

METAL

CUTTING

- HSS → 30 m/min
Carbides → 150 m/min
Ceramics → 600 m/min
- Orthogonal cutting
 - Cutting edge of tool \perp to dirⁿ of velocity
 - Cutting edge wider than width of w/p.
 - width of w/p is much greater than depth of cut
 - chip flow \perp to cutting edge
 - cutting forces are along 2 dirⁿ only.
- During any metal cutting, increase in cutting speed does not change cutting forces.
- Tool signature (ASA)

$$\alpha_b - \alpha_s - r_e - r_s - c_e - c_s - R$$

→ rake - relief - cutting
→ side will come last.

- Orthogonal rake system (ORS)

$$i - \alpha - r - r_i - c_e - \lambda - R$$

i = inclination angle = 0° for orthogonal cutting

α = orthogonal rake angle

$\lambda = 90 - c_s$ = principle cutting edge angle
or
Approach angle

R = nose radius (R)

- $i = 0^\circ$ for turning bcz plane of cut is at 90° to the principle cutting edge.
- $\lambda = 90^\circ$ for orthogonal turning
- Interconversion b/w ASN & ORS

$$\tan i = \sin d \cdot \tan \alpha_b - \cos d \cdot \tan \alpha_s$$

$$\tan \alpha = \sin d \cdot \tan \alpha_s + \cos d \cdot \tan \alpha_b$$

$$\tan \alpha_b = \sin d \cdot \tan i + \cos d \cdot \tan \alpha$$

$$\tan \alpha_s = \sin d \cdot \tan \alpha - \cos d \cdot \tan i$$

- Chip thickness ratio $\Rightarrow (\gamma)$

$$\gamma = \frac{t}{t_c} = \frac{d_c}{d} = \frac{V_c}{V} \quad \text{always less than 1.}$$

- Shear angle (ϕ)

$$\tan \phi = \frac{\gamma \cos \alpha}{1 - \gamma \sin \alpha}$$

t = uncut chip thickness
 t_c = chip thickness after cut

- Cutting shear strain (γ)

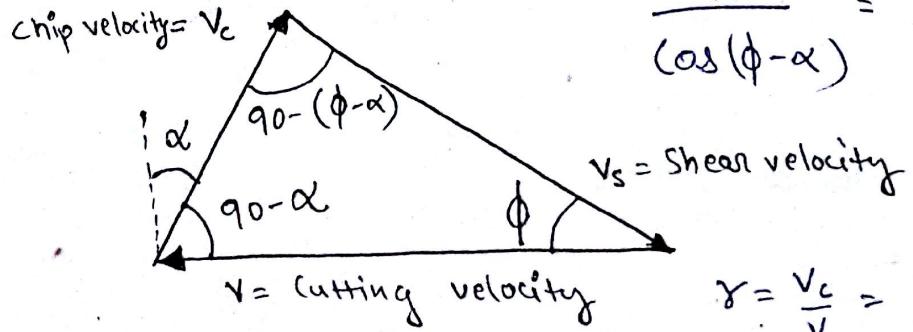
$$\gamma = \cot \phi + \tan(\phi - \alpha)$$

\Rightarrow irrespective of value of α , minimum γ occurs when $\gamma = 1$

\Rightarrow at $\alpha = 0$

$$\gamma = \cot \phi + \tan \phi \geq 2 \quad [\because x + \frac{1}{x} \geq 2]$$

- Velocity triangle



$$\frac{V}{\cos(\phi - \alpha)} = \frac{V_c}{\sin \phi} = \frac{V_s}{\cos \alpha}$$

$$\gamma = \frac{V_c}{V} = \frac{\sin \phi}{\cos(\phi - \alpha)} ; \quad \frac{V_s}{V} = \frac{\cos \alpha}{\cos(\phi - \alpha)}$$

- Shear strain rate ($\dot{\gamma}$)

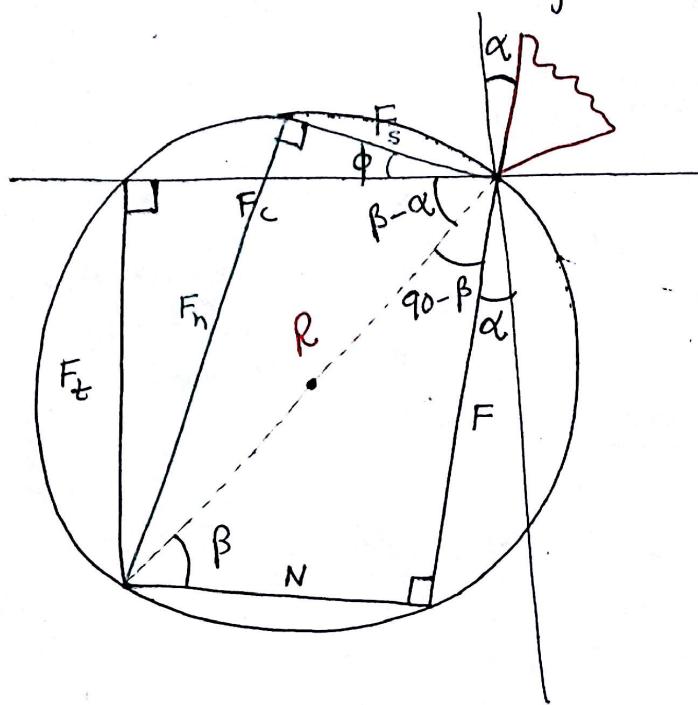
$$\dot{\gamma} = \frac{dx}{dt} = \frac{V_s}{\text{thickness of shear zone}} = \frac{V_s}{t_s}$$

