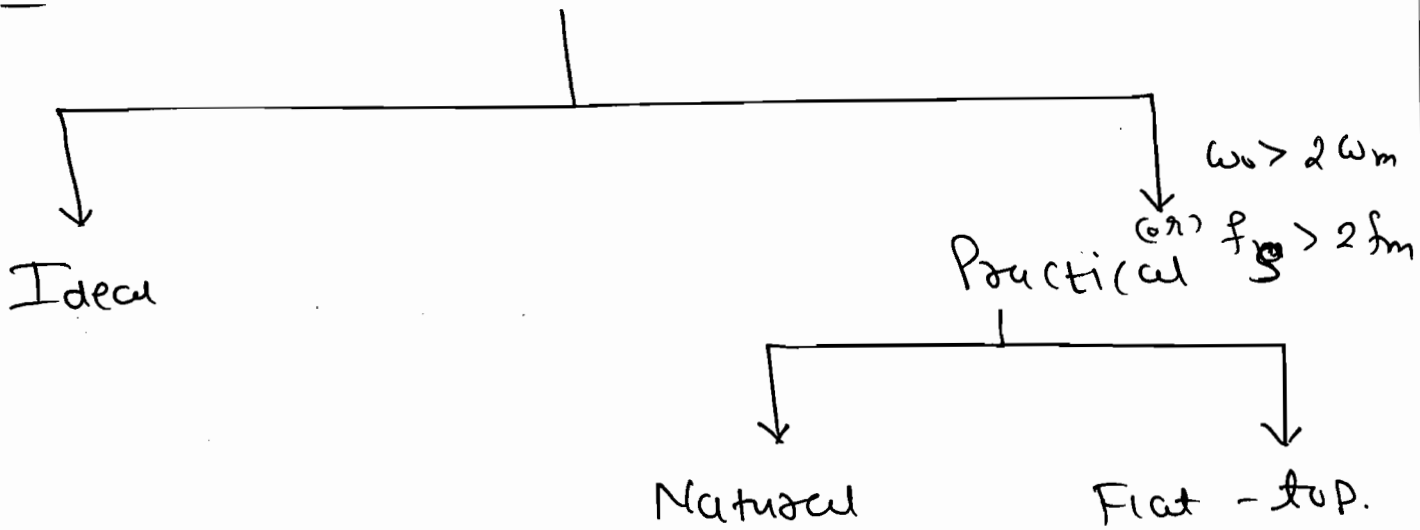
⇓
 $Y(\omega)$



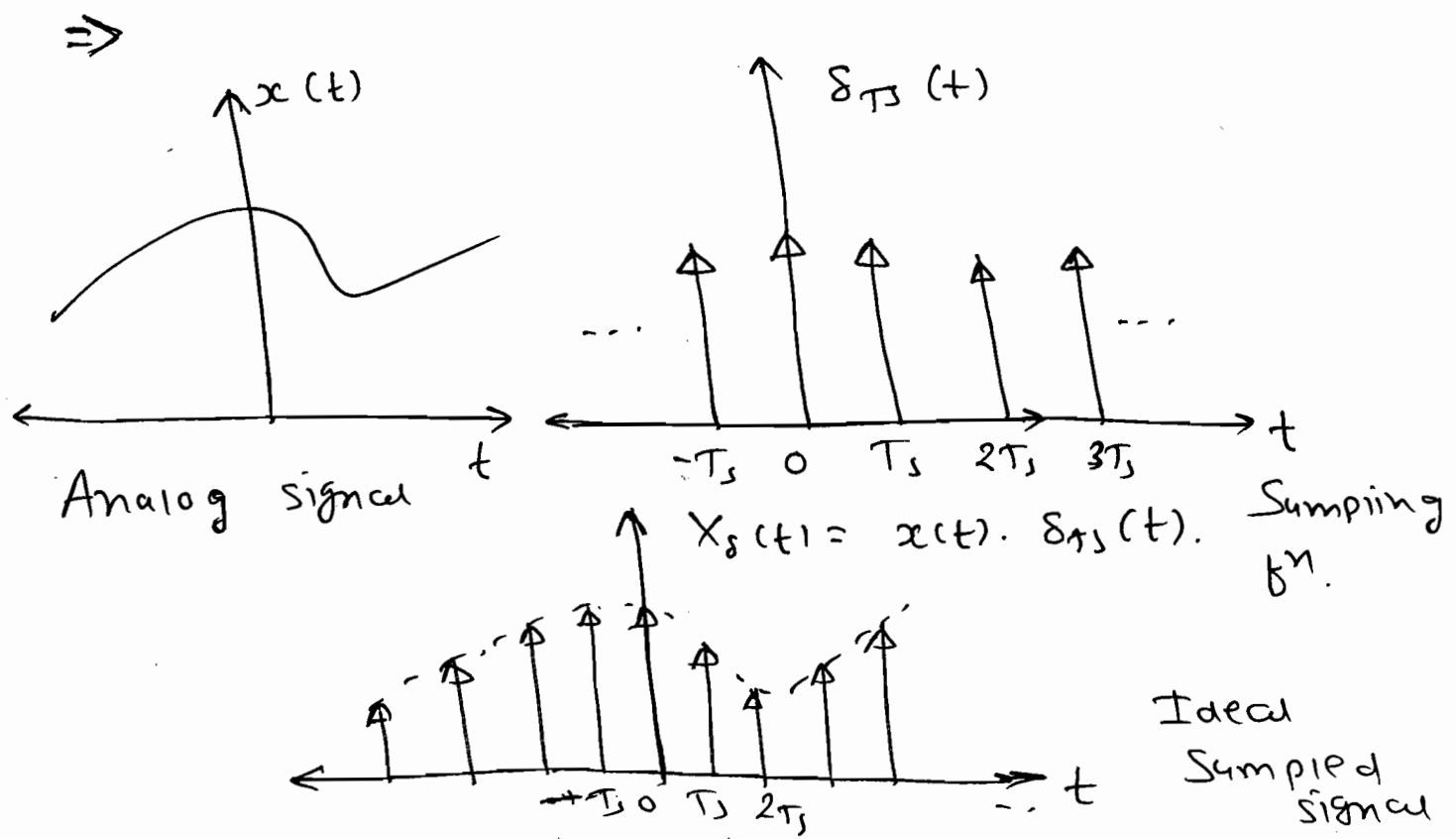
$$\Rightarrow Y(\omega) = 2\pi \left[\delta(\omega - 5\pi) + \delta(\omega + 5\pi) + \delta(\omega - 7\pi) + \delta(\omega + 7\pi) + \delta(\omega - 9\pi) + \delta(\omega + 9\pi) \right]$$

$$\therefore Y(\omega) = 2 [\cos 5\pi t + \cos 7\pi t + \cos 9\pi t]$$

* Sampling Theorem :-



① Ideal Sampling:-



$\Rightarrow x(t) \rightarrow$ Analog signal

$$\Rightarrow \delta_{TS}(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT_s)$$

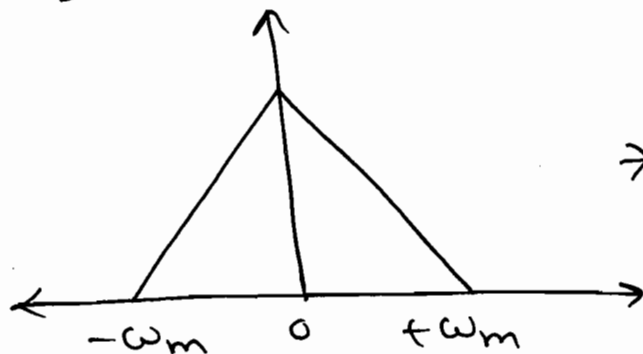
$\delta_{TS}(t) =$ Sampling function.

$\Rightarrow x_s(t) \rightarrow$ Ideally Sampled signal.

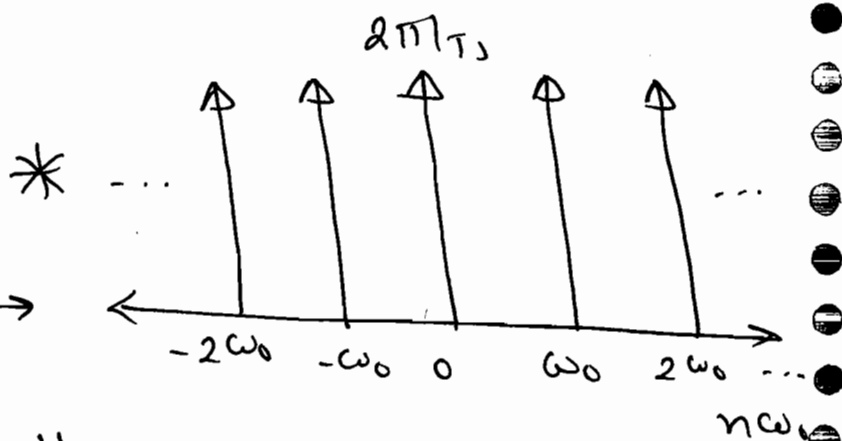
$$x_s(t) = x(t) \cdot \sum_{n=-\infty}^{+\infty} \delta(t - nT_s) \quad \leftarrow \text{Time domain.}$$

$\Rightarrow$ Take F.T.

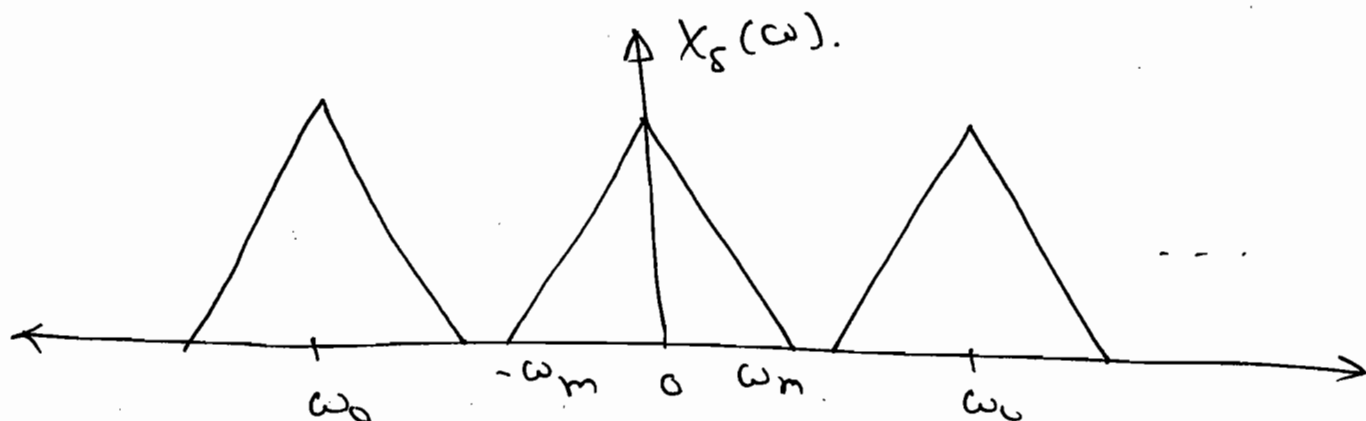
$$x(t) \leftrightarrow X(\omega)$$



$$\sum_{n=-\infty}^{\infty} \delta(t - nT_s) \xleftrightarrow{\text{F.T.}} \frac{1}{T_s} \sum_{n=-\infty}^{\infty} \delta(\omega - n\omega_0)$$



$\Downarrow$ Convolve.



$$\Rightarrow X_s(\omega) = \frac{1}{T_s} \left[X(\omega) * \sum_{n=-\infty}^{\infty} \delta(\omega - n\omega_0) \right]$$

