### Sample Question Paper - 3 CLASS: XII Session: 2021-22 Mathematics (Code-041) Term - 1

#### Time Allowed: 1 hour and 30 minutes

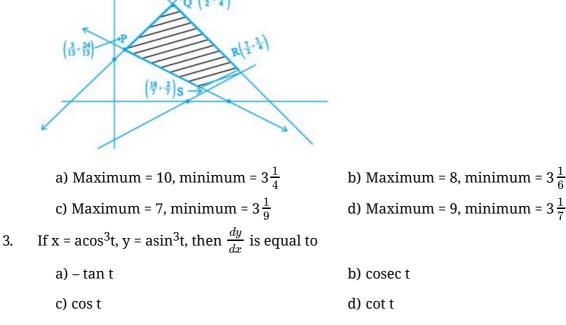
#### **General Instructions:**

- 1. This question paper contains three sections A, B and C. Each part is compulsory.
- 2. Section A has 20 MCQs, attempt any 16 out of 20.3
- 3. . Section B has 20 MCQs, attempt any 16 out of 20
- 4. Section C has 10 MCQs, attempt any 8 out of 10.
- 5. There is no negative marking.
- 6. All questions carry equal marks.

#### $\boldsymbol{SECTION-A}$

#### Attempt any 16 questions

- 1. Let A = { 2 , 3 , 6 }. Which of the following relations on A are reflexive?
  - a) None of these b)  $R_1 = \{(2,2), (3,3), (6,6)\}$ c)  $R_2 = \{(2,2), (3,3), (3,6), (6,3)\}$ d)  $R_3 = \{(2,2), (3,6), (2,6)\}$
- In Figure, the feasible region (shaded) for a LPP is shown. Determine the maximum and [1] minimum value of Z = x + 2y



[1]

[1]

## Maximum Marks: 40

[1]

4.	The function $f(x) = \cot^{-1} x + x$ increases in the	interval	
	a) 0 , $\infty$	b) - $\infty,\infty$	
	c) (1, $\infty$ )	d) -1, $\infty$	
5.	The point at which the maximum value of x + $\leq$ 95, x, y $\geq$ 0 is obtained, is	y, subject to the constraints x + 2y $\leq$ 70, 2x + y	[1]
	a) (20, 35)	b) (30, 25)	
	c) (35, 20)	d) (40,15)	
6.	The system of equations, x + y = 2 and 2x + 2y	= 3 has	[1]
	a) a unique solution	b) finitely many solutions	
	c) no solution	d) infinitely many solutions	
7.	If y = $x^{xsinx}$ then $\frac{dy}{dx} = ?$		[1]
	a) $x^{\sin x} \left\{ \frac{\sin x + x \log x \cdot \sin x}{x} \right\}$	b) $(\sin x \cos x) \cdot x^{(\sin x - 1)}$	
	c) None of these	d) $(\sin x) \cdot x^{(\sin x - 1)}$	
8.	If A and B are matrices of same order, then (A	.B' – BA') is a	[1]
	a) null matrix	b) unit matrix	
	c) symmetric matrix	d) skew-symmetric matrix	
9.	Maximize Z = $3x + 4y$ , subject to the constraints : $x + y \le 1$ , $x \ge 0$ , $y \ge 0$ .		[1]
	a) 4	b) 5	
	c) 6	d) 3	
10.	If $y=\sqrt{rac{1+ an x}{1- an x}}$ then $rac{dy}{dx}=$ ?		[1]
	a) $\sec^2\left(\frac{x}{4}\right)$	b) $rac{1}{2} \mathrm{sec}^2 x \cdot \mathrm{tan}ig(x + rac{\pi}{4}ig)$	
	a) $\frac{\sec^2\left(\frac{x}{4}\right)}{\sqrt{\tan\left(x+\frac{\pi}{4}\right)}}$		
	c) $\sec^2\left(x+\frac{\pi}{4}\right)$	d) none of these	
	c) $rac{\sec^2\left(x+rac{\pi}{4} ight)}{2\sqrt{ an(x+rac{\pi}{4})}}$		
11.	Let $f(x) = egin{cases} rac{1}{ x } &  ext{for }  x  \geq 1 \ ax^2 + b &  ext{for }  x  < 1 \end{cases}$ If f(x) is	s continuous and differentiable at any point, then	[1]
	a) a = 1, b = –1	b) $a=rac{1}{2}, b=-rac{3}{2}$	
	c) $a = \frac{1}{2}, b = \frac{3}{2}$	d) none of these	
12.	Minimize Z = 5x + 10 y subject to x + 2y $\leq$ 120,	$x + y \ge 60, x - 2y \ge 0, x, y \ge 0$	[1]
	a) Minimum Z = 310 at (60, 0)	b) Minimum Z = 320 at (60, 0)	
	c) Minimum Z = 330 at (60, 0)	d) Minimum Z = 300 at (60, 0)	
13.	The normal to the curve x = a $(\cos  heta +  heta \sin  heta$ that	) ,y = a $(\sin heta -  heta\cos heta)$ at any point $ heta$ is such	[1]