CHAPTER-2 [Analysis of metal cutting]

- $F_s = T_s \times \frac{bt}{\sin \phi}$

$$F_n = T_s \times \frac{bt}{\sin \phi}$$

- merchant circle diagram for orthogonal cutting



$$\tan \beta = \frac{F}{N} = \mu$$

$$\beta = \tan^{-1}(\mu)$$

= friction angle

$$F = R \sin \beta$$

$$N = R \cos \beta$$

$$F_s = R \cos (\phi + \beta - \alpha)$$

$$F_n = R \sin (\phi + \beta - \alpha)$$

$$F_c = R \cos (\beta - \alpha)$$

$$F_t = R \sin (\beta - \alpha)$$

- merchant theory

$$\phi = 45^\circ + \frac{\alpha}{2} - \frac{\beta}{2}$$

[it is used to calculate ϕ only when $\tan \phi = \frac{\alpha \cos \alpha}{1 - \alpha \sin \alpha}$ is not having sufficient data]

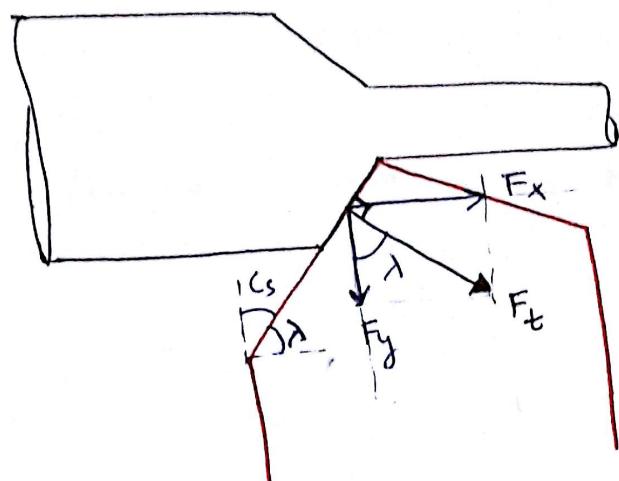
it give higher value of ϕ which means lower cutting forces, smaller shear plane, lower power, lower temp^r, i.e. easier m/cing.

- modified merchant theory

$$2\phi + \beta - \alpha = c$$

- Conversion of turning into orthogonal

F_t is in orthogonal plane



$$F_t = \frac{F_x}{\sin \alpha} = \frac{F_y}{\cos \alpha}$$

$$t = f \sin \alpha$$

$$b = \frac{d}{\sin \alpha}$$

Once F_t , t , b are calculated, rest calculation are same as orthogonal cutting.

- Power consumption

Total power = Shearing Power + frictional power

$$F_c \cdot V = F_s \cdot V_s + F \cdot V_c$$

65-70% 30-35%

- Specific energy consumption (e)

$$e = \frac{\text{Power (w)}}{\text{MRR (mm}^3/\text{s)}} = \frac{F_c \cdot \frac{V}{60}}{1000 f d \frac{V}{60}} = \frac{F_c}{1000 f d}$$

- Force relations

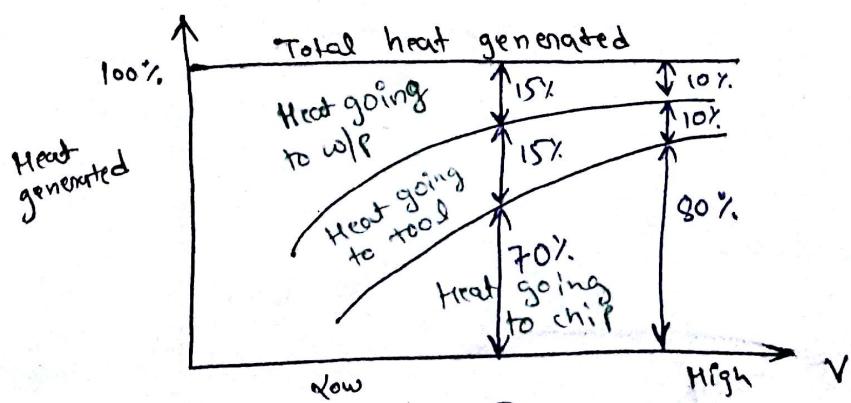
$$F = F_c \sin \alpha + F_t \cos \alpha$$