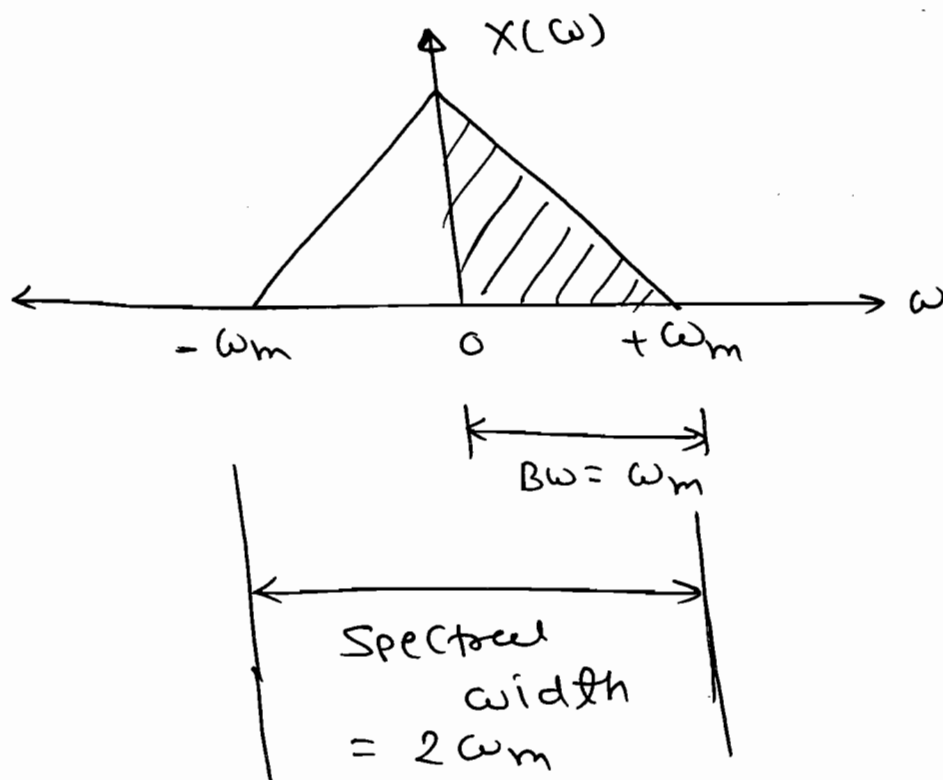
⇒ Spectrum of $x_s(t)$

⇒

$$X_s(\omega) = \frac{1}{T_s} \sum_{n=-\infty}^{+\infty} X(\omega - n\omega_0).$$

↑
Freq. domain.

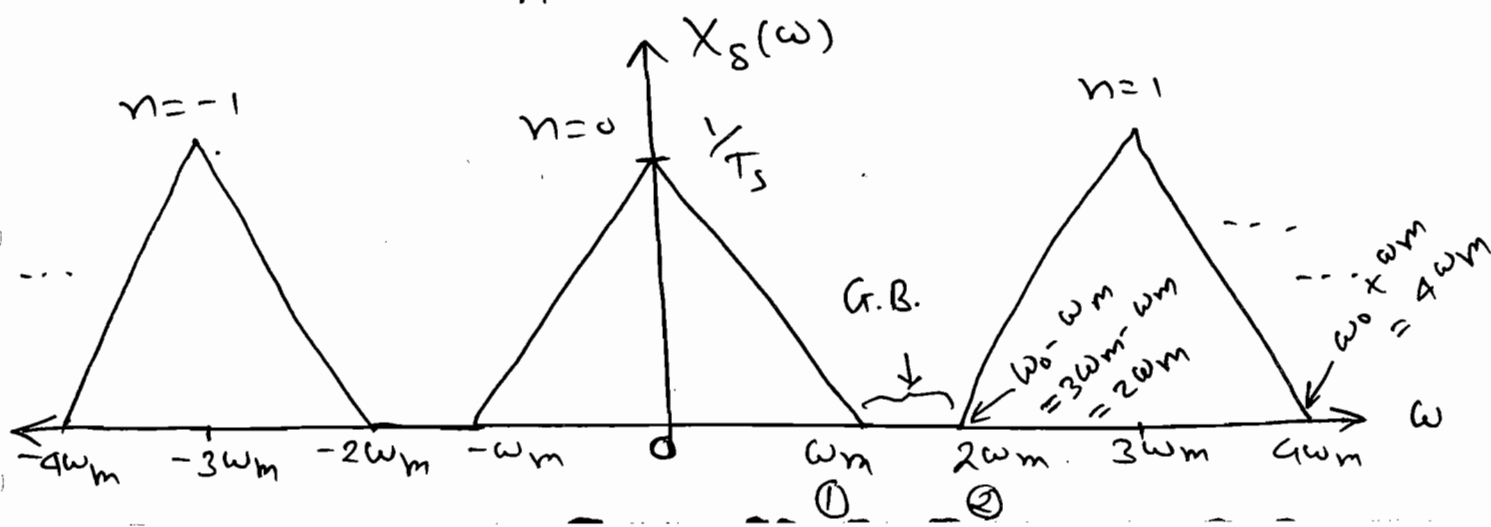
⇒ Assume Band limited Spectrum,



Case- (i): $\omega_0 > 2\omega_m$ ⇒ over Sampling

⇒ Let, $\omega_0 = 3\omega_m$

$$X_s(\omega) = \frac{1}{T_s} \sum_{n=-\infty}^{\infty} X(\omega - 3n\omega_m).$$



$$\Rightarrow \text{Guard Band} = (2) - (1) \\ = (\omega_0 - \omega_m) - (\omega_m)$$

$$\boxed{\text{Guard Band} = \omega_0 - 2\omega_m.}$$

$\Rightarrow$ Images don't overlap,

if ~~also~~ (2) > (1).

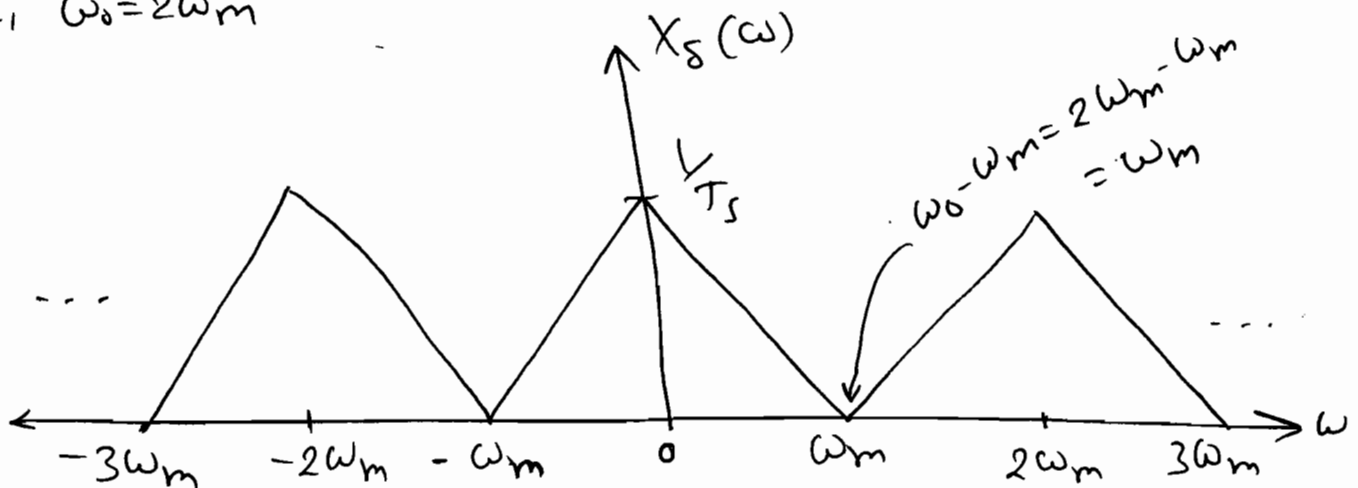
i.e. $\omega_0 - \omega_m > \omega_m.$

$$\Rightarrow \boxed{\omega_0 > 2\omega_m.}$$

Case-(ii):- $\omega_0 = 2\omega_m$, Critical Sampling.

$$\Rightarrow X_s(\omega) = \frac{1}{T_s} \sum_{n=-\infty}^{+\infty} X(\omega - 2\omega_m n).$$

let, $\omega_0 = 2\omega_m$



$$\Rightarrow \text{G.B.} = \omega_0 - 2\omega_m = 2\omega_m - 2\omega_m = 0.$$

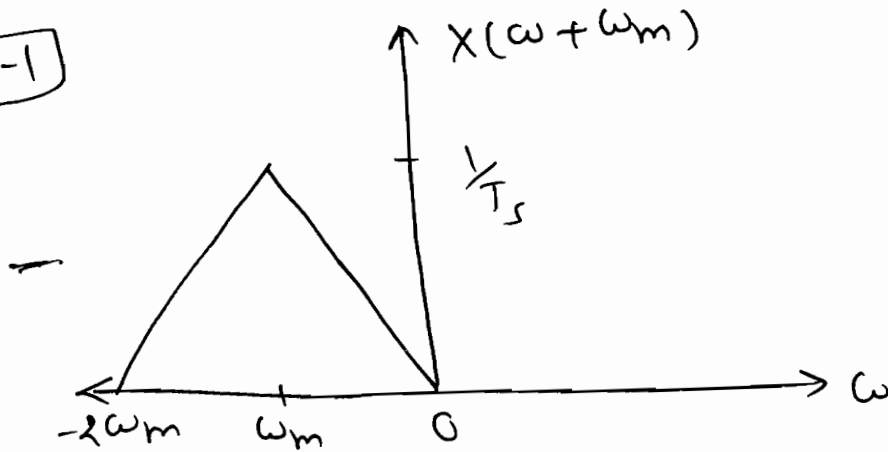
$$\boxed{\text{G.B.} = 0.}$$

$\Rightarrow$ Case-(iii):- $\omega_0 < 2\omega_m$ Under Sampling.

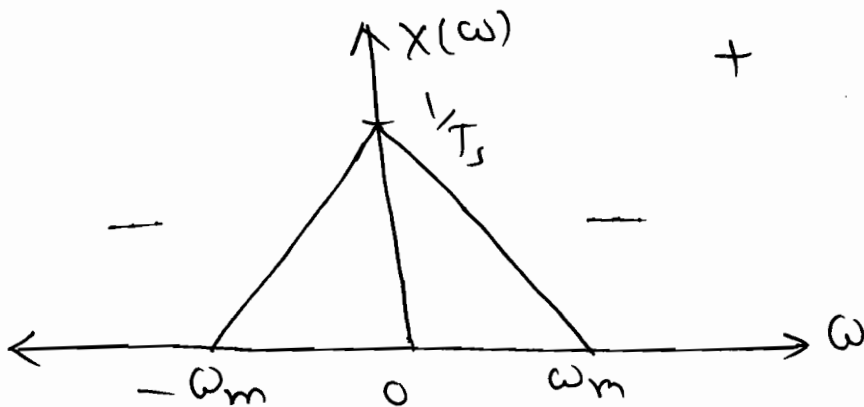
$\Rightarrow$ Let, $\omega_0 = \omega_m$.

$$\therefore X_s(\omega) = \frac{1}{T_s} \sum_{n=-\infty}^{\infty} X(\omega - n\omega_m).$$