	a) it is at a constant distance from the origin	b) it passes through the origin	
	c) it makes a constant angle with X – axis	d) none of these	
14.	The function $f(x) = \sin^{-1}(\cos x)$ is		[1]
	a) None of these	b) differentiable at x = 0	
	c) discontinuous at x = 0	d) continuous at x = 0	
15.	The equation of the tangent to the curve y = (1, 0) and (e, e), the value of x is:	x log x is parallel to the chord joining the points	[1]
	a) $e^{1/1-e}$	b) $e^{(e-1)(2e-1)}$	
	c) $e^{\frac{2e-1}{e-1}}$	d) $\frac{e-1}{e}$	
16.	Assume X, Y, Z, W, and P are matrices of orderespectively.	er 2 $ imes$ n, 3 $ imes$ k, 2 $ imes$ p, n $ imes$ 3 and p $ imes$ k,	[1]
	The restriction on n, k and p so that PY + WY	will be defined are	
	a) p is arbitrary, k = 3	b) k is arbitrary, p = 2	
	c) k = 2, p = 3	d) k = 3, p = n	
17.	At what points the slope of the tangent to the	e curve $x^2 + y^2 - 2x - 3 = 0$ is zero	[1]
	a) (3, 0), (1, 2)	b) (-1, 0), (1, 2)	
	c) (3, 0), (-1, 0)	d) (1, 2), (1, -2)	
18.	If $\sin^{-1} x - \cos^{-1} x = \frac{\pi}{6}$ , then x =		[1]
	a) $\frac{1}{2}$	b) None of these	
	c) $\frac{\sqrt{3}}{2}$	d) $-\frac{1}{2}$	
19.	If $f(x) = \sqrt{x^2 + 6x + 9}$ , then f'(x) is equal	l to	[1]
	a) 1 for all $x \in R$	b) none of these	
	c) 1 for x < -3	d) -1 for x < -3	
20.	If A is a square matrix, then AA is a		[1]
	a) none of these	b) skew-symmetric matrix	
	c) symmetric matrix	d) diagonal matrix	
		TION – B	
21.	$egin{array}{c}  extsf{Attempt}  extsf{array} \  extsf{Let} \ f \ : \ R \  o \ R \  extsf{be} \ R \  extsf{be} \  extsf{def} \  extsf{be} \  extsf{def} \  extsf{array} \  extsf{array} \  extsf{array} \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	<b>ny 16 questions</b> $f x \in R$ Then f is	[1]
<u>4</u> 1,	-		[1]
	a) one – one	b) Bijective	
nn	c) f is not defined The minimum value of f(x) = 3x <sup>4</sup> - 8x <sup>3</sup> - 48x -	d) Onto	[1]
22.			[-]
	a) 25	b) 16	

#### d) None of these

[1]

23. Feasible region (shaded) for a LPP is shown in Figure. Maximize Z = 5x + 7y.

23.	reasible region (shaded) for a LPP is shown	in Figure. Maximize Z – 3x + 7y.	[1]
	(0, 2) 0 A(7, 0)		
	a) 45	b) 49	
	c) 47	d) 43	
24.	If y = $\cos^2 x^3$ then $\frac{dy}{dx} = ?$		[1]
	a) $_{-3x^2} \sin^2 x^3$	b) none of these	
	c) $_{-3x^2} \cos^2(2x^3)$	d) $_{-3x^2} \sin (2x^3)$	
25.	If y = $ax^2$ + bx + c, then $y^3 \frac{d^2y}{dx^2}$ is		[1]
	a) a constant	b) a function of x only	
	c) a function of y only	d) a function of x and y	
26.	$\sinig(rac{\pi}{3}-\sin^{-1}ig(-rac{1}{2}ig)ig)$ is equal to		[1]
	a) $\frac{1}{4}$	b) $\frac{1}{3}$	
	c) 1	d) $\frac{1}{2}$	
27.	R is a relation on the set Z of integers and it i	is given by (x, y) $\in$ R $\Leftrightarrow$ $ x - y  \le$ 1. Then, R is	[1]
	a) an equivalence relation	b) symmetric and transitive	
	c) reflexive and symmetric	d) reflective and transitive	
28.	$\sin^{-1}(1-x)-2\sin^{-1}x=rac{\pi}{2}$ then x is equ	ial to	[1]
	a) $\frac{1}{2}$	b) $(0, \frac{1}{2})$	
	c) $(1, \frac{1}{2})$	d) 0	
29.	If A + B = $\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$ and A - 2 B = $\begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix}$	, then A = ?	[1]
	a) $\begin{bmatrix} 1 & 1 \\ 2 & 1 \end{bmatrix}$	b) none of these	
	c) $\frac{1}{3} \begin{bmatrix} 1 & 1 \\ 3 & 1 \end{bmatrix}$	d) $\frac{1}{3}\begin{bmatrix} 2 & 1\\ 1 & 2 \end{bmatrix}$	
30.	If y = tan <sup>-1</sup> $\left(\frac{1-\cos x}{\sin x}\right)$ then $\frac{dy}{dx} = ?$		[1]
	a) 1	b) $\frac{1}{2}$	
	c) -1	d) $\frac{-1}{2}$	
31.	If $f(x) =  \log_e x $ , then		[1]

	a) f'(1) = -1	b) f'(1) = 1	
	c) $f'(1^{-}) = -1$	d) $f'(1^+) = 1$	
32.	If $y = \log \sqrt{\tan x}$ , then the value of $rac{dy}{dx}$ at $x$	$r=rac{\pi}{4}$ is given by	[1]
	a) 0	b) $\infty$	
	c) $\frac{1}{2}$	d) 1	
33.	The function $f(x) = x^9 + 3x^7 + 64$ is increasing	g on	[1]
	a) (-∞ , 0)	b) R <sub>0</sub>	
	c) (0 , $\infty$ )	d) R	
34.	If $\cos^{-1}x > \sin^{-1}x$ , then		[1]
	a) $0 \leq x < rac{1}{\sqrt{2}}$	b) $rac{1}{\sqrt{2}} < x \leq 1$	
	c) $-1 \leq x < rac{1}{\sqrt{2}}$	d) x > 0	
35.	Any tangent to the curve $y = 2x^7 + 3x + 5$		[1]
	a) is parallel to x-axis	b) is parallel to y-axis	
	c) makes an acute angle with x-axis	d) makes an obtuse angle with x-axis	
36.	In a LPP, the linear inequalities or restriction	ns on the variables are called	[1]
	a) Limits	b) Inequalities	
	c) Linear constraints	d) Constraints	
37.	If A is an invertible square matrix and k is a	non-negative real number then(kA) <sup>-1</sup> = ?	[1]
	a) $\frac{1}{k}$ . A <sup>-1</sup>	b) <sub>-k.A</sub> -1	
	c) <sub>k.A</sub> -1	d) None of these	
38.	If a matrix A is symmetric as well as skew sy	mmetric, then A is a	[1]
	a) none of these	b) null matrix	
	c) unit matrix	d) diagonal matrix	
39.	If $\sqrt{x}+\sqrt{y}=\sqrt{a,}$ then $\left(rac{d^2y}{dx^2} ight)_{x=a}$ is equal	l to	[1]
	a) $\frac{1}{2a}$	b) a	
	c) None of these	d) $\frac{1}{a}$	
40.	Let $\mathrm{f}:\mathrm{R} o\mathrm{R}$ be a function defined by $f(x)$ =	$=rac{x^2-8}{x^2+2}.$ Then, f is	[1]
	a) one-one and onto	b) one-one but not onto	
	c) onto but not one-one	d) neither one-one nor onto	
		TION – C	
41.	$egin{array}{c} { m Attempt}{ m a} \ { m If}lpha={ m tan}^{-1}ig({ m tan}rac{5\pi}{4}ig){ m and}eta={ m tan}^{-1}ig(-{ m tan}eta) \ { m tan}eta={ m tan}^{-1}ig(-{ m tan}eta){ m tan}eta={ m tan}eta={$	ny 8 questions $\frac{2\pi}{2\pi}$ then	[1]
II.	a) none of these	_	[1]
		b) $lpha-eta=rac{7\pi}{12}$	