$$N = F_c \cos \alpha - F_t \sin \alpha$$

$$F_n = F_c \sin \phi + F_t \cos \phi$$

$$F_s = F_c \cos \phi - F_t \sin \phi$$

- Heat distribution in metal cutting



- In metal cutting

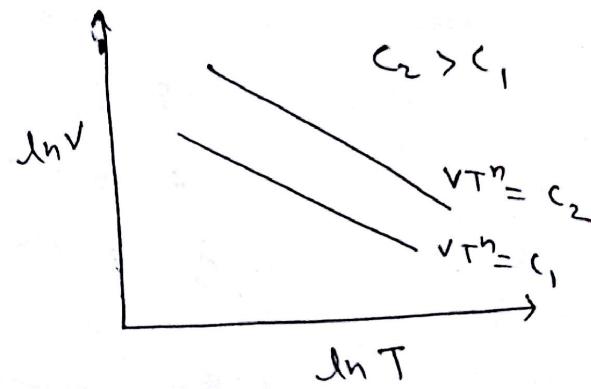
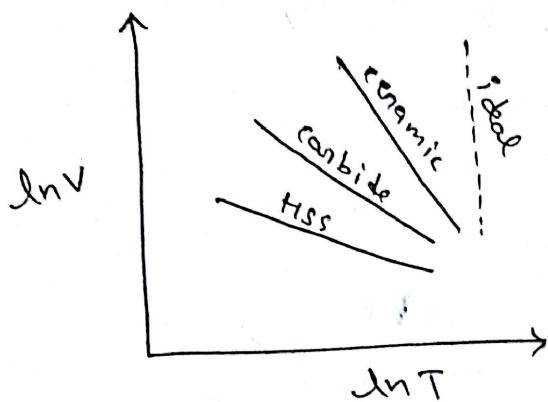
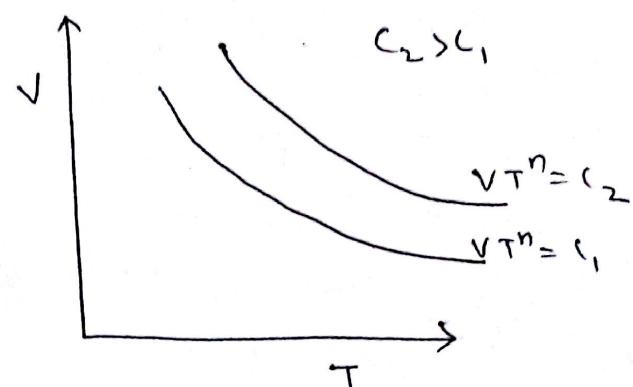
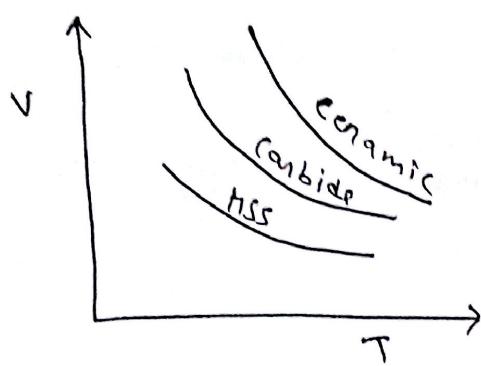
Heat \rightarrow calculated by calorimeter method

Temperature \rightarrow Tool-work thermo couple

Forces \rightarrow Dynamometer.

CHAPTER-3 [Tool life, Tool wear, tool economics]

- Tool life curves



- Crater wear starts at some distance from tool tip on rake face bcz temp is maximum at that region