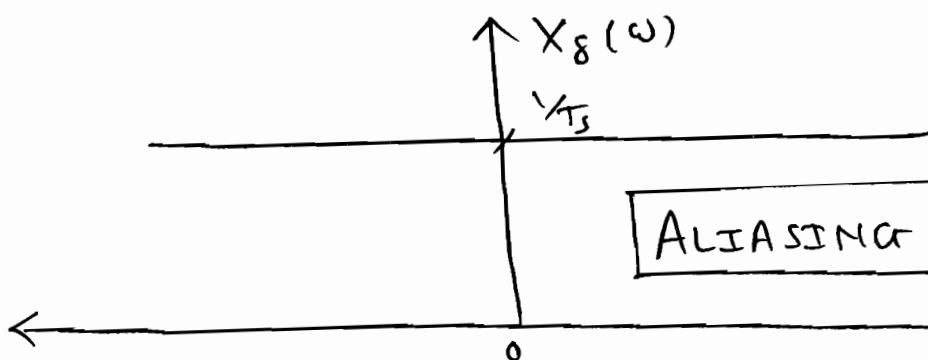
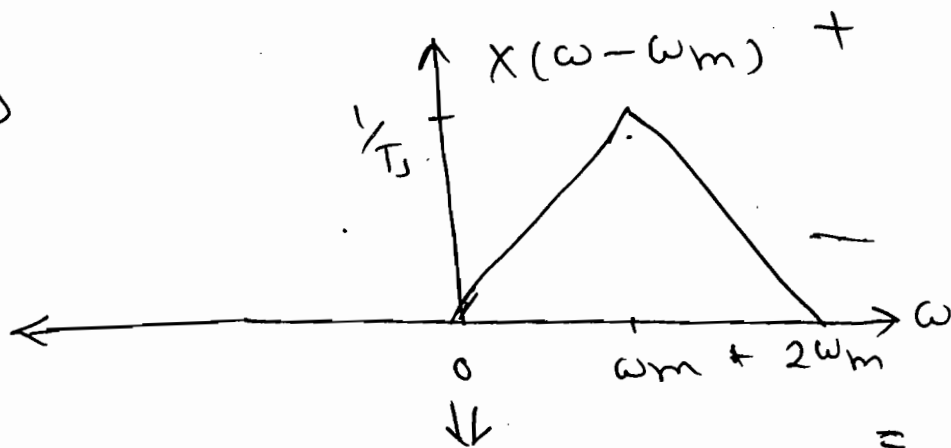
$n = -1$



$n = 0$



$n = 1$



ALIASING (or) Spectral

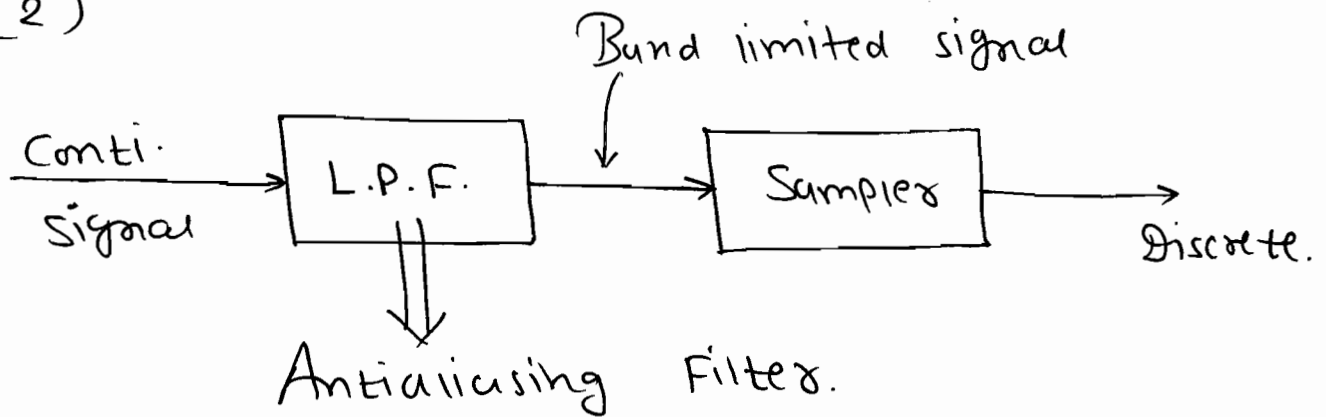
Folding.

⇒ To Avoid Aliasing

(1)

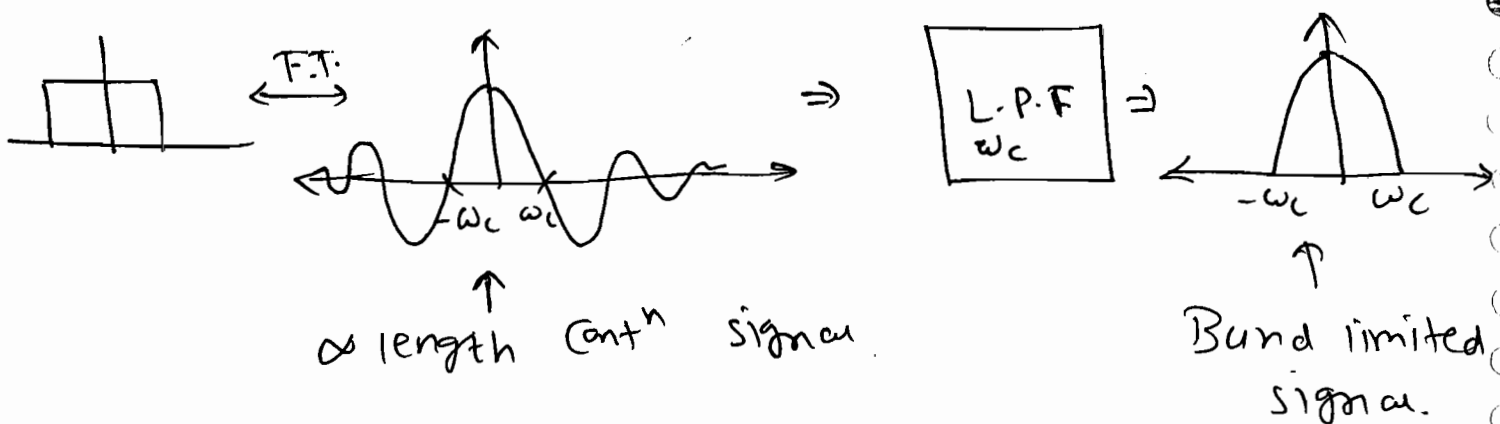
$$\omega_0 > 2\omega_m$$

(2)



⇒ No Spectrum in Real time is Band-limited. So, to make ∞ length spectrum as Band limited, Continuous signal is applied to L.P.F. before Sampling.

eg.



⇒ Nyquist Rate = minimum Sampling Rate

$$= 2\omega_m$$

= 2 (Highest freq. of signal component).

P4.6-1 Find the Nyquist rate & Nyquist interval for each of the following signals.

(a) $x_1(t) = \left(\frac{\sin 200\pi t}{\pi t} \right)$.

Soln: Here, $\omega_m = 200\pi$.

$$\therefore \text{N.R.} = 2\omega_m = 2(200\pi) \text{ rad/sec.}$$

$$\Rightarrow \text{N.R.} = 200 \text{ Hz.} = f_s$$

$$T_s = \frac{1}{f_s} = \frac{1}{200} \text{ sec.}$$

$$\therefore \boxed{T_s = 5 \text{ ms}}$$

(b) $x_2(t) = \left(\frac{\sin 200\pi t}{\pi t} \right)^2$.

Soln:
$$x_2(t) = \frac{1 + \cos 400\pi t}{4(\pi t)^2}$$

So, $\omega_m = 400\pi$

$$\text{N.R.} \Rightarrow \omega_0 = 2\omega_m = 2(400\pi) \text{ rad/sec.}$$

$$f_s = 2f_m = 400 \text{ Hz.}$$

$$\Rightarrow T_s = \frac{1}{f_s} = \frac{1}{400} \Rightarrow \boxed{T_s = 2.5 \text{ ms}}$$

(c) $x_3(t) = 5 \cos 1000\pi t \cos 4000\pi t$.

Soln:
$$x_3(t) = \frac{5}{2} \cdot 2 \cos 1000\pi t \cos 4000\pi t$$

$$= \frac{5}{2} (\cos 4000\pi t + \cos 5000\pi t)$$

$$\Rightarrow \omega_m = 5000 \pi$$

$$\Rightarrow \text{N.R.} = \omega_0 = 2\omega_m = 2(5000\pi) \text{ rad/sec.}$$

$$f_s = 2f_m = 5 \text{ kHz.}$$

$$\Rightarrow T_s = \frac{1}{5k} = 0.2 \text{ msec.}$$

$$\boxed{T_s = 0.2 \text{ ms}}$$

$$(d) X_4(t) = e^{-\delta t} u(t) * \frac{\sin at}{\pi t}$$

Soln:

$$X_4(\omega) = \frac{1}{\delta + j\omega} \times \text{[Rectangular Pulse from } -a \text{ to } a \text{ with height 1]}$$

$\downarrow \text{F.T}$
 $\downarrow \text{F.T}$

$$= \text{[Gaussian Curve]} \times \text{[Rectangular Pulse from } -a \text{ to } a \text{ with height 1]}$$

$$= \text{[Truncated Gaussian Curve } X_4(\omega) \text{ from } -a \text{ to } a \text{]} \times \omega$$

$$\Rightarrow \omega_m = a.$$

$$\text{N.R.} \Rightarrow \omega_0 = 2\omega_m = 2a. \text{ rad/sec.}$$

$$f_s = 2f_m = 2 \times \frac{\omega_m}{2\pi} = \frac{a}{\pi} \text{ Hz.}$$

$$\Rightarrow \boxed{T_s = \frac{\pi}{a} \text{ sec}}$$

$$(e) X_5(t) = \text{sinc}(100t) + 3 \text{sinc}^2(60t).$$

Soln: $x_5(t) = \frac{\sin(100\pi t)}{100\pi t} + 3 \left(\frac{\sin 60\pi t}{60\pi t} \right)^2$

$$x_5(t) = \frac{\sin(100\pi t)}{100\pi t} + 3 \left[\frac{1 - \cos 120\pi t}{(2)^2 \times (60\pi t)^2} \right]$$

$\Rightarrow \omega_m = 120\pi$

N.R. $\Rightarrow \omega_0 = 2\omega_m = 2(120\pi) \text{ rad/sec.}$

$f_s = 2f_m = 120 \text{ Hz.}$

$\Rightarrow T_s = \frac{1}{120} \text{ sec.}$

P 4.6.2. Let $x(t)$ be a signal with Nyquist rate ω_0 . Determine the Nyquist rate for each of the following signals.

(a) $x(t) + x(t-1)$.

Soln: $x(t) \rightarrow \text{B.W.} = \omega_m$
 $\quad \quad \quad \& \quad \text{N.R.} = \omega_0$

i.e. $\boxed{\omega_0 = 2\omega_m}$

F.T.

$X(\omega) + e^{-j\omega} X(\omega) \rightarrow \text{N.R.} = \omega_0$

Bw not change hence N.R. not change. i.e. ω_0 .

(b) $\frac{d}{dt} x(t)$.

$\Rightarrow$ Soln: $\downarrow \text{F.T.} = j\omega X(\omega)$

$\Rightarrow$ B.W. not change hence N.R. Same.
i.e. ω_0 .

(c) $x(3t)$.

Solⁿ: $x(3t) \xleftrightarrow{\text{F.T.}} \frac{1}{|3|} \cdot X(\omega/3)$.

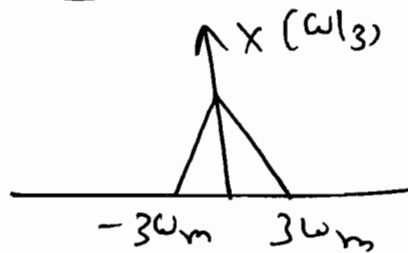
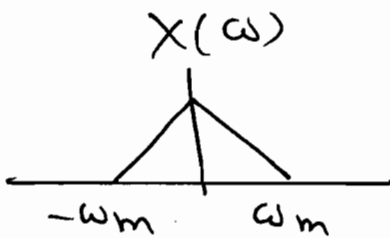
New B.W. $\Rightarrow \omega_m' = 3\omega_m$.

So. New N.R.