43.

44.

45.

42. Determine the minimum value of Z = 3x + 4y if the feasible region (shaded) for a LPP is shown [1] in Figure above.

$ \begin{array}{c}                                     $		
a) 154	b) 196	
c) 112	d) 132	
If $y = ae^{mx} + be^{-mx}$ , then $y_2$ is equal to		[1]
a) my <sub>1</sub>	b) <sub>-m<sup>2</sup>y</sub>	
c) <sub>m<sup>2</sup>y</sub>	d) None of these	
Let f(x) = 2x <sup>3</sup> - 3x <sup>2</sup> - 12x + 5 on [-2, 4]. The rela	ative maximum occurs at x =	[1]
a) 2	b) -1	
c) 4	d) -2	
S is a relation over the set R of all real numbers is	ers and its is given by (a, b) $\in$ S $\Leftrightarrow$ ab $\geq$ 0. Then, S	[1]
a) an equivalence relation	b) reflexive and symmetric only	
c) symmetric and transitive only	d) antisymmetric relation	

# Question No. 46 to 50 are based on the given text. Read the text carefully and answer the questions:

The upward speed v(t) of a rocket at time t is approximated by v(t) =  $at^2 + bt + c$ ,  $0 \le t \le 100$ , where a, b and c are constants. It has been found that the speed at times t = 3, t = 6 and t = 9 seconds are respectively 64, 133 and 208 miles per second.

If	$\begin{pmatrix} 9 & 3 & 1 \\ 36 & 6 & 1 \\ 81 & 9 & 1 \end{pmatrix}^{-1} = \frac{1}{18} \begin{pmatrix} 1 & -2 \\ -15 & 24 \\ 54 & -54 \end{pmatrix}$	$\begin{pmatrix} 1\\ -9\\ 1 & 18 \end{pmatrix}$ ,	
	v(t) is given by		
46.			[1]
46.		b) t <sup>2</sup> + 20t + 1	[1]
46.	a) $t^2 + \frac{1}{3}t + 20$ c) $t^2 + t + 1$		[1
<ul><li>46.</li><li>47.</li></ul>	a) $t^2 + \frac{1}{3}t + 20$	b) $t^2 + 20t + 1$ d) $\frac{1}{3}t^2 + 20t + 1$	[1
	a) $t^2 + \frac{1}{3}t + 20$ c) $t^2 + t + 1$		
	a) $t^2 + \frac{1}{3}t + 20$ c) $t^2 + t + 1$ The speed at time t = 15 seconds is	d) $\frac{1}{3}t^2 + 20t + 1$	
	a) $t^{2} + \frac{1}{3}t + 20$ c) $t^{2} + t + 1$ The speed at time t = 15 seconds is a) 366 miles/sec	<ul> <li>d) <sup>1</sup>/<sub>3</sub>t<sup>2</sup> + 20t + 1</li> <li>b) 346 miles/sec</li> <li>d) 356 miles/sec</li> </ul>	
47.	a) $t^{2} + \frac{1}{3}t + 20$ c) $t^{2} + t + 1$ The speed at time t = 15 seconds is a) 366 miles/sec c) 376 miles/sec	<ul> <li>d) <sup>1</sup>/<sub>3</sub>t<sup>2</sup> + 20t + 1</li> <li>b) 346 miles/sec</li> <li>d) 356 miles/sec</li> </ul>	[1
47.	<ul> <li>a) t<sup>2</sup> + 1/3 t + 20</li> <li>c) t<sup>2</sup> + t + 1</li> <li>The speed at time t = 15 seconds is</li> <li>a) 366 miles/sec</li> <li>c) 376 miles/sec</li> <li>The time at which the speed of rock</li> </ul>	d) $\frac{1}{3}t^2 + 20t + 1$ b) 346 miles/sec d) 356 miles/sec tet is 784 miles/sec is	[1
47.	<ul> <li>a) t<sup>2</sup> + 1/3 t + 20</li> <li>c) t<sup>2</sup> + t + 1</li> <li>The speed at time t = 15 seconds is</li> <li>a) 366 miles/sec</li> <li>c) 376 miles/sec</li> <li>The time at which the speed of rock</li> <li>a) 20 seconds</li> </ul>	d) $\frac{1}{3}t^2 + 20t + 1$ b) 346 miles/sec d) 356 miles/sec tet is 784 miles/sec is b) 25 seconds	[1
47. 48.	<ul> <li>a) t<sup>2</sup> + 1/3 t + 20</li> <li>c) t<sup>2</sup> + t + 1</li> <li>The speed at time t = 15 seconds is</li> <li>a) 366 miles/sec</li> <li>c) 376 miles/sec</li> <li>The time at which the speed of rock</li> <li>a) 20 seconds</li> <li>c) 30 seconds</li> </ul>	d) $\frac{1}{3}t^2 + 20t + 1$ b) 346 miles/sec d) 356 miles/sec tet is 784 miles/sec is b) 25 seconds	[1
47. 48.	<ul> <li>a) t<sup>2</sup> + 1/3 t + 20</li> <li>c) t<sup>2</sup> + t + 1</li> <li>The speed at time t = 15 seconds is</li> <li>a) 366 miles/sec</li> <li>c) 376 miles/sec</li> <li>The time at which the speed of rock</li> <li>a) 20 seconds</li> <li>c) 30 seconds</li> <li>The value of b + c is</li> </ul>	d) $\frac{1}{3}t^2 + 20t + 1$ b) 346 miles/sec d) 356 miles/sec tet is 784 miles/sec is b) 25 seconds d) 27 seconds	[] [1
47. 48.	a) $t^2 + \frac{1}{3}t + 20$ c) $t^2 + t + 1$ The speed at time t = 15 seconds is a) 366 miles/sec c) 376 miles/sec The time at which the speed of rock a) 20 seconds c) 30 seconds The value of b + c is a) 21	d) $\frac{1}{3}t^2 + 20t + 1$ b) 346 miles/sec d) 356 miles/sec tet is 784 miles/sec is b) 25 seconds d) 27 seconds b) $\frac{3}{4}$	[1 [1 [1
<ul><li>47.</li><li>48.</li><li>49.</li></ul>	a) $t^2 + \frac{1}{3}t + 20$ c) $t^2 + t + 1$ The speed at time t = 15 seconds is a) 366 miles/sec c) 376 miles/sec The time at which the speed of rock a) 20 seconds c) 30 seconds The value of b + c is a) 21 c) $\frac{4}{3}$	d) $\frac{1}{3}t^2 + 20t + 1$ b) 346 miles/sec d) 356 miles/sec tet is 784 miles/sec is b) 25 seconds d) 27 seconds b) $\frac{3}{4}$	[1

