## TEST

## **OPERATING SYSTEM**

*Directions for questions 1 to 30:* Select the correct alternative from the given choices.

- 1. A program is \_\_\_\_\_ entity, while a process is \_\_\_\_\_ entity.
  - (A) Active, passive
  - (B) Active, sometimes active
  - (C) Passive, active
  - (D) Both (B) and (C)
- **2.** All the information associated with a specific process is contained in:
  - (A) Process control block
  - (B) Program control block
  - (C) TLB
  - (D) Heap
- Kernel-level threads and user-level threads are supported, respectively, by \_\_\_\_\_.
  - (A) Operating system and operating system
  - (B) Operating system and user
  - (C) User and user
  - (D) None of these
- **4.** Which of the following is false about user-level threads?
  - (A) User-level threads are visible to the programmer and are unknown to the Kernel.
  - (B) These are faster to create.
  - (C) Kernel never interferes.
  - (D) There is no effect of a system call () on process.
- **5.** Which of the following interprocess communication models are implemented using system calls?
  - (A) Shared memory
  - (B) Message passing
  - (C) Both (A) and (B)
  - (D) Neither (A) nor (B)
- 6. Peterson's solution
  - (i) is restricted to two processes
  - (ii) share two data items turn and flag [i]
  - (iii) mutual exclusion is achieved
  - (iv) is a hardware solution

Which of the above are true?

- (A) (i), (ii), (iii)
- (B) (ii), (iii), (iv)
- (C) (iv), (i), (ii)
- (D) (i), (ii), (iii), (iv)
- 7. Which of the following requires a mode switch from one thread to another?
  - (A) One process multiple thread
  - (B) User-level thread
  - (C) Kernel-level threads
  - (D) Both (B) and (C)

- 8. When a process is created, its state is
  - (A) New
  - (B) Ready
  - (C) Block
  - (D) Suspend
- 9. The data section of a process in memory contains
  - (A) Local variables, function parameters
  - (B) Return addresses
  - (C) Global variables
  - (D) None of the above
- 10. Which one of the following is true about process states?
  - (i) A process which is running must have terminated as next state.
  - (ii) From running state process can go to either waiting, ready or terminated state.
  - (iii) Only one process can run at any instant.
  - (iv) Ready process can go to waiting state.
  - (A) (i), (ii), (iii)
  - (B) (ii) and (iii) only
  - (C) (i) and (iv) only
  - (D) (ii), (iii), (iv)
- **11.** Message passing model of inter process communication can be
  - (A) Blocking only
  - (B) Blocking and non-blocking
  - (C) Synchronous and asynchronous
  - (D) Both (B) and (C)
- **12.** The definition of wait() is as follows:
  - wait (S) {
    while (S <=0);</pre>
  - S - ;
  - }

The semicolon after while statement, signifies

- (A) Infinite looping
- (B) Blank statement
- (C) Depends on interpretation of compiler
- (D) No operation
- **13.** To avoid race condition, the number of processes using the critical sections is/are:
  - (A) 1 (B) 2
  - (C) 3 (D) More than 3
- 14. The 'Critical Section' is the region in which
  - (A) Any number of processes can enter without any permission
  - (B) Only one process enters at a time and others wait for it.
  - (C) Section is very critical
  - (D) None of these

## Time: 60 min.

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- 15. What does process control block contain?
  - (A) Process Identification
  - (B) Process state information
  - (C) Process control information
  - (D) All of the above
- **16.** Match the following

(i)	Multiprogramming	(x)	Managing multiple pro- cesses executing on multiple computers
(ii)	Multiprocessing	(y)	Management of multiple pro- cesses within a uniprocessor system.
(iii)	Distributed process Management	(z)	Management of multi- ple processes within a multiprocessor.

- (A) (i) -y (ii) -z (iii) -x
- (B) (i) -z (ii) -x (iii) -y
- (C) (i) -y (ii) -x (iii) -z
- (D) Ambiguous
- **17.** For '*n*' number of fork() system call, how many parent and child processes will be created?
  - (A) 1,  $2^n 1$ , respectively
  - (B)  $1, 2^n$ , respectively
  - (C)  $2^n 1$ , 1, respectively
  - (D) n, 2n, respectively
- 18. If the value of binary semaphore is initialized with 1 and three wait() operations are performed, how many processes are there in the block list?(A) 1 (B) 0

(A) I	(Б) О
(C) 3	(D) 2

19. A counting semaphore is initialized with the value 3. A list of 'P' and 'V' operations are performed on the semaphore as: 1P, 2V, 2P, 3V, 5P, 7V, 2P, 3V. The final value of semaphore is?