$\omega_0' = 2(3\omega_m)$
 $= 3(2\omega_m)$

$\omega_0' = 3\omega_0$

~~$\omega_0' = 3(2\omega_m)$~~
 ~~$\omega_0' = 3\omega_0$~~

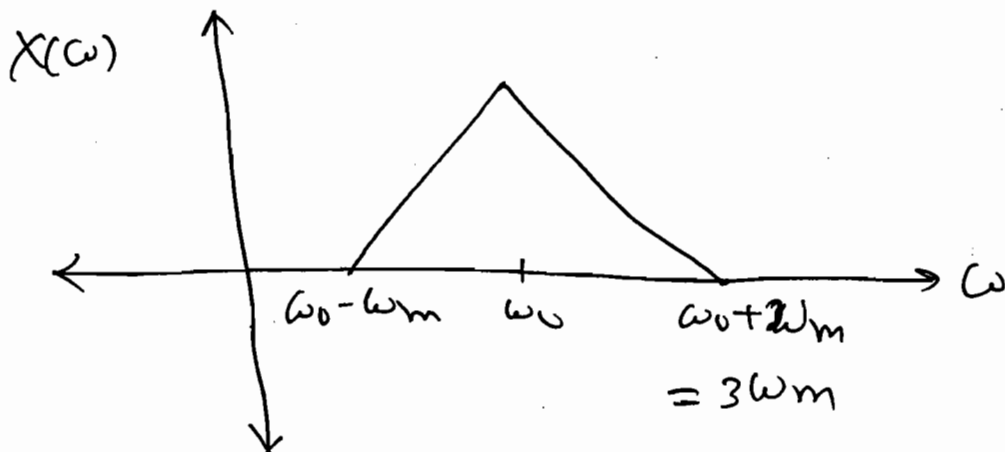


(d) $x(t) \cdot \cos(\omega_0 t)$.

Solⁿ: $x(t) \cdot \cos(\omega_0 t) \xleftrightarrow{\text{F.T.}} \pi \left[X(\omega_m - \omega_0) + X(\omega_m + \omega_0) \right]$.

eg. $\omega_0 = 2\omega_m$

~~$= \pi [X(\omega_m - 2\omega_m) + X(\omega_m + 2\omega_m)]$~~



So, New N.R. $\omega_0' = 2 (3\omega_m)$

$= 3(2\omega_m)$

$$\boxed{\omega_0' = 3\omega_0}$$

P4.6.3 Two signals $x_1(t)$ & $x_2(t)$ are band limited to 2 kHz & 3 kHz respectively, find the Nyquist rate of the following signals.

Solⁿ: (a) $x_1(2t)$.

Solⁿ: $x_1(2t) \xleftrightarrow{F.T.} \frac{1}{2} X_1(\omega/2)$

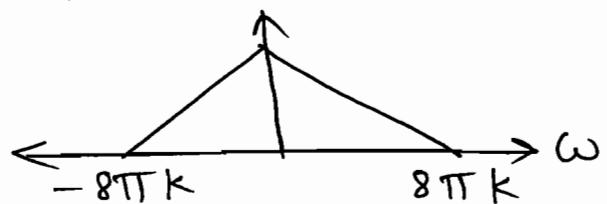
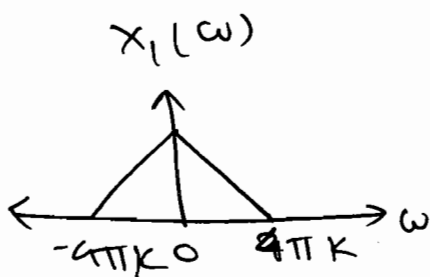
$x_1(t) \rightarrow B.W. = 2 \text{ kHz}$

So, N.R. of $x_1(t) \Rightarrow \text{Sample rate} = 4 \text{ kHz}$.

$f_{s_1} = 2 f_{m_1} = 4 \text{ kHz}$

$\omega_0 = 2 \omega_{m_1} = 8\pi \text{ k rad/sec}$

$x_1(\omega/2)$



So, N.R. of $x_1(t)$

$\Rightarrow \omega_0' = 2 \omega_{m_1}' = 2 (8\pi) \text{ k}$
 $= 16\pi \text{ k rad/sec}$

$f_{s_1}' = 2 f_{m_1}'$

$$\boxed{f_{s_1}' = 8 \text{ kHz}}$$

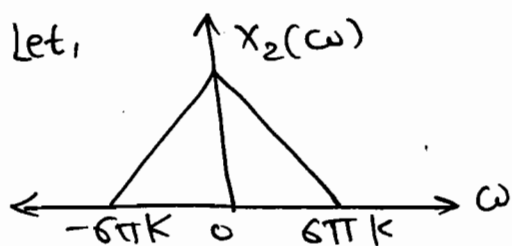
(b) $x_2(t-3)$.

Soln: B.W. of $x_2(t)$ is $\rightarrow 3 \text{ KHz}$.
 $\Rightarrow f_{m_2} = 3 \text{ KHz}$.

N.R. $f_{s_2} = 2 f_{m_2} = 6 \text{ KHz}$

$\omega_{o_2} = 2 \omega_{m_2} = 6(2\pi) = 12\pi \text{ k rad/sec}$

Now, $x_2(t-3) \xleftrightarrow{\text{F.T.}} e^{-j3\omega} \cdot X_2(\omega)$.



B.W. is not change. Hence.
 N.R. is not change.

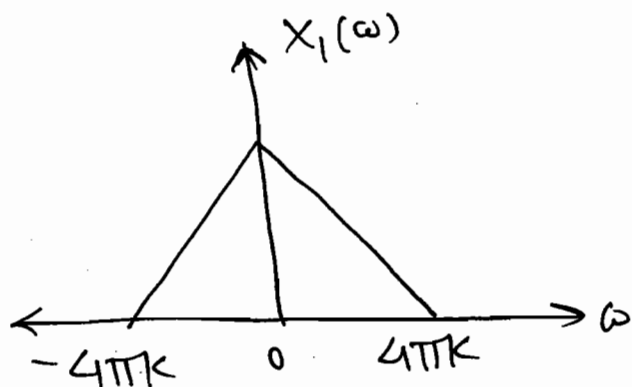
i.e. N.R. of $x_2(t-3)$

$\Rightarrow \omega'_{o_2} = 2 \omega_{m_2} = 12\pi \text{ k rad/sec}$.

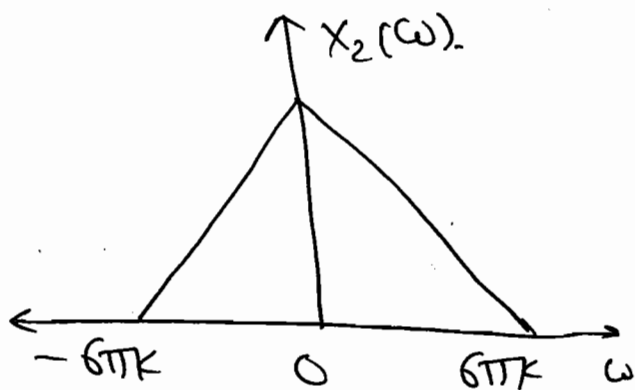
& $f'_{s_2} = 2 f_m = 6 \text{ KHz}$

(c) $x_1(t) + x_2(t)$.

Soln: $x_1(t) + x_2(t) \xleftrightarrow{\text{F.T.}} X_1(\omega) + X_2(\omega)$.



+



$\Rightarrow$ Max. freq. after addition of $x_1(\omega)$
 & $x_2(\omega)$ is $6\pi \text{ k rad/sec}$.

$$\Rightarrow \omega_m' = 6\pi k \text{ rad/sec}$$

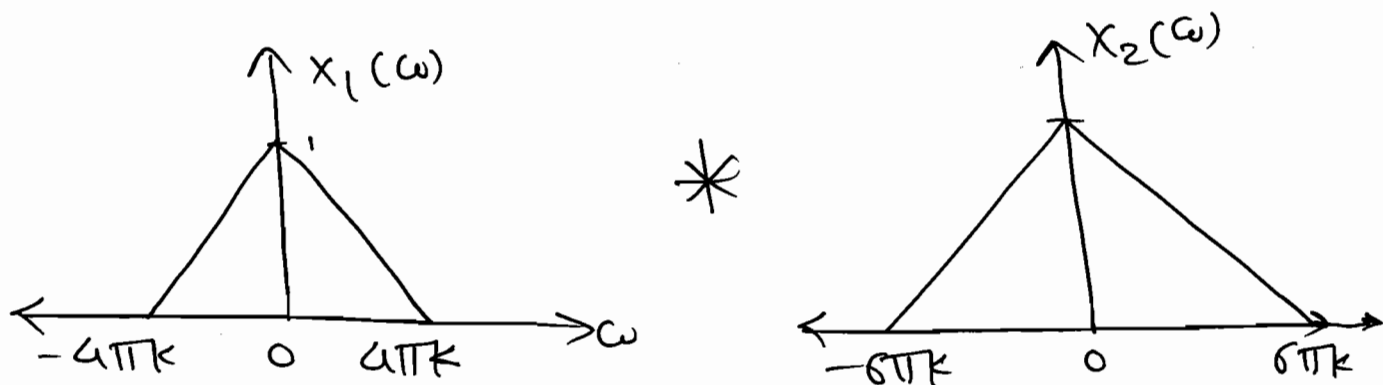
$$\text{N.R.} \Rightarrow \omega_o' = 2\omega_m' = 12\pi k \text{ rad/sec.}$$

$$\therefore \boxed{f_s' = 2f_m' = 6k \text{ Hz.}}$$

$$(d) x_1(t) \cdot x_2(t).$$

$$\text{Soln:} \quad \text{Mul.} \xleftrightarrow{\text{F.T.}} \text{Conv.}$$

$$\therefore x_1(t) \cdot x_2(t) \xleftrightarrow{\text{F.T.}} X_1(\omega) * X_2(\omega).$$



$\Rightarrow$ After Convolution new upper & lower limit of the signal are.

$$\text{Lower limit} = \left\{ \begin{array}{l} \text{Sum of the lower} \\ \text{limit of } x_1(\omega) \text{ \& } x_2(\omega) \end{array} \right\}.$$

$$\text{Upper limit} = \left\{ \begin{array}{l} \text{Sum of the upper} \\ \text{limit of } x_1(\omega) \text{ \& } x_2(\omega) \end{array} \right\}.$$

$$\Rightarrow \text{So, Lower limit} = \{-10\pi k\}.$$

$$\text{Upper limit} = \{+10\pi k\}.$$

$$\text{So, } \omega_m' = 10\pi k \text{ rad/sec.}$$

$$\text{N.R. } \omega_o' = 2\omega_m' = 2(10\pi k) = 20\pi k \frac{\text{rad}}{\text{sec.}}$$