## Solution

#### SECTION – A

### 1. **(b)** $R_1 = \{(2,2), (3,3), (6,6)\}$ **Explanation:** $R_1$ is a reflexive on A, because (a,a) $\in R_1$ for each $a \in A$

2. **(d)** Maximum = 9, minimum =  $3\frac{1}{7}$ 

#### Explanation:

Corner points	Z = x +2 y
P(3/13,24/13)	51/13
Q(3/2,15/4)	9(Max.)
R(7/2,3/4)	5
S(18/7,2/7)	22/7(Min.)

Hence the maximum value is 9 and the minimum value is  $3\frac{1}{7}$ 

#### 3. **(a)** – tan t

**Explanation:** We have to find:  $\frac{dy}{dx} = \frac{\frac{dy}{dt}}{\frac{dx}{dt}} = \frac{3a\sin^2 t \cos t}{3a\cos^2 t(-\sin t)} = -\tan t$ 

4. **(b)** - $\infty$  , $\infty$ 

Explanation: 
$$(-\infty, \infty)$$
  
 $f(x) = \cot^{-1} x + x$   
 $f'(x) = \frac{-1}{1+x^2} + 1$   
 $= \frac{-1+1+x^2}{1+x^2}$   
 $= \frac{x^2}{1+x^2} \ge 0, \forall x \in R$   
So, f (x) is increasing on  $(-\infty, \infty)$ 

#### 5. **(d)** (40,15)

**Explanation:** We need to maximize the function z = x + y Converting the given inequations into equations, we obtain

x + 2y = 70, 2x + y = 95, x = 0 and y = 0

Region represented by x + 2y  $\leq$  70 :

The line x + 2y = 70 meets the coordinate axes at A(70, 0) and B(0, 35) respectively. By joining these points we obtain the line x + 2y = 70. Clearly (0, 0) satisfies the inequation x + 2y  $\leq$  70. So, the region containing the origin represents the solution set of the inequation x + 2y  $\leq$  70.

Region represented by 2x + y  $\leq$  95 :

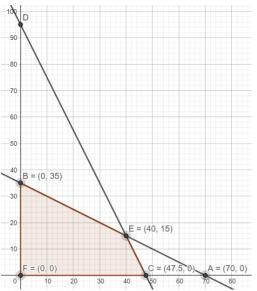
The line 2x + y = 95 meets the coordinate axes at  $C\left(\frac{95}{2}, 0\right)$  respectively. By joining these points we obtain the line 2x + y = 95

Clearly (0, 0) satisfies the inequation  $2x + y \le 95$ . So, the region containing the origin represents the solution set of the inequation  $2x + y \le 95$ 

Region represented by  $x \ge 0$  and  $y \ge 0$ :

since, every point in the first quadrant satisfies these inequations. So, the first quadrant is the region represented by the inequations  $x \ge 0$ , and  $y \ge 0$ 

The feasible region determined by the system of constraints x + 2y  $\leq$  70, 2x + y  $\leq$  95, x  $\geq$  0, and y  $\geq$  0 are as follows.



The corner points of the feasible region are O(0, 0), C( $\frac{95}{2}$ , 0) E(40, 15) and B(0, 35). The value fo Z at these corner points are as follows.

Corner point : z = x + yO(0, 0) : 0 + 0 = 0 $C\left(\frac{95}{2}, 0\right) : \frac{95}{2} + 0 = \frac{95}{2}$ E(40, 15) : 40 + 15 = 55B(0, 35) : 0 + 35 = 35

We see that maximum value of the objective function Z is 55 which is at (40, 15).

#### 6. **(c)** no solution

**Explanation:** For No solution,  $\frac{a_1}{a_2} = \frac{b_1}{b_2} \neq \frac{c_1}{c_2}$ , for given system of equations we have:  $\frac{1}{2} = \frac{1}{2} \neq \frac{2}{3}$ .