		1	
(A)	5		(B) 8
(C)	7		(D) 6

**20.** The final value of semaphore after 10 '*P*' operations and 23 '*V*' operations is 1. What will be the initial value of this counting semaphore?

(A) –14		(B) –13
(C) -12		(D) –11

- **21.** For a machine-instruction approach to enforce mutual exclusion, following are its properties:
  - (i) starvation and deadlock free
  - (ii) it is applicable to any number of processes.
  - (iii) it can be used to support multiple critical sections, each defined by its own variable.
  - (iv) it is simple, easy to verify and employed with busy waiting

Which of the above is false?

(A) (iv) only (B) (ii), (ii)	(11) Only
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(C) (i), (ii) only (D) (i) only (D)

**22.** Consider the following code:

```
if (fork() == 0)
{
    a = a + 5;
    printf("%d,%d\n",a,&a);
    else
    {
        a = a - 5;
    printf("%d,%d\n",a,&a);
    }
```

Let p, q be the values printed by the parent process, and s, t be the values printed by the child process. Which one of the following is true?

(A) p = s + 10 and q = t(B) p = s + 10 and  $q \uparrow t$ (C) p + 10 = s and q = t

- (D) p + 10 = s and  $q \uparrow t$
- **23.** Consider the following statements with respect to user-level threads:
  - (i) Context switch is faster with kernel-supported threads.
  - (ii) For user-level threads, a system call can block the entire process.
  - (iii) Kernel-supported threads can be scheduled independently.
  - (iv) User-level threads are transparent to the Kernel.
  - Which of the above statements are true?
  - (A) (i), (iii) and (iv) only
  - (B) (ii) and (iii) only
  - (C) (i) and (iii) only
  - (D) (i) and (ii) only
- 24. Suppose there are 'n' CPUs and 'm' processes such that m > n. What will be the minimum and maximum number of ready, running and blocked process, respectively?
  (A) 0, 0, 0 and m, n, m
  (B) 1, m, 1 and n, n, n
  (C) m, 1, 0 and m, m, n
  (D) 0, 0, 0 and n, m, m
- **25.** Consider the following signal semaphore code signal (semaphore \*s)

Choose the suitable options for (I) and (II), respectively

- (A) S.value = 0 and wakeup(P);
- (B) S.value <= 0 and wakeup(P);
- (C) S.value <0 and block( );
- (D) S.value <= 0 and block();

**26.** Consider the methods used by processes  $P_1$  and  $P_2$  for accessing their critical sections whenever needed. The initial values of shared Boolean variables  $S_1$  and  $S_2$  are randomly assigned.

Method used by  $P_1$ 

While  $(S_1 = = S_2)$ ; Critical section  $S_1 = S_2$ ;

Method used by  $P_2$ 

While  $(S_1 != S_2)$ ; Critical section  $S_2 = !(S_1)$ ;

Which of the following statements describes the properties achieved?

- (A) Mutual exclusion but not progress
- (B) Progress only
- (C) Bounded waiting, progress
- (D) Mutual exclusion, progress, bounded waiting
- 27. Consider the following statements regarding spin locks:
  - (i) No context switch is required when a process wait on a lock
  - (ii) Spin locks are useful when locks are expected to be held for short times.
  - (iii) They are often employed on multiprocessor systems
  - (iv) Process 'spins' while waiting for a lock
  - Choose the correct option:
  - (A) (i), (ii), (iii), (iv) are true
  - (B) Only (i) and (ii) are true
  - (C) (iii) is false
  - (D) (ii) is true and (iv) is false

**Common data for questions 28, 29 and 30:** From the Readers-Writers problem, the data structure for reader process is:

semaphore mutex, wrt; int readcount;

```
while(1)
{
  wait(mutex);
  readcount++;
  if(readcount == 1)
  wait(wrt);
  signal(mutex);
  - - - - -
  wait(mutex);
  readcount - -;
  if(readcount ==0)
  signal(wrt); signal(mutex);
}
```

mutex and wrt are initialized to 1 and readcount is initialized to 0.

- 28. Mutual exclusion for readers is attained by
  - (A) Wrt
  - (B) Mutex
  - (C) Readcount
  - (D) Both (A) and (B) (
- **29.** Which of the following semaphore or semaphores is used by the first or last reader that enters or exits the critical section?
  - (A) Wrt
  - (B) Mutex
  - (C) Readcount
  - (D) Both (A) and (B)
- **30.** The readcount variable keeps track of how many processes are \_\_\_\_\_.
  - (A) Currently reading the object
  - (B) Currently writing the object
  - (C) Waiting in the queue
  - (D) Reading the shared data

Answer Keys									
11. D	12. D	<b>13.</b> A	14. B	15. D	<b>16.</b> A	7. C 17. A 27. A	18. D	<b>19.</b> B	<b>20.</b> C