$\Rightarrow$

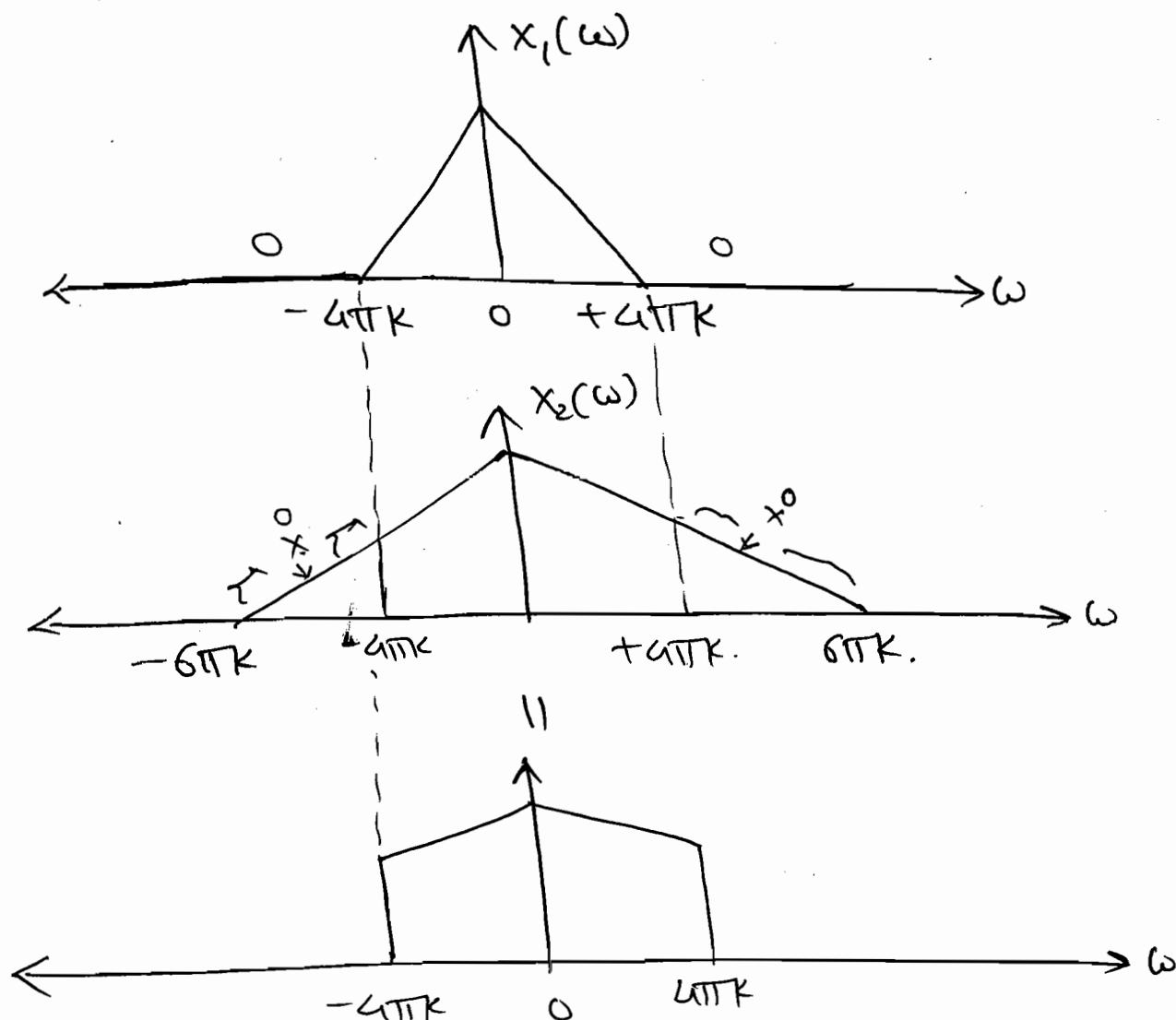
$$f_s' = 2 f_m = 10 \text{ KHz.}$$

(e) $x_1(t) * x_2(t)$.

Soln:

Conv. $\xleftrightarrow{\text{F.T.}}$ Mult.

$\Rightarrow x_1(t) * x_2(t) \xleftrightarrow{\text{F.T.}} X_1(\omega) \cdot X_2(\omega)$.



$\Rightarrow$ After Multiplication of two signals $X_1(\omega)$ & $X_2(\omega)$ new highest freq. is $4\pi K$ rad/sec.

So, N.R. $\Rightarrow \omega_0' = 2\omega_m' = 2(4\pi K) = 8\pi K$ rad/sec.

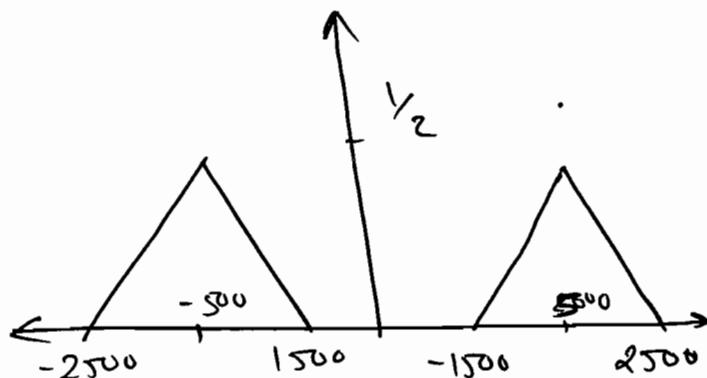
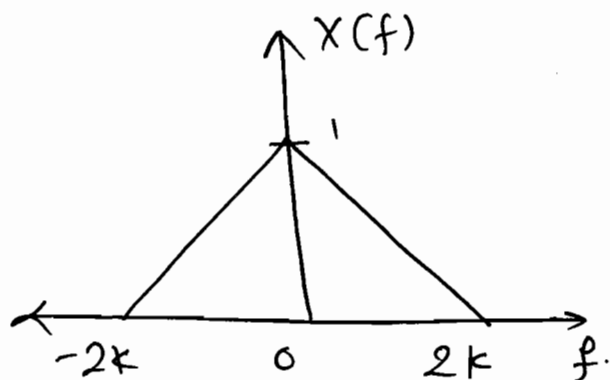
$$f_s' = 2 f_m = 8 \text{ KHz.}$$

(f) $X_1(t) \cdot \cos(1000\pi t) \rightarrow f_0 = 500 \text{ Hz}$.

Soln:

$= X_1(t) \cdot \cos(1000\pi t)$.

$\xleftrightarrow{\text{F.T.}} \frac{X_1(f - f_0) + X_1(f + f_0)}{2}$



$\Rightarrow$ $f_m' = 2500 \text{ Hz}$.

N.R. $2f_m = f_s = 5000 \text{ Hz}$.

$\therefore f_s = 5 \text{ kHz}$.

Note:-

$x_1(t) \leftrightarrow X_1(\omega) \rightarrow \omega_{m1}$

$x_2(t) \leftrightarrow X_2(\omega) \rightarrow \omega_{m2}$

① $x_1(t) \pm x_2(t) \xleftrightarrow{\text{F.T.}} X_1(\omega) \pm X_2(\omega)$

② $x_1(t) \cdot x_2(t) \leftrightarrow X_1(\omega) * X_2(\omega)$

③ $x_1(t) * x_2(t) \leftrightarrow X_1(\omega) \cdot X_2(\omega)$

B.W.

ω_{m1}

ω_{m2}

New B.W.

$\text{Max}(\omega_{m1}, \omega_{m2})$

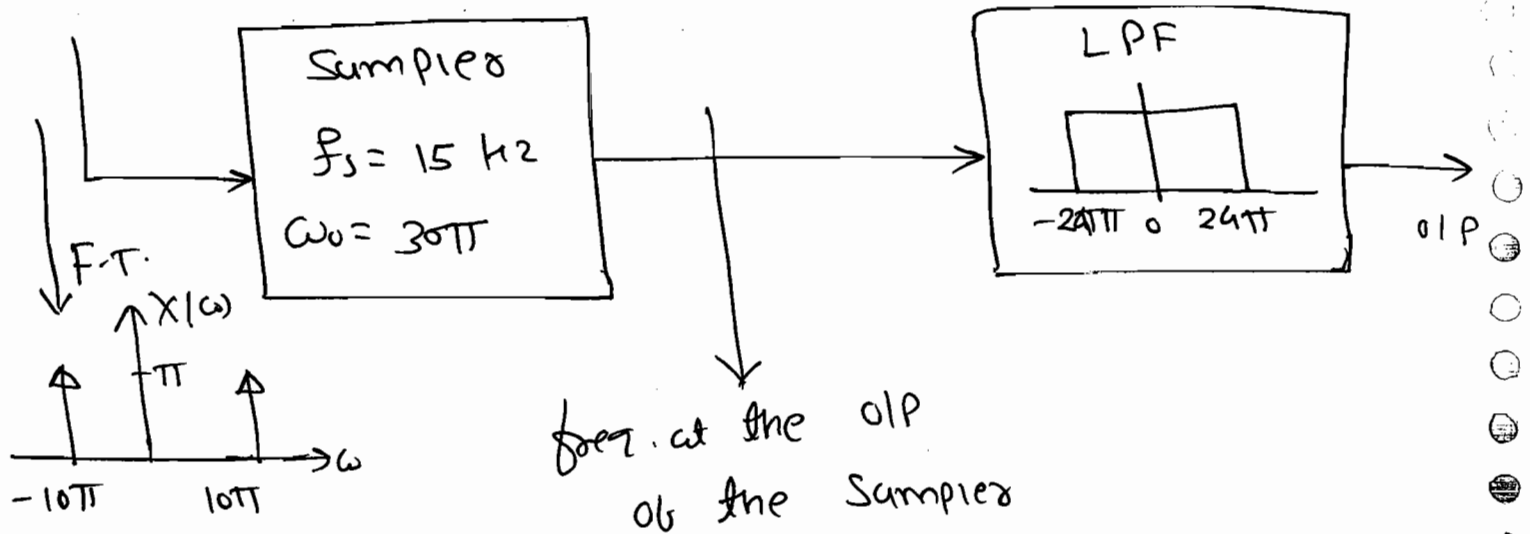
$(\omega_{m1} + \omega_{m2})$

$\text{Min}(\omega_{m1}, \omega_{m2})$

Q A signal $x(t) = \cos(10\pi t)$ is a sampled at 15 kHz and is passed through an ideal L.P.F with cut off freq 12 kHz. What freq. will appear at the o/p of the filter?

Soln:

$$x(t) = \cos(10\pi t)$$



$$(\omega - n\omega_0) \quad n \rightarrow -\infty \text{ to } +\infty$$

$$(\omega_m - n\omega_0) \Rightarrow (f_m - nf_s)$$

$$\Rightarrow \text{here. } \omega_m = 10\pi$$

$$\omega_0 = 30\pi$$

$$\text{let, } n=0 \Rightarrow \omega = \pm 10\pi \quad \text{L.P.F}$$

$$n=1 \Rightarrow \omega = \omega_m - \omega_0$$

$$\begin{matrix} \text{L.P.F} \\ \text{O/P} \end{matrix} \quad \begin{matrix} -20\pi & -40\pi \end{matrix} \quad \begin{matrix} \text{O/P} \\ 20\pi \end{matrix}$$

$$n=-1 \Rightarrow \omega = \omega_m + \omega_0 \quad \begin{matrix} 40\pi \end{matrix}$$

$$n=2 \Rightarrow \omega = \omega_m - 2\omega_0 \quad \begin{matrix} -50\pi \\ -70\pi \end{matrix}$$

So, freq. at LPF i.e. at O/P $\Rightarrow \pm 100\pi, \pm 200\pi$.

P4.6.4. A signal represented by $x(t) = 5 \cos(400\pi t)$ is sampled at a rate of 300 Hz. The resulting samples are passed through an ideal LPF with cut-off freq. of 150 Hz. Which of the following will be contained in the O/P of LPF?

(a) 100 Hz (b) 100 Hz, 150 Hz

(c) 50 Hz, 100 Hz (d) 20, 100, 150 Hz.

Solⁿ: $\omega_m = 400\pi \Rightarrow f_m = \pm 200 \text{ Hz}$.

$f_s = 300 \text{ Hz}$.

$\Rightarrow$ Freq. at O/P of the sampler is,
 $f = f_m - n f_s, \quad n \rightarrow -\infty \text{ to } +\infty$.

$n=0, \quad f = f_m = \pm 200 \text{ Hz}$.

$n=1, \quad f = f_m - f_s = 100 \text{ Hz}, -500 \text{ Hz}$.

$n=-1, \quad f = f_m + f_s = 500 \text{ Hz}, 100 \text{ Hz}$.