- Taylor's tool life equation

$$VT^n = C$$

$V = \text{m/min}$

$T = \text{min}$

$n = \text{depends on tool material}$

$C = \text{based on cutting conditions}$

no	material
.08 - .2	HSS
.2 - .4	carbide
.5 - .7	ceramic

- Modified Taylor's equation

$$VT^n f^a d^b = C$$

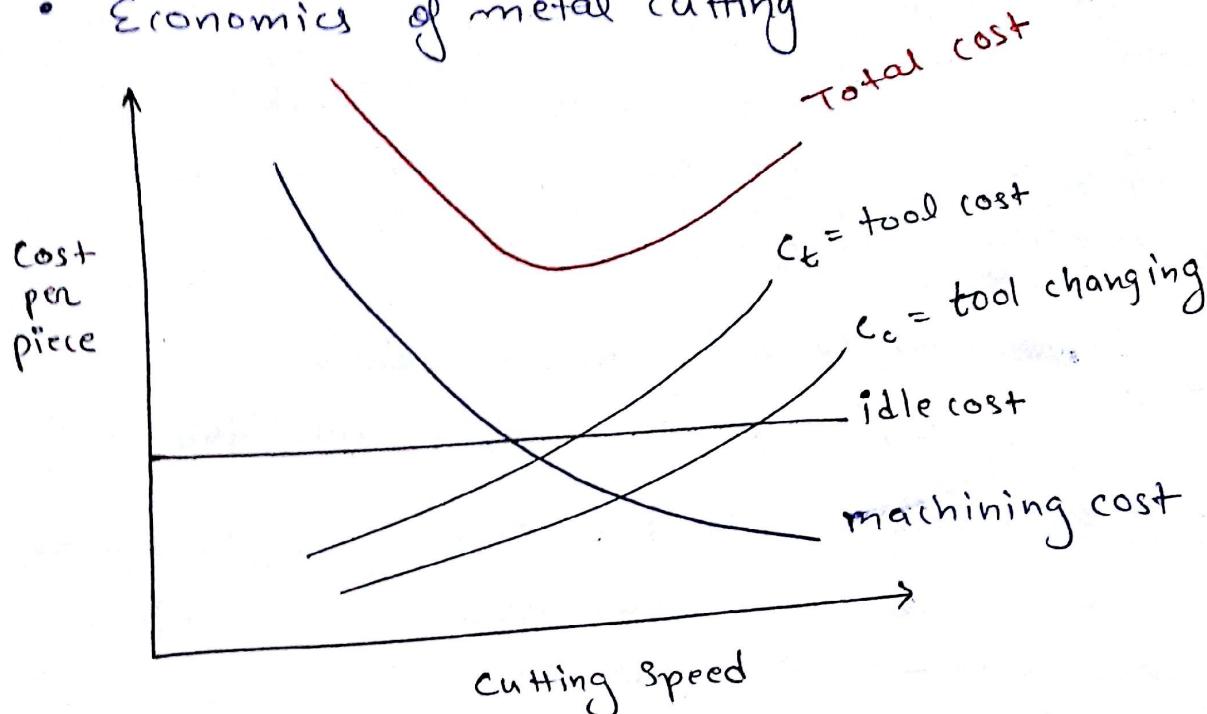
$$d = \text{mm}$$

$$f = \text{mm/rev}$$

\Rightarrow effect on tool life

$$v > f > d$$

- Economics of metal cutting



\Rightarrow Optimum tool life for minimum cost

$$T_o = \left(T_c + \frac{c_t}{c_m} \right) \left(\frac{1-n}{n} \right)$$

T_c = tool changing time (min)

c_t = tool regrinding cost
+
tool depreciation / replacement

c_m = machining cost
= labour + overhead

\Rightarrow Optimum tool life for maximum productivity

$$T_o = T_c \left(\frac{1-n}{n} \right)$$

- $v_{\max.}$ Production $>$ $v_{\max.}$ Profit $>$ $v_{\min.}$ cost

- Surface roughness [Turning]

Ideal surface ($R=0$)

$$h = \frac{f}{\tan(\zeta_s) + \cot(\zeta_c)}$$

$$R_a = \frac{h}{4}$$

Practical surface ($R \neq 0$)

$$h = \frac{f^2}{8R}$$

$$R_a = \frac{f^2}{18\sqrt{3}R}$$

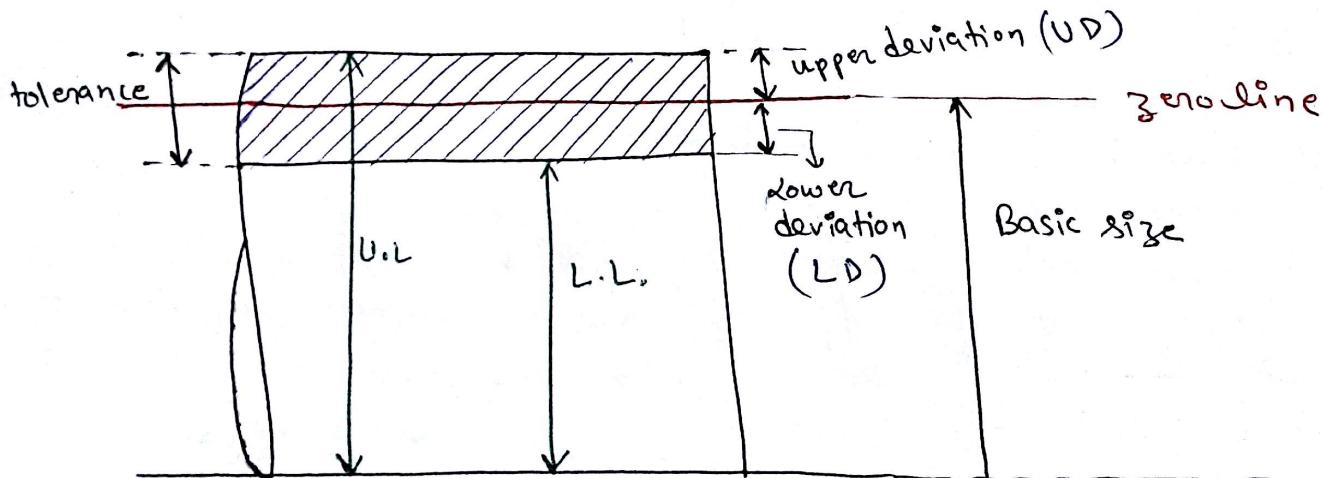
$\Rightarrow h$ = Peak to valley roughness