7. **(a)** 
$$x^{\sin x} \left\{ \frac{\sin x + x \log x \cdot \sin x}{x} \right\}$$

**Explanation:** Let  $y = f(x) = x^{sinx}$ Taking log both sides, we obtain

 $\log_e y = \sin x \log_e x$  -(1) (Since  $\log_a b^c = c \log_a b$ )

Differentiating (i) with respect to x, we obtain

$$rac{1}{y}rac{dy}{dx} = \sin x imes rac{1}{x} + \log_e x imes \cos x$$
  
 $\Rightarrow rac{dy}{dx} = y imes \left(rac{\sin x}{x} + \log_e x \cos x
ight)$   
 $\Rightarrow rac{dy}{dx} = f'(x) = x^{sinx} \left(rac{\sin x + x \log x \sin x}{x}
ight).$ 

Which is the required solution.

#### 8. (d) skew-symmetric matrix

**Explanation:** We have matrices A and B of same order. Let P = (AB' - BA')Then, P' = (AB' - BA')'= (AB')' - (BA')'= (B')' (A)' - (A')'B' = BA' - AB' = -(AB' - BA') = -PTherefore, the given matrix (AB - BA') is a skew-symmetric matrix.

#### 9. **(a)** 4

**Explanation:** According to the question, maximize , Z = 3x + 4y, subject to the constraints:  $x + y \le 1$ ,  $x \ge 0$ ,  $y \ge 0$ .

Corner points	Z = 3x +4 y
C(0, 0 )	0
B (1,0)	3
D(0,1 )	4

Hence the maximum value is 4

10. (c) 
$$\frac{\sec^2\left(x+\frac{\pi}{4}\right)}{2\sqrt{\tan\left(x+\frac{\pi}{4}\right)}}$$

**Explanation:** Given that  $y = \sqrt{\frac{1 + \tan x}{1 - \tan x}}$ Using  $\tan\left(\frac{\pi}{4} + x\right) = \frac{1 + \tan x}{1 - \tan x}$ , we obtain  $y = \sqrt{\tan\left(\frac{\pi}{4} + x\right)}$ 

Differentiating with respect to x, we obtain

$$rac{dy}{dx} = rac{1}{2\sqrt{ anigl(rac{\pi}{4}+xigr)}} imes \sec^2igl(rac{\pi}{4}+xigr) imes 1$$
  
Hence,  $rac{dy}{dx} = rac{\sec^2igl(rac{\pi}{4}+xigr)}{2\sqrt{ anigl( anigl(rac{\pi}{4}+xigr)igr)}}$ 

11. (d) none of these

Explanation: Given that 
$$f(x)=\left\{egin{array}{c} rac{-1}{x},x\leq -1\ ax^2+b,-1< x< 1\ rac{1}{x},x\geq 1\end{array}
ight\}$$

 $\therefore f(\mathbf{x}) \text{ is continuous and differentiable at any point, consider } \mathbf{x} = 1.$   $\lim_{x \to 1} \frac{1}{x} = \lim_{x \to 1} ax^2 + b$   $\Rightarrow \mathbf{a} + \mathbf{b} = 1$ Also,  $\Rightarrow \lim_{x \to 1^-} \frac{f(x) - f(1)}{x - 1} = \lim_{x \to 1^+} \frac{f(x) - f(1)}{x - 1}$   $\Rightarrow \lim_{x \to 1} \frac{ax^2 - a}{x - 1} = \lim_{x \to 1^+} \frac{1 - x}{x(x - 1)}$   $\Rightarrow \lim_{x \to 1} a(x + 1) = \lim_{x \to 1} (-x)$   $\Rightarrow a = \frac{-1}{2}$ Putting above value in a + b = 1, we get

$$b = \frac{3}{2}$$

Which is the required value of a and b.

12. **(d)** Minimum Z = 300 at (60, 0)

**Explanation:** Objective function is Z = 5x + 10 y .....(1).

The given constraints are : x + 2y  $\leq$  120, x + y  $\geq$  60, x – 2y  $\geq$  0, x, y  $\geq$  0 .

The corner points are obtained by drawing the lines x+2y = 120, x+y = 60 and x-2y = 0. The points so obtained are (60,30),(120,0), (60,0) and (40,20)

Corner points	Z = 5x + 10y
D(60 ,30 )	600
A(120,0)	600
B(60,0)	300(Min.)
C(40,20)	400

Here , Z = 300 is minimum at ( 60, 0 ).

13. (a) it is at a constant distance from the origin

**Explanation:** Equation of normal at  $\theta$  is  $x\cos\theta + y\sin\theta - a = 0$ . So, normal is at a fixed distance a from the origin.