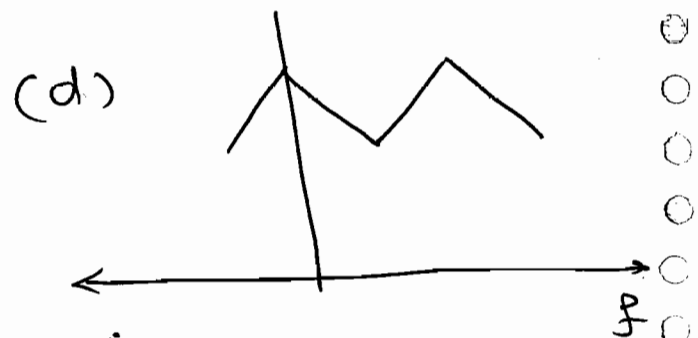
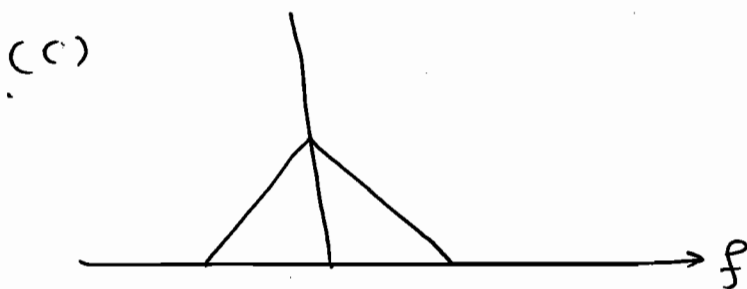
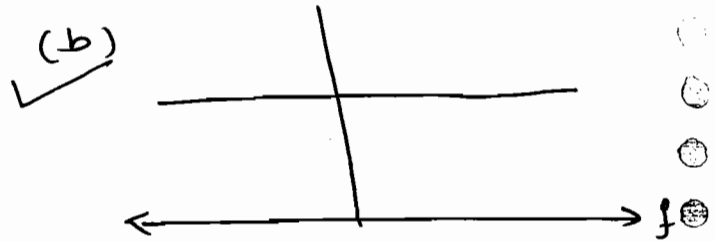
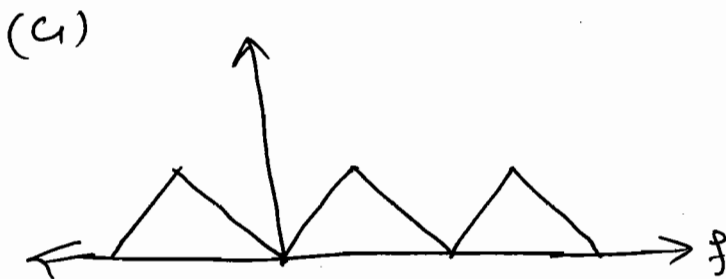
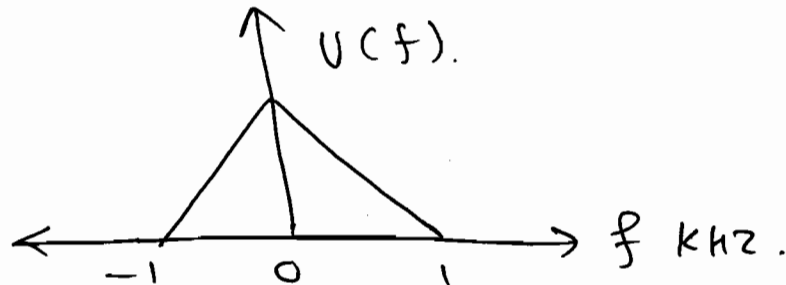
$n=2, \quad f = f_m - 2f_s = 800 \text{ Hz}, -400 \text{ Hz}$.

$\Rightarrow$ Cut-off freq. of LPF is 150 Hz.

So, O/P freq. at LPF is in betⁿ -150 to 150.

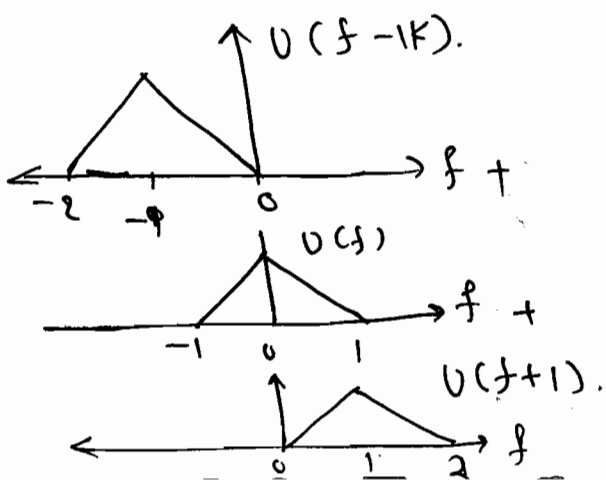
i.e. $\pm 100 \text{ Hz}$ So, ans - **(a) 100 Hz.**

P4.6.5 The freq. Spectrum of a signal is shown in figure it this signal is ideally sampled at intervals of 1 msec, then the freq. Spectrum of the sampled signal will be

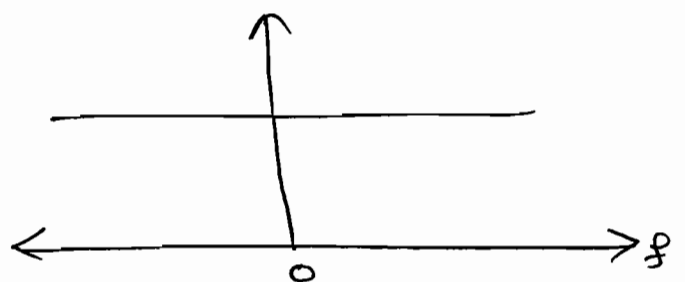


Soln: $f_m = 1 \text{ kHz}$
 $f_s = 1 \text{ msec}$

$\therefore f_s < 2 f_m$ So, under sampling.

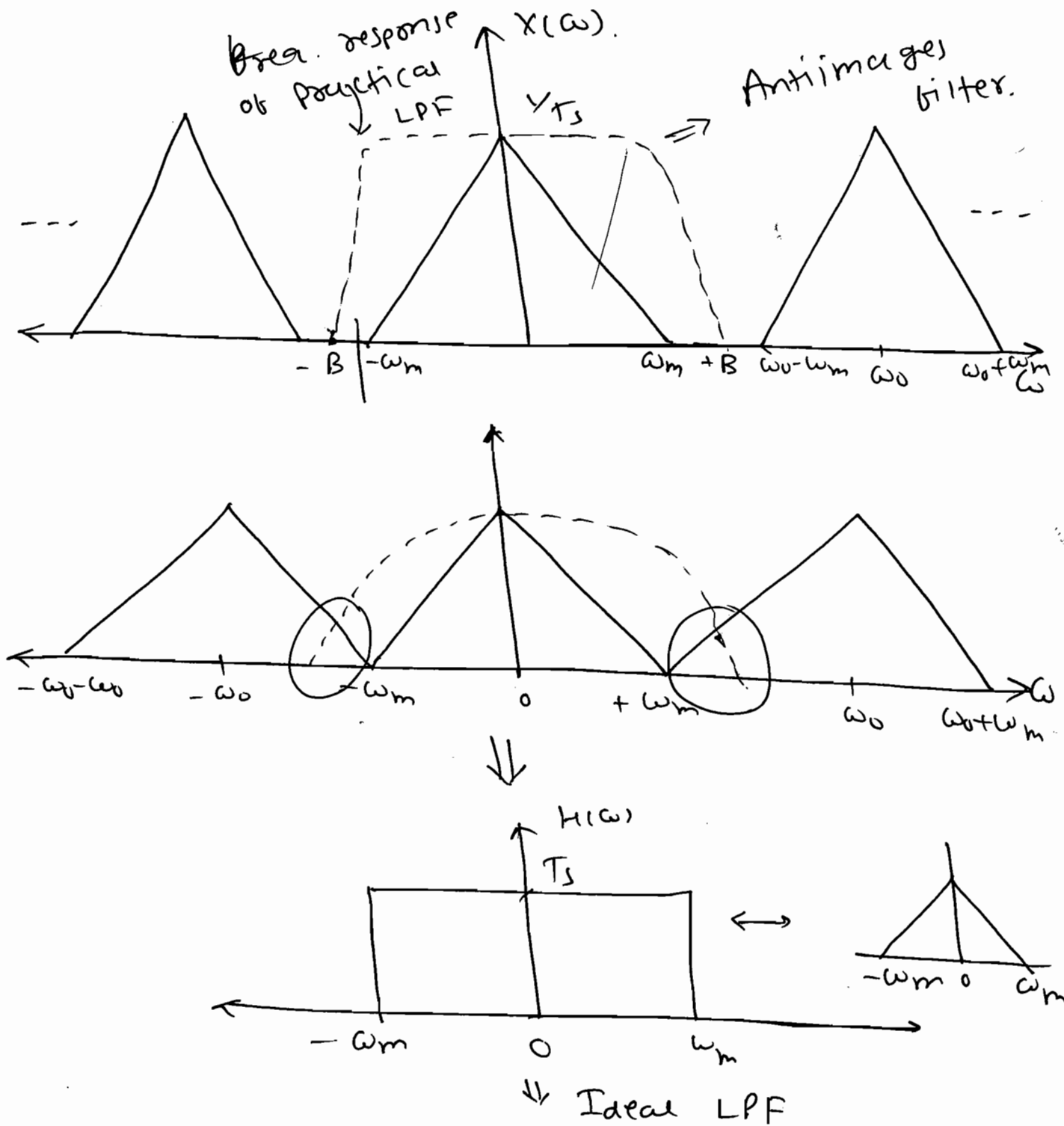


$\Rightarrow$



* Signal Reconstruction:-

⇒ The process of recovering original Continuous Spectrum from the Sampled Spectrum is signal reconstruction.



⇒

$$\omega_m < B < \omega_0 - \omega_m \quad \checkmark$$

P 4.6.7 A signal $x(t) = 6 \cos 10\pi t$ is sampled at a rate of 14 kHz to recover the original signal, cut-off freq. of the LPF should be _____.

- (a) $5 < f_c < 9$ (b) 9 (c) 10 (d) 14.

Solⁿ: $\omega_m = 10\pi \Rightarrow f_m = 5 \text{ kHz}, f_s = 14 \text{ kHz}$

$\therefore f_m < B < f_s - f_m$

$\therefore 5 < B < 14 - 5$

$\Rightarrow 5 < B < 9$

P 4.6.6 A signal with 2 freq. components at 6 kHz and 12 kHz is sampled at the rate of 16 kHz and then passed through a LPF having a cut-off freq. of 16 kHz. The output signal of the filter is _____.

(a) is an undistorted version of original signal.

(b) contains 6 kHz & spurious components of 4 kHz.

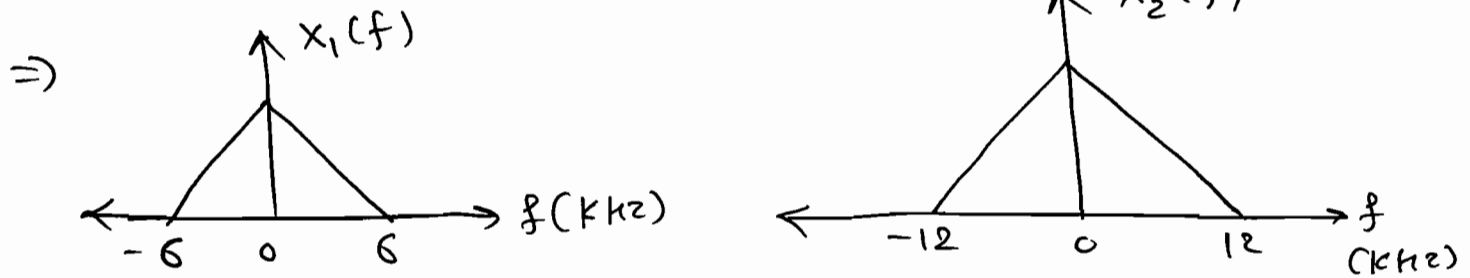
(c) contains only 6 kHz components.

(d) contains both components of original signal and 2 spurious components of

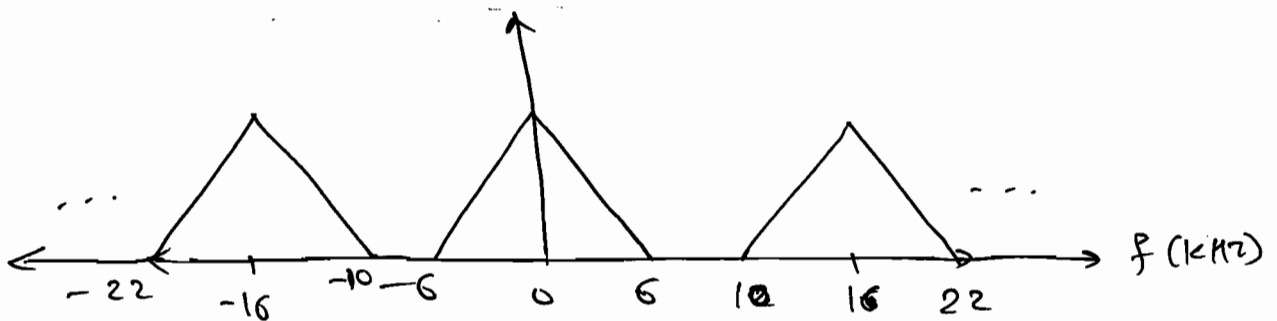
of 4 kHz & 10 kHz.