R_a = average roughness height

- Cutting fluid
 - Primary Aim is cooling
 - 2ndry Aim is lubrication

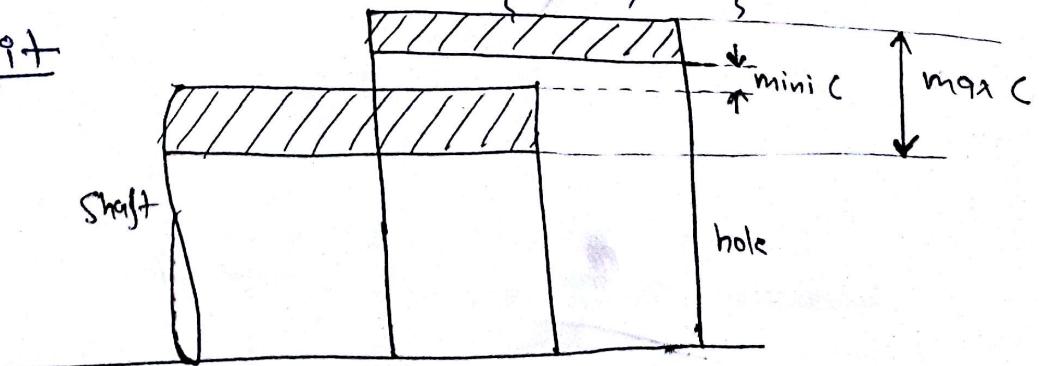
- Cast iron → machined with dry compressed Air
- Brass → no coolant used
- Aluminium → Kerosene oil

CHAPTER- 4 [Limit, tolerance & fits]