#### 14. **(d)** continuous at x = 0

**Explanation:** Given  $f(x) = \sin^{-1}(\cos x)$ , Checking differentiability and continuity, LHL at x = 0,  $\lim_{\mathbf{x}\to 0^-} \mathbf{f}(\mathbf{x}) = \lim_{\mathbf{h}\to 0} \mathbf{f}(0-\mathbf{h}) = \lim_{\mathbf{h}\to 0} \sin^{-1}(\cos(0-\mathbf{h})) = \lim_{\mathbf{h}\to 0} \sin^{-1}(\cos(-\mathbf{h})) = \sin^{-1}1 = \frac{\pi}{2}$  $\mathbf{x} \rightarrow 0^{-}$ RHL at x = 0,  $\lim_{\mathbf{x}\to 0^+} \mathbf{f}(\mathbf{x}) = \lim_{\mathbf{h}\to 0} \mathbf{f}(0+\mathbf{h}) = \lim_{\mathbf{h}\to 0} \sin^{-1}(\cos(0+\mathbf{h})) = \lim_{\mathbf{h}\to 0} \sin^{-1}(\cos(\mathbf{h})) = \sin^{-1} 1 = \frac{\pi}{2}$  $\mathbf{x} {
ightarrow} 0^+$  ` And  $f(0) = \frac{\pi}{2}$ Hence, f(x) is continuous at x = 0. LHD at x = 0,  $\lim_{x \to 0^{-}} \frac{f(x) - f(0)}{x - 0} = \lim_{h \to 0} \frac{f(0 - h) - f(0)}{0 - h - 0}$  $=\lim_{h o 0}rac{\sin^{-1}(\cos(0-h))-\left(rac{\pi}{2}
ight)}{-h}=1$ RHD at x = 0,  $\lim_{x \to 0^+} \frac{f(x) - f(0)}{x - 0} = \lim_{h \to 0} \frac{f(0 + h) - f(0)}{0 + h - 0}$  $=\lim_{h o 0}rac{\sin^{-1}(\cos(0+h))-\left(rac{\pi}{2}
ight)}{h}=-1$  $\therefore$  LHD  $\neq$  RHD  $\therefore$  f(x) is not differentiable at x =0. (a)  $e^{1/1-e}$ **Explanation:**  $y = x \log x$ Differentiating the function with respect to 'x',  $\frac{dy}{dx} = 1 + \log x$ Slope of tangent to the curve =  $1 + \log x$ And, slope of the chord joining the points, (1, 0) & (e, e)  $m = \frac{e}{e-1}$ The tangent to the curve is parallel to the chord joining the points, (1, 0) & (e, e) ∴ m = 1 + log x  $\frac{e}{e-1} = 1 + \log x$   $\log x = \frac{e}{e-1} - 1$   $\log x = \frac{e}{e-1}$   $\log x = \frac{1}{e-1}$  $x = e^{\frac{1}{1-e^2}}$ (d) k = 3, p = n **Explanation:** Matrices P and Y are of the orders  $p \times k$  and  $3 \times k$  respectively. Therefore, matrix PY will be defined if k = 3. Then, PY will be of the order  $p \times k = p \times 3$ .

Matrices W and Y are of the orders n imes 3 and 3 imes k = 3 imes 3 respectively.

As, the number of columns in W is equal to the number of rows in Y, Matrix WY is well defined and is of the order n imes 3.

Matrices PY and WY can be added only when their orders are the same.

Therefore, PY is of the order  $p \times 3$  and WY is of the order  $n \times 3$ . Thus, we must have p = n. Therefore, k = 3 and p = n are the restrictions on n, k and p so that

PY + WY will be defined.

17. **(d)** (1, 2), (1, -2)

15.

16.

**Explanation:**  $x^2 + y^2 - 2x - 3 = 0$ Differentiating with respect to x,

 $2x+2yrac{dy}{dx}-2=0 \ \Rightarrow rac{dy}{dx}=rac{2-2x}{2y}$ Given that slope of tangent =  $\frac{dy}{dx} = 0$  $\Rightarrow \frac{2-2x}{2y} = 0$ x = 1  $x^2 + y^2 - 2x - 3 = 0$  $\Rightarrow$  y<sup>2</sup> = 2x + 3 - x<sup>2</sup> x = 1  $\Rightarrow y = \pm 2$ Point are (1, 2) and (1, -2) 18. (c)  $\frac{\sqrt{3}}{2}$ **Explanation:**  $\sin^{-1} - \cos^{-1} x = \frac{\pi}{6}$ Explanation:  $\sin^{-1} - \cos^{-1} x = \frac{\pi}{2} - \cos^{-1} x - \cos^{-1} x = \frac{\pi}{6}$   $\frac{\pi}{2} - 2\cos^{-1} x = \frac{\pi}{6}$   $\frac{\pi}{2} - \frac{\pi}{6} = 2\cos^{-1} x$   $\frac{2\pi}{6} = 2\cos^{-1} x$   $\frac{\pi}{3} \times \frac{1}{2} = \cos^{-1} x$   $\frac{\pi}{6} = \cos^{-1} x$   $x = \cos^{\frac{\pi}{2}}$  $x = \cos \frac{\pi}{6}$  $x = \frac{\sqrt{3}}{2}$ (d) -1 for x < -3 19. **Explanation:** We have,  $f(x) = \sqrt{x^2 + 6x + 9}$  $=\sqrt{(x+3)^2}$ = |x + 3|  $f(x) = egin{cases} x+3 & x \geq -3 \ -x-3 & x < -3 \ \Rightarrow f'(x) = egin{cases} 1 & x \geq -3 \ -1 & x \geq -3 \ -1 & x < -3 \ \end{pmatrix}$ f'(x) = -1 for x < -3. Which is the required solution. 20. (a) none of these Explanation: If A is a square matrix, Let A =  $\begin{bmatrix} 1 & 2 \\ 1 & 0 \end{bmatrix}$ 

 $AA = \begin{bmatrix} 1 & 0 \\ 1 & 2 \\ 1 & 0 \end{bmatrix} \times \begin{bmatrix} 1 & 2 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 3 & 2 \\ 1 & 2 \end{bmatrix}$ then AA is neither of the matrices given i

then AA is neither of the matrices given in the options of the question.

#### SECTION – B

21. (c) f is not defined

**Explanation:** Because ,  $rac{1}{x}$  is not defined for  $x = 0, \, as \, 0 \in R, \, \therefore \, f \, is \, not \, defined.$ 

22. **(c)** -39

**Explanation:** Given function,  $f(x) = 3x^4 - 8x^3 - 48x + 25$   $F'(x) = 12x^3 - 24x^2 - 48 = 0$   $F'(x) = 12(x^3 - 2x^2 - 4) = 0$ Differentiating again, we obtain F"(x) =  $3x^2 - 4x = 0$ x(3x - 4) = 0 x = 0 or x =  $\frac{4}{3}$ Putting the value in equation, we obtain f(x) = -39

#### 23. **(d)** 43

#### **Explanation:**

Corner points	Z = 5x + 7y
O(0,0)	0
B (3,4)	43
A(7,0)	35
C(0,2)	14

Hence the maximum value is 43

#### 24. **(d)** $-3x^2 \sin(2x^3)$

**Explanation:** Given,  $y = \cos^2 x^3 = (\cos(x^3))^2$   $\frac{dy}{dx} = (2\cos x^3)(-\sin(x^3)) \times 3x^2$ Using 2 sin A cos A = sin 2A  $\frac{dy}{dx} = -3x^2 \sin (2x^3)$ 