$\Rightarrow$ $f_{m1} = 6 \text{ kHz}, \quad f_{m2} = 12 \text{ kHz}.$

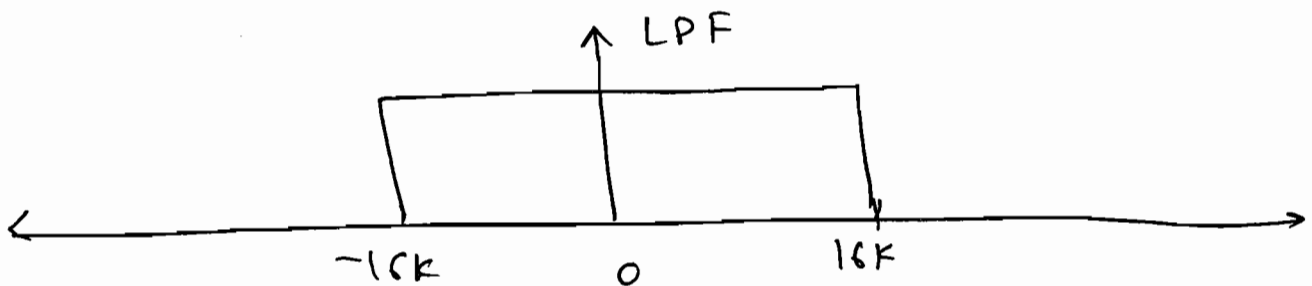
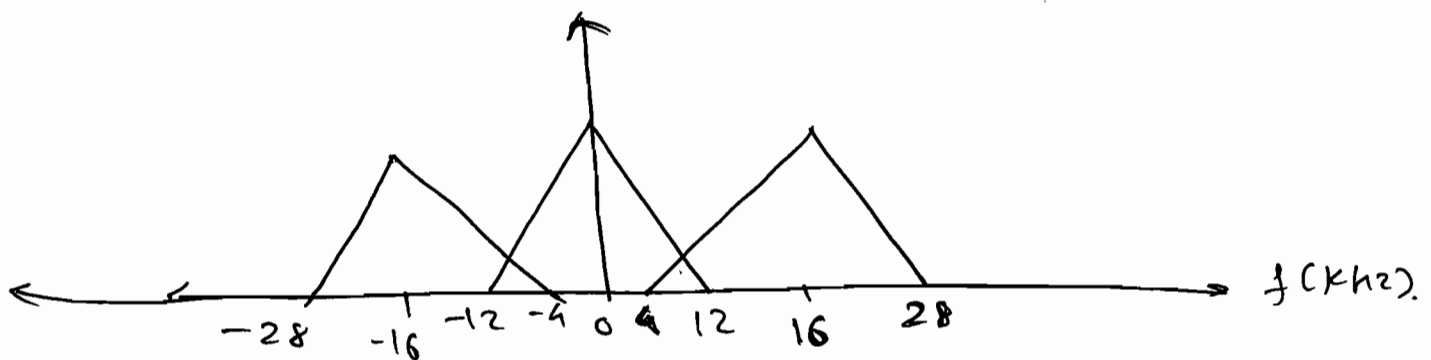
$f_s = 16 \text{ kHz}.$



① $(f_s = 16 \text{ K}) > (2 f_{m1} = 12 \text{ kHz}) \Rightarrow$ over sampling

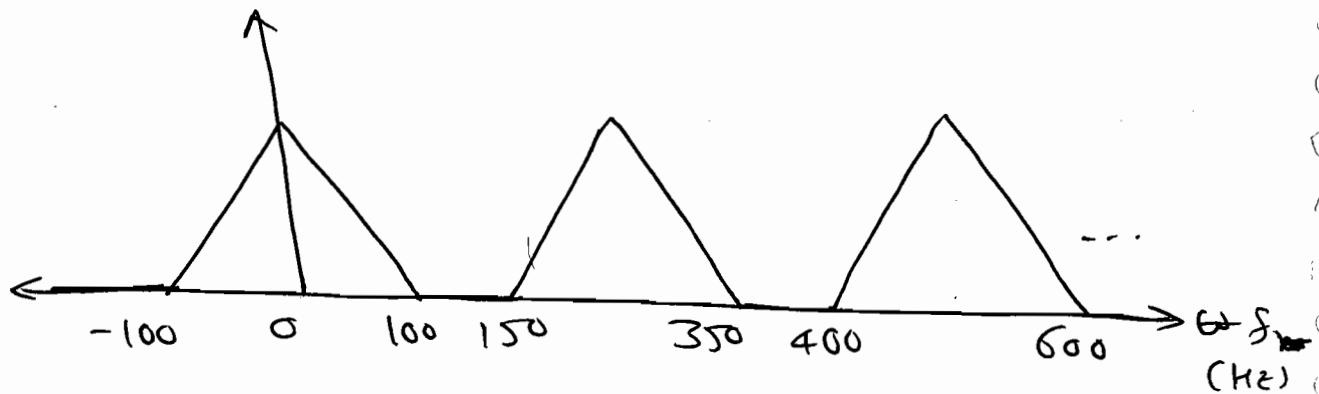


② $(f_s = 16 \text{ K}) < (2 f_{m2} = 24 \text{ kHz}) \Rightarrow$ under sampling



$\Rightarrow$ Ans-(b) contains 6 kHz & spurious components of 4 kHz.

P 4.6.8 The Spectrum of a bandlimited signal after sampling is shown in figure. The value of sampling interval is _____.



Soln: $f_m = 100 \text{ kHz}$.

$\therefore f_s - f_m = 150 \text{ kHz}$.

$\therefore f_s = 150 + 100 = 250 \text{ kHz}$.

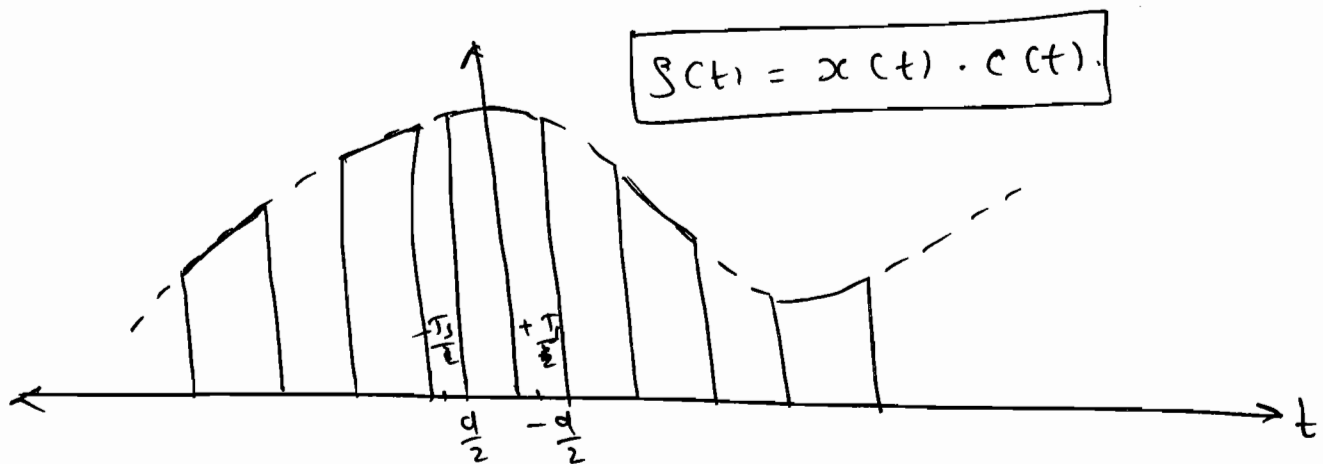
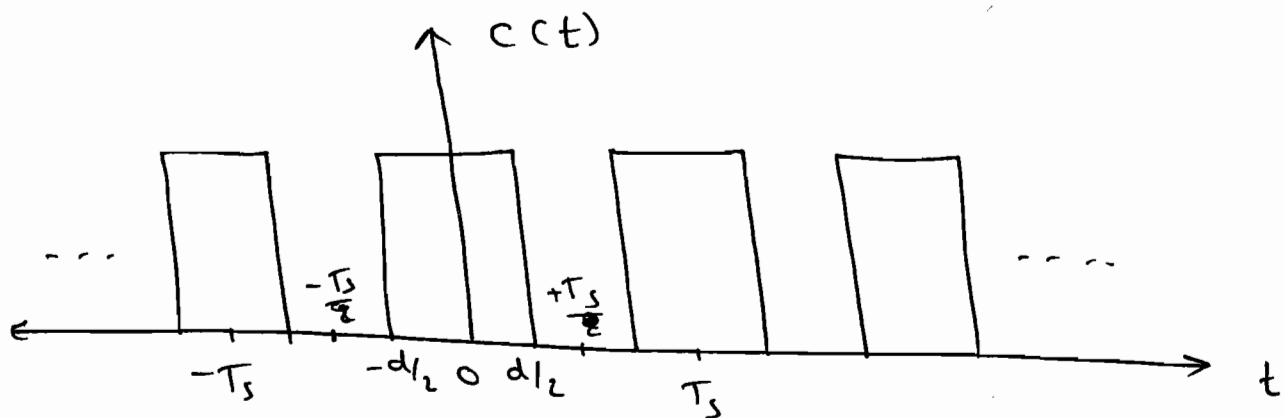
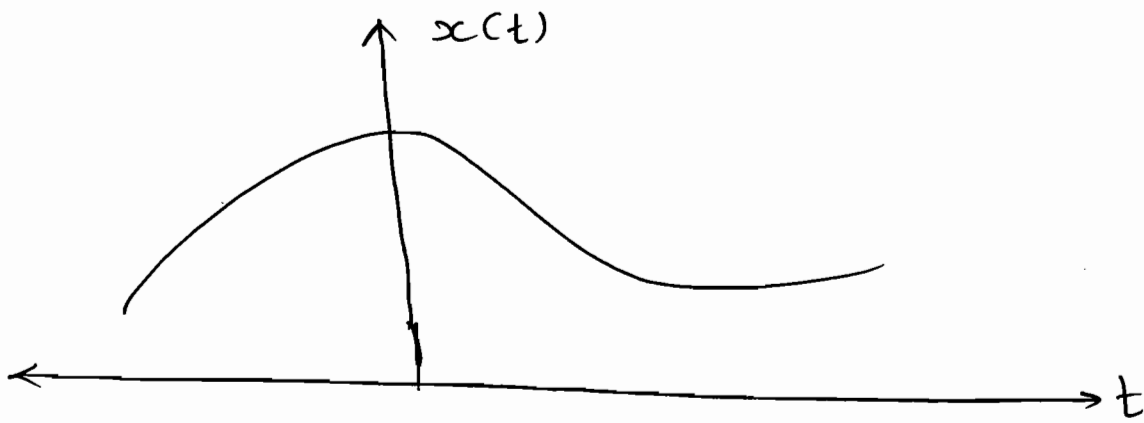
$\therefore f_s = 250 \text{ kHz}$.

$\Rightarrow \text{S.I. } T_s = \frac{1}{f_s} = \frac{1}{250} = 4 \text{ m sec.}$

$T_s = 4 \text{ msec}$

Note: The freq. at the o/p of Sampler is $\omega - n\omega_0$ in ideal sampling. We can take the value of n from $-\infty$ to $+\infty$, but in natural sampling n value is decided by C_n .