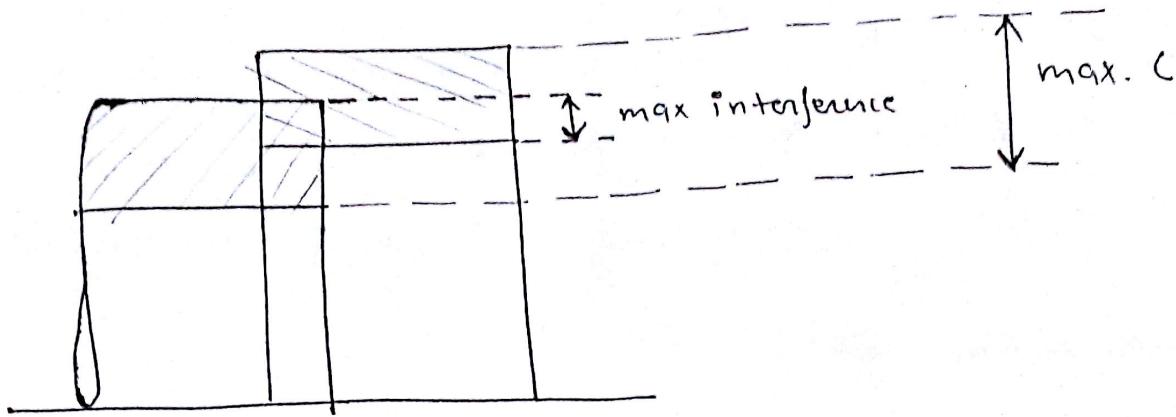


fundamental deviation = mini. { UD, LD }

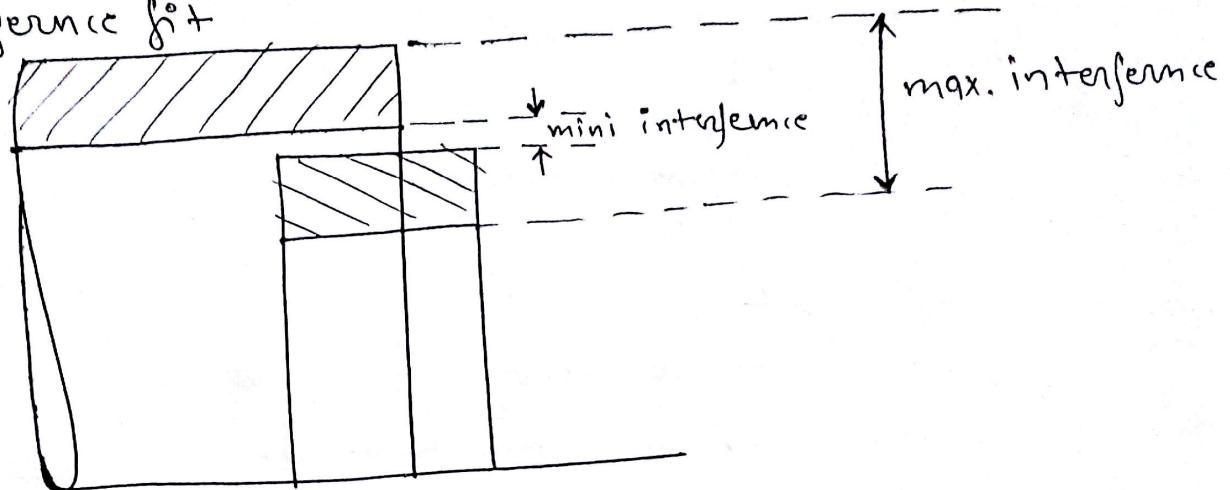
- 1) clearance fit



2) Transient fit



3) Interference fit



- Allowance is the minimum clearance [it is -ve if in case of interference fit]

⇒ Limits & fits

- There are 25 fundamental deviations
- and grades upto 18

IT 6	→ 10°	commonly used
IT 7	→ 16°	
IT 8	→ 25°	
IT 9	→ 40°	
IT 10	→ 64°	

100 E +

↓
Basic size

- Capital letter means hole
- E gives fundamental deviation

Step-1 $D = \sqrt{D_1 D_2}$ [D_1, D_2 are taken from dia table acc. to Basic size]

Step-2 $i = 0.45(D)^{1/3} + 0.001D \text{ } \mu\text{m}$

Step-3 Tolerance = $Ki \text{ } \mu\text{m}$

Step-4 calculation of fundamental deviation

- upto H fundamental deviation is +ve for hole
- upto h fundamental deviation is -ve for shaft
- FD is given in Question or table in terms of D.
- Recommended fits

H7 p6
H7 s6] interference

H7 n6
H7 k6] transition

limit Gauges

Plug gauge → to check tolerance of holes

Ring gauge → to check tolerance of shafts

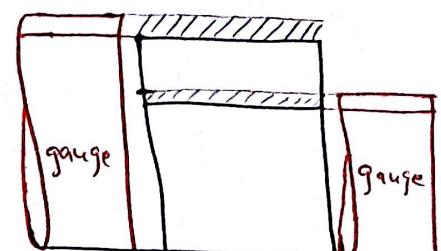
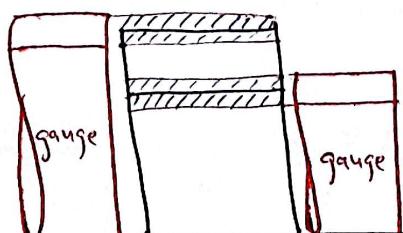
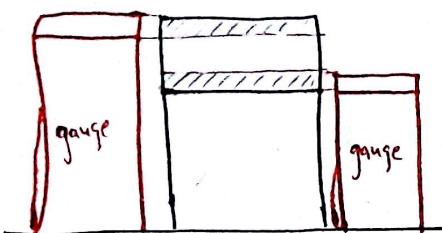
gauge tolerance = 10% of work tolerance

Tolerance system

unilateral

Bilateral

workshop(ISO)