25. **(c)** a function of y only

Explanation: y =  $ax^2 + bx + c$   $\frac{dy}{dx} = 2ax + b$   $\frac{d^2y}{dx^2} = 2a$  $y^3 \frac{d^2y}{dx^2} = 2ay^3$  = A function of y only

26. **(c)** 1

**Explanation:**  $\sin^{-1}\left(-\frac{1}{2}\right) = -\sin^{-1}\left(\frac{1}{2}\right)$ , as  $\sin^{-1}(-x) = -\sin^{-1}x$ We all know that the principle branch of  $\sin^{-1}x$  is  $\left[-\frac{\pi}{2}, \frac{\pi}{2}\right]$  and  $-\frac{\pi}{6} \in \left[-\frac{\pi}{2}, \frac{\pi}{2}\right]$  $\therefore \sin^{-1}\left(-\frac{1}{2}\right) = -\frac{\pi}{6}$ Now,  $\sin\left(\frac{\pi}{3} - \sin^{-1}\left(-\frac{1}{2}\right)\right) = \sin\left(\frac{\pi}{3} + \frac{\pi}{6}\right) = \sin\left(\frac{3\pi}{6}\right) = \sin\left(\frac{\pi}{2}\right) = 1$ Therefore, the required value of  $\sin\left(\frac{\pi}{3} - \sin^{-1}\left(-\frac{1}{2}\right)\right) = 1$ 

27. (c) reflexive and symmetric

```
Explanation: According to the condition,

(x,y) \in \mathbb{R} \implies |x-y| \le 1

Reflexive: let (x,x) \in \mathbb{R} \implies |x-x|=0<1

\Rightarrow \mathbb{R} is Reflexive

Symmetric:

If (x,y) \in \mathbb{R} \implies |x-y| \le 1

and (y,x) \in \mathbb{R} \implies |y-x| \le 1 [Since |x-y|=|y-x|]

\Rightarrow \mathbb{R} is Symmetric

Transitive:

If (x,y) \in \mathbb{R} \Rightarrow |x-y| \le 1

and (y,z) \in \mathbb{R} \Rightarrow |y-z| \le 1

\Rightarrow |x-y|=|x-y+y-z|

\le |x-y|+|y-z| \le 1+1=2

\Rightarrow |x-z| \le 2

\therefore \mathbb{R} is not transitive
```

#### 28. (d) 0

Explanation: 
$$\sin^{-1}(1-x) - 2\sin^{-1}x = \frac{\pi}{2}$$
  
Now, we will put x = sin y in the given equation, and we get  
 $\sin^{-1}(1 - \sin y) - 2\sin^{-1}\sin y = \frac{\pi}{2}$   
 $\Rightarrow \sin^{-1}(1 - \sin y) - 2y = \frac{\pi}{2}$   
 $\Rightarrow \sin^{-1}(1 - \sin y) = \frac{\pi}{2} + 2y$   
 $\Rightarrow 1 - \sin y = \sin(\frac{\pi}{2} + 2y)$   
 $\Rightarrow 1 - \sin y = \cos 2y(as \sin(\frac{\pi}{2} + x)) = \cos x)$   
 $\Rightarrow 1 - \cos 2y = \sin y$   
 $\Rightarrow 2\sin 2y = \sin y$   
 $\Rightarrow 2\sin 2y = \sin y$   
 $\Rightarrow \sin y. (2\sin y - 1) = 0$   
 $\Rightarrow \sin y = 0 \text{ or } \sin y = \frac{1}{2}$   
 $\therefore x = 0 \text{ or } x = \frac{1}{2}$   
Now, if we put  $x = \frac{1}{2}$ , then we will see that,  
L.H.S.  $= \sin^{-1}(1 - \frac{1}{2}) - 2\sin^{-1}\frac{1}{2}$   
 $= -\sin^{-1}(\frac{1}{2}) - 2\sin^{-1}\frac{1}{2}$   
 $= -\sin^{-1}(\frac{1}{2}) - 2\sin^{-1}\frac{1}{2}$   
 $= -\frac{\pi}{6} \neq \frac{\pi}{2} \neq \text{R.H.S}$   
Hence,  $x = \frac{1}{2}$  is not the solution of the given equation.  
Thus,  $x = 0$ 

29. (c)  $\frac{1}{3} \begin{bmatrix} 1 & 1 \\ 2 & 1 \end{bmatrix}$ 

$$S \begin{bmatrix} 3 & 1 \end{bmatrix}$$
  
Explanation: A + B =  $\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$  ...(i)  
A - 2B =  $\begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix}$  ...(ii)  
adding 2 × (i) and (ii), we get  
2A + 2B =  $\begin{bmatrix} 2 & 0 \\ 2 & 2 \end{bmatrix}$  ...(iii)  
A - 2B =  $\begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix}$  ...(iv)  
adding (iii) and (iv), we get  

$$\Rightarrow 3A = \begin{bmatrix} 2 & 0 \\ 2 & 2 \end{bmatrix} + \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$\Rightarrow A = \frac{1}{3} \begin{bmatrix} 1 & 1 \\ 3 & 1 \end{bmatrix}$$

(b)  $\frac{1}{2}$ Explanation: Given that  $y = \tan^{-1}\left(\frac{1-\cos x}{\sin x}\right)$ Using 1 - cos x =  $2\sin^2 \frac{x}{2}$  and Using sin x =  $2\sin x \frac{x}{2}\cos \frac{x}{2}$ , we obtain  $y = \tan^{-1}\left(\frac{2\sin^2 \frac{x}{2}}{2\sin \frac{x}{2}\cos \frac{x}{2}}\right)$  or  $y = \tan^{-1}\tan \frac{x}{2}$   $x = \frac{x}{2}$ Differentiating with respect to x, we obtain  $\frac{dy}{dx} = \frac{1}{2}$ (c) f'(1<sup>−</sup>) = −1