* ② Natural Sampling:



$$s(t) = x(t) \sum_{n=-\infty}^{+\infty} c_n e^{jn\omega_0 t}$$

↓ F.T.

$$S(\omega) = \sum_{n=-\infty}^{\infty} C_n X(\omega - n\omega_0).$$

$$C_n = \frac{1}{T} \int_{-d/2}^{d/2} c(t) e^{-jn\omega_0 t} dt$$

$$\Rightarrow T = T_s$$

$$\therefore \frac{C_n}{T_s} = \frac{1}{2T_s} \times \left[\frac{e^{-jn\omega_0 t}}{-jn\omega_0} \right]_{-d/2}^{+d/2}$$

$$= \frac{1}{T_s} \times \left[\frac{e^{-jn\omega_0 \frac{d}{2}} - e^{jn\omega_0 \frac{d}{2}}}{-jn\omega_0} \right]$$

$$\frac{C_n}{T_s} = \frac{\sin\left(\frac{n\omega_0 d}{2}\right)}{n\omega_0 T_s}$$

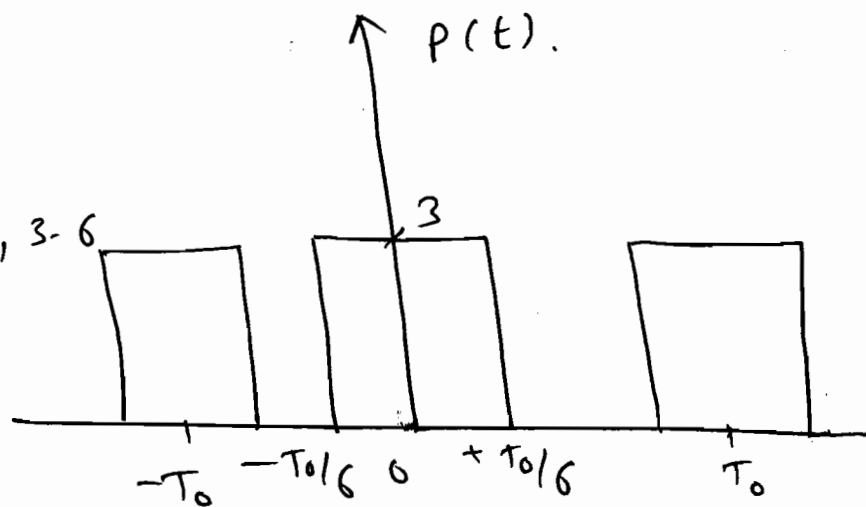
P 4.6.9 Let $x(t) = 2\cos(800\pi t) + \cos(1400\pi t)$ and $x(t)$ is sampled with the rectangular pulse train as shown in fig. The only spectral components (in kHz) in the sampled signal in the freq. range 2.5 kHz to 3.5 kHz.

(a) 2.7, 3.4

(b) 3.3, 3.8

(c) 2.6, 2.7, 3.3, 3.4, 3.6

(d) 2.7, 3.3



Soln:

$$C_n = \frac{1}{T_0} \int_{-T_0/6}^{T_0/6} (3) \cdot e^{-jn\omega_0 t} \cdot dt$$

$$\omega_0 = \frac{2\pi}{T_0}$$

$$\omega_0 = 2\pi \text{ kHz}$$

$$f_s = \frac{1}{T_0} \text{ kHz}$$

$$C_n = \frac{\sin\left(\frac{n\omega_s d}{2}\right)}{n\omega_s T_s}$$

$$= \frac{\sin\left(\frac{n \times \frac{2\pi}{2 \times 10^{-3}} \times \frac{10^{-3}}{6}\right)}{n \times \frac{2\pi}{2 \times 10^{-3}} \times T_s}$$

$$C_n = \frac{\sin\left(\frac{2\pi}{3}\right)}{n\pi}$$

$$C_n = 0 \text{ for } n = 3, 6, 9, \dots$$

$$C_n \neq 0 \text{ for } n = 0, 1, 2, 4, 5, \dots$$

$\Rightarrow$ freq. at the output of natural sampler.

$$\left. \begin{array}{l} f_{m1} \pm n f_s \\ f_{m2} \pm n f_s \end{array} \right\} n = 0, 1, 2, 4, 5, 7, 8, \dots$$

$$\Rightarrow n=0 \Rightarrow \begin{array}{l} f_{m1} = f = 0.4 \text{ K} \\ f_{m2} = f = 0.7 \text{ K} \end{array}$$

$$\Rightarrow n=1 \Rightarrow \begin{array}{l} f_1 = f_{m1} \pm f_s = 0.4 + 1\text{K} = 1.4 \text{ KHz} \\ f_2 = f_{m2} \pm f_s = 0.7 + 1\text{K} = 1.7 \text{ KHz} \end{array}$$

$$\Rightarrow n=2 \Rightarrow \begin{array}{l} f_1 = f_{m1} \pm 2f_s = 0.4 + 2\text{K} = 2.4 \text{ KHz} \\ f_2 = f_{m2} \pm 2f_s = 0.7 + 2\text{K} = 2.7 \text{ KHz} \end{array}$$

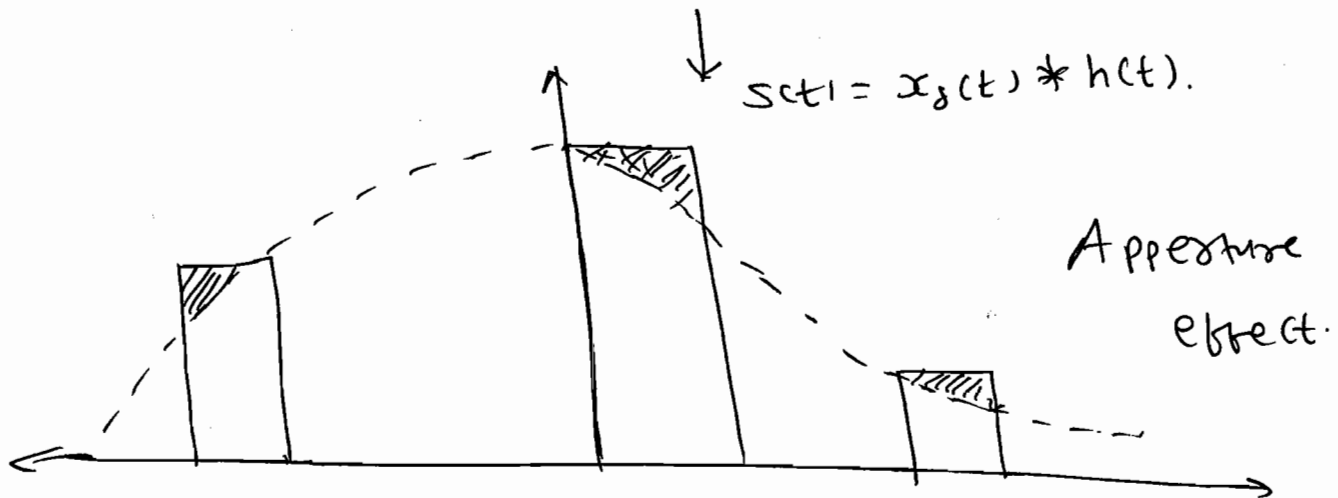
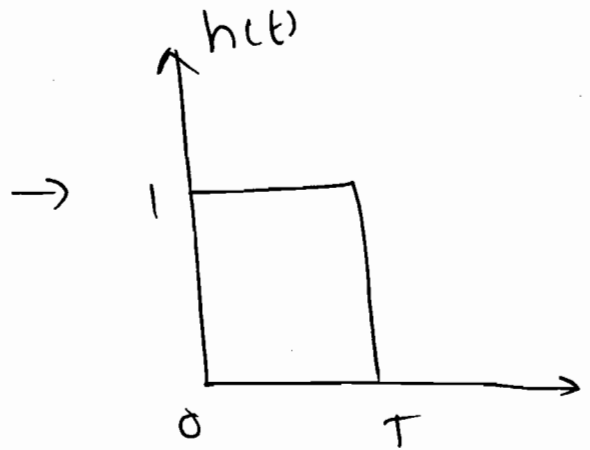
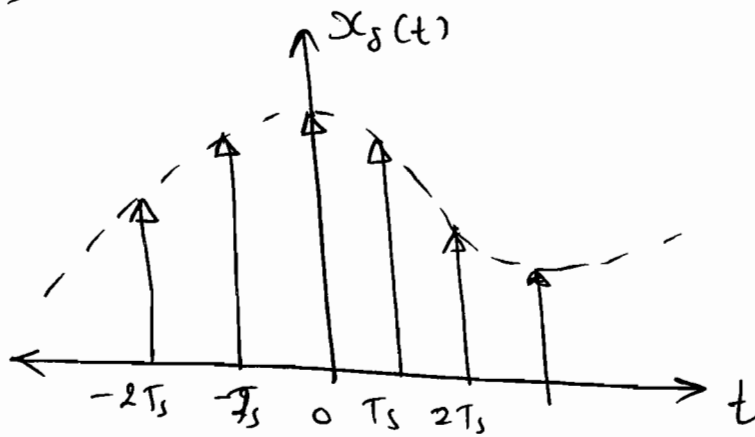
$$\Rightarrow n=4 \Rightarrow \begin{array}{l} f_1 = f_{m1} \pm 4f_s = 0.4 + 4\text{K} = 3.6 \text{ K} \\ f_2 = f_{m2} \pm 4f_s = 0.7 + 4\text{K} = 3.3 \text{ K} \end{array}$$

$$\Rightarrow n=1 \Rightarrow \begin{array}{l} f_1 = f_{m1} - f_s = 2.4 \\ f_2 = f_{m2} - f_s = 3.3 \end{array}$$

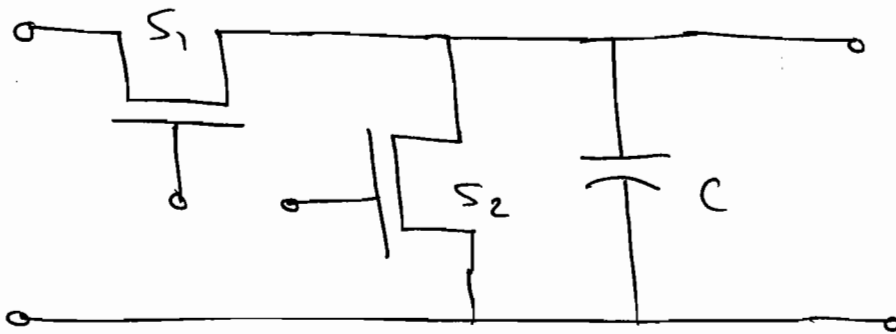
So, Ans: (d) 2.7, 3.3.

③ Flat - Top Sampling:

⇒



⇒

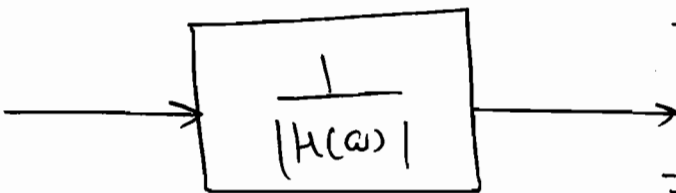


Sample and hold ckt.

⇒ because of maintaining constant amplitude level we introduce amplitude distortion of $T \text{sinc} \left(\frac{\omega T}{2\pi} \right)$ & phase delay of $-\frac{\omega T}{2}$, which is known as Aperture effect.

$\Rightarrow$ To Cancel this, Flat-Top Sampled sig. is applied to an equalizer $\frac{1}{|h(\omega)|}$.

$\Rightarrow$



$$S(\omega) = X_s(\omega) \cdot H(\omega)$$

$$= \frac{1}{T_s} \sum_{n=-\infty}^{+\infty} X(\omega - n\omega_0) \cdot H(\omega).$$

Equalizer $H(\omega) = T \text{sinc}\left(\frac{\omega T}{2\pi}\right) \cdot e^{-j\omega(T/2)}.$