→ Producer's risk

→ consumer's risk

Best wire size to measure thread parameters

$$d = \frac{P}{2} \sec \frac{\alpha}{2}$$

P = pitch of thread

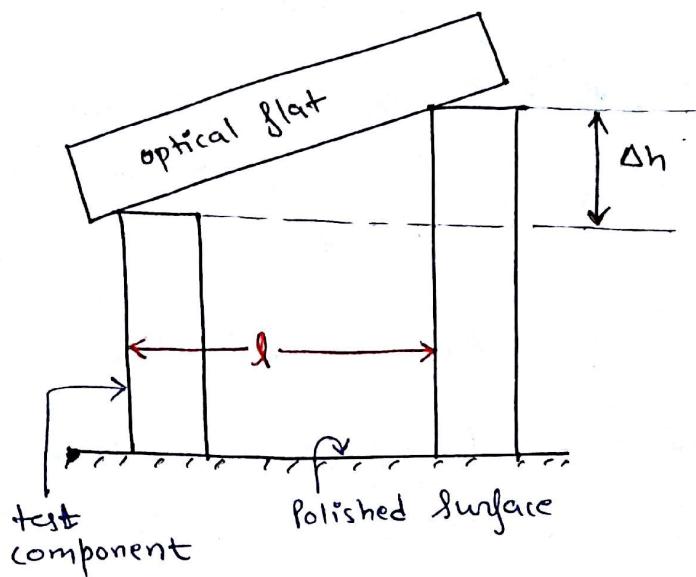
α = thread angle

- Planimeter is a device used to measure surface area of any plane surface by tracing boundary of the area.

- Optical flats: Use monochromatic light to determine the flatness of other optical surface by interference.

$$\Rightarrow \text{Distance b/w two successive fringes} = \frac{\lambda}{2}$$

$$\text{Distance b/w w/p \& optical flat} = n \frac{\lambda}{2}$$



$$\Delta h = n l \frac{\lambda}{2}$$

λ = separation b/w edges (cm)

n = no. of fringes/cm

λ = monochromatic light wavelength (cm)

Δh = diff. b/w gauge heights (cm)

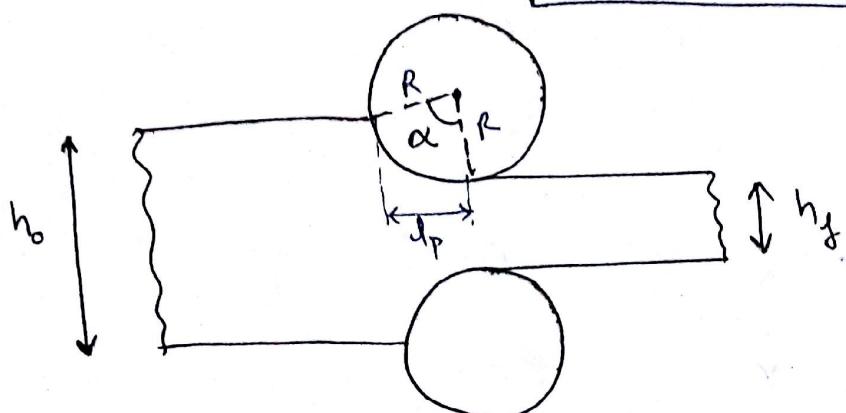
Device	usage
Clinometer	optical device for measuring elevation angle above horizontal
Auto collimator	measurement of small angles
optical Square	Used to set out right angles
Laser scanning micrometer	inspection of tiny workpiece at high temp & motion
Mcleod gauge	Used to measure vacuum
Telescopic Gauges	Used to measure a bore's size

CHAPTER-5 [Metal forming]

- Recrystallisation temp^r for pure metal = $\frac{1}{3}$ of MP
- Recrystallisation temp^r for alloys = $\frac{1}{2}$ of mp

- Rolling is considered as Hot rolling unless mentioned
- Pack rolling \rightarrow Aluminium foil

\Rightarrow Rolling



$$h_o b o V_o = h_f b_f V_f$$

$$\Delta h = h_o - h_f$$

α = bite angle

μ = friction coefficient

$$\cos \alpha = \left(\frac{D - \Delta h}{D} \right)$$

$$\tan \alpha \leq \mu$$

$$(\Delta h)_{\max} = \mu^2 R$$

$$\text{minimum no. of passes} = n = \frac{(\Delta h)_{\text{reqd.}}}{(\Delta h)_{\max}}$$

• Elongation coefficient

$$E = \frac{l_1}{l_0} = \frac{A_0}{A_1} \quad \text{for single pass}$$

$$E^n = \frac{l_n}{l_0} = \frac{A_0}{A_n} \quad \text{for } n\text{-pass}$$

• Power required in rolling

$$\text{projected length} = l_p = R \sin \alpha \text{ mm}$$

$$\text{Projected Area} = l_p \times b \text{ mm}^2$$

$$\text{Roll separating force} = F_o \times (l_p \cdot b) \text{ N}$$

$$\begin{aligned} \text{Arm length} &= a = 0.5 l_p \text{ for hot rolling} \\ &\quad 0.45 l_p \text{ for cold rolling} \end{aligned}$$

$$\text{Torque per roller} = T = F \times \frac{a}{100} \text{ Nm}$$

$$\text{Power} = 2 \times T \times \omega \text{ watt}$$

⇒ Forging : max. mechanical properties obtained 128

- Upsetting test
Hot twist test] to determine forgeability
- Sequence involved in closed die forging

Fullering or Swaging reducing x-s/c to elongate

↓
Edging gathering material at required position

Bending required for those parts which are to be bent.

↓
Drawing reducing x-s/c at one end only

↓
Flattening fitting into die

↓
Blocking Semifinishing impression

↓
Finishing Final push

↓
Trimming Removing flash.

- Hot Forging → molten glass as lubricant
Cold forging → phosphate as lubricant

$$\tau_T = \tau (1 + \epsilon)$$

$$\epsilon_T = \ln(1 + \epsilon) = \ln\left(\frac{l}{l_0}\right) = \ln\left(\frac{A_0}{A}\right)$$

$$\text{True strain } \epsilon_T = \frac{\Delta l}{\text{instantaneous length}}$$

$$\tau_T = K \epsilon_T^n$$

$$n = \epsilon_T \text{ at ultimate tensile stress}$$

⇒ Extrusion

Extrusion ratio = ratio of Areas

- Cold Extrusion \rightarrow collapsible tubes
- Hydrostatic Extrusion \rightarrow for brittle materials
- Extrusion load (P)

$$P = \tau_0 A_0 \ln \left(\frac{A_0}{A_f} \right)$$

Extrusion stress (τ)

$$\tau = \tau_0 \ln \left(\frac{A_0}{A_f} \right)$$

- Drawing load

$$P = \tau_0 A_f \ln \left(\frac{A_0}{A_f} \right)$$

$$\tau = \tau_0 \ln \left(\frac{A_0}{A_f} \right)$$

\Rightarrow Sheet metal operation

- Punching : Punch size = size of hole

$$\text{Die size} = \text{punch size} + 2c$$

Blanking : Die size = size of Product

$$\text{Punch size} = \text{Die size} - 2c$$

$$c = 0.0032 + \sqrt{\tau} \quad \text{mm}$$

$$t = \text{mm}$$

$$\tau = \text{MPa}$$

- Force in punching or blanking = length of cut $\times t \times \tau$
- Shear on Punch

$$F = F_{\max} \times \left(\frac{Pt}{S+Pt} \right) \quad \text{in general}$$

$$F = F_{\max} \times \left(\frac{Pt}{S} \right) \quad \text{when displacement curve is trapezoidal}$$

for ideal condition

$$\tau = \tau_0$$

$$\Rightarrow \frac{A_0}{A_f} = e$$

$$A_0 = e \times A_f$$

τ_0 = flow stress

$B = \mu \cot \alpha$

μ = coefficient of friction

α = half die angle

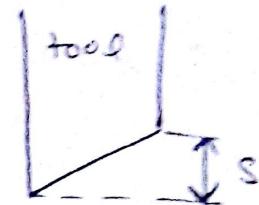
τ_b = back stress on wire

wire drawing

$$\tau = \tau_0 \left(\frac{1+B}{B} \right) \left[1 - \left(\frac{\gamma_f}{\gamma_0} \right)^{2B} \right] + \left(\frac{\gamma_f}{\gamma_0} \right)^{2B} \tau_b$$

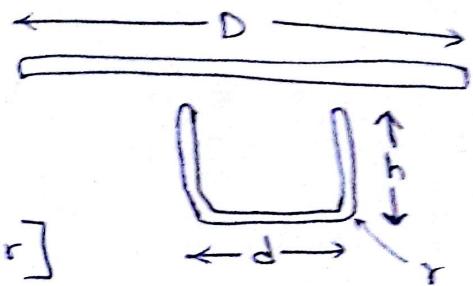
$$W.D. = F_{max} \times P_t$$

$$P_t = (\% \text{ Penetration}) \times t$$



\Rightarrow Drawing

$$\frac{\pi}{4} D^2 = \frac{\pi}{4} d^2 + \pi d h$$



$$\Rightarrow D = \sqrt{d^2 + 4dh} \quad [d > 20r]$$

$$D = \sqrt{d^2 + 4dh} - 0.5r \quad [15r \leq d \leq 20r]$$

- Limiting drawing ratio (LDR)

$$LDR = \frac{D}{d} \approx 1.4 \text{ to } 2.3$$

Allowable reduction in diameter

1st \rightarrow 50%

2nd \rightarrow 30%

3rd \rightarrow 25%

4th \rightarrow 16%

Bend allowance

$$= \alpha (R + Kt)$$

α = bend angle (in radian)

R = bend radius

t = sheet thickness

K = 0.5 for R > 2t

causes/Reason $K = 0.33$
if $R \leq 2t$

- Defects in Drawing

wrinkle

insufficient blank holder pressure

Fracture

large blank holder pressure

earring

anisotropy

miss strike

misplacement

orange peel

coarse grain size

surface scratch

insufficient lubrication

\Rightarrow Spinning

$$t_c = t_b \sin \alpha = \text{cone thickness}$$

t_b = base thickness

α = half cone angle