31. **(c)** 
$$f'(1^-) = -1$$
  
**Explanation:** Given that  $f(x) = \begin{cases} -\log_e x, 0 < x < 1 \\ \log_e x, x \ge 1 \end{cases}$ 

Differentiability at x =1, LHD at x =1,  $\lim_{x \to 1^{-}} \frac{f(x) - f(1)}{x - 1} = \lim_{h \to 0} \frac{f(1 - h) - f(1)}{1 - h - 1}$   $= \lim_{h \to 0} \frac{\log 1 - h}{-h} = -1$ RHD at x =1,  $\lim_{x \to 1^{+}} \frac{f(x) - f(1)}{x - 1} = \lim_{h \to 0} \frac{f(1 + h) - f(1)}{1 + h - 1}$   $= \lim_{h \to 0} \frac{\log(1 + h)}{h} = 1$ So, f'(1<sup>+</sup>) = 1 and f'(1<sup>-</sup>) = -1

32. **(d)** 1

Explanation: 
$$y = \log \sqrt{\tan x}$$
  
 $\frac{dy}{dx} = \frac{1}{\sqrt{\tan x}} \times \frac{1}{2\sqrt{\tan x}} \sec^2 x$   
 $\frac{dy}{dx} = \frac{\sec^2 x}{2\tan x}$   
 $\left|\frac{dy}{dx}\right|_{x=\frac{\pi}{4}} = \frac{\sec^2 \frac{\pi}{4}}{\sqrt{\tan \frac{\pi}{4}}} = \frac{2}{2 \times 1} = 1$ 

33. **(d)** R

34. (c) 
$$-1 \le x < \frac{1}{\sqrt{2}}$$

**Explanation:** We have  $\cos^{-1}x > \sin^{-1}x$   $\Rightarrow \frac{\pi}{2} - \sin^{-1}x > \sin^{-1}x$   $\Rightarrow \frac{\pi}{2} > 2\sin^{-1}x$   $\Rightarrow \sin^{-1}x < \frac{\pi}{4} \dots (i)$ But  $-\frac{\pi}{2} \le \sin^{-1}x \le \frac{\pi}{2} \dots (ii)$ From (i) and (ii),  $-\frac{\pi}{2} \le \sin^{-1}x < \frac{\pi}{4}$   $\Rightarrow \sin(-\frac{\pi}{2}) \le x < \sin\frac{\pi}{4}$  $\Rightarrow -1 \le x < \frac{1}{\sqrt{2}}$ 

35. **(c)** makes an acute angle with x-axis

**Explanation:**  $y = 2x^7 + 3x + 5$   $\Rightarrow \frac{dy}{dx} = 14x^6 + 3$ Even power is always positive. Hence,  $\frac{dy}{dx} > 0$  $\tan \theta > 0$ 

Hence, tangent makes an acute angle with x-axis to the curve.

36. **(c)** Linear constraints

Explanation: In a LPP, the linear inequalities or restrictions on the variables are called Linear constraints.

37. **(a)**  $\frac{1}{k}$  . A<sup>-1</sup>

Explanation: by the property of inverse

 $(AB)^{-1} = B^{-1}A^{-1}$  $(KA)^{-1} = A^{-1}K^{-1}$  $= \frac{1}{K}A^{-1}$ 

38. **(b)** null matrix

Explanation: Only a null matrix can be symmetric as well as skew symmetric.

In Symmetric Matrix  $A^{T} = A$ ,

Skew Symmetric Matrix  $A^{T} = -A$ ,

Given that the matrix is satisfying both the properties. Therefore, Equating the RHS we get A = -A i.e, 2A = 0. Therefore A = 0, which is a null matrix.

39. (a)  $\frac{1}{2a}$ 

Explanation: 
$$\sqrt{x} + \sqrt{y} = \sqrt{a}$$
.....(1)  

$$\Rightarrow \frac{1}{2\sqrt{x}} + \frac{1}{2\sqrt{y}} \frac{dy}{dx} = 0$$

$$\Rightarrow \frac{dy}{dx} = -\frac{\sqrt{y}}{\sqrt{x}}$$
.....(2)
$$\Rightarrow \frac{d^2y}{dx^2} = -\frac{\sqrt{x}\frac{1}{2}y^{-\frac{1}{2}} \frac{dy}{dx} - \sqrt{y}\frac{1}{2}x^{-\frac{1}{2}}}{x}$$

$$= \frac{-\left(\frac{\sqrt{x}}{2\sqrt{y}}\left(-\frac{\sqrt{y}}{\sqrt{x}}\right) - \frac{\sqrt{y}}{2\sqrt{x}}\right)}{x}$$

$$= \frac{\sqrt{x} + \sqrt{y}}{2x\sqrt{x}} = \frac{\sqrt{a}}{2x\sqrt{x}} = \frac{\sqrt{a}}{2a\sqrt{a}} = \frac{1}{2a}$$

40. (d) neither one-one nor onto **Explanation:** Given that 
$$f : R \to R$$
 be a function where

$$f(x)=rac{x^2-8}{x^2+2}$$

Here, we can see that for negative as well as positive x we will get same value. So, it is not one-one.

$$y = f(x)$$

$$\Rightarrow y = \frac{x^2 - 8}{x^2 + 2}$$

$$\Rightarrow y(x^2 + 2) = (x^2 - 8)$$

$$\Rightarrow x^2(y - 1) = -2y - 8$$

$$\Rightarrow x = \sqrt{\frac{2y + 8}{1 - y}}$$
For y = 1, no x is defined.  
So, f is not onto.

SECTION – C

41. **(d)** 
$$4a = 3\beta$$
  
**Explanation:**  $\alpha = \tan^{-1}(\tan\frac{5\pi}{4})$   
 $\Rightarrow \alpha = \tan^{-1}(\tan(\pi + \frac{\pi}{4}))$   
 $\Rightarrow \alpha = \tan^{-1}(\tan(\pi - \frac{\pi}{4}))$   
 $\Rightarrow \alpha = \frac{\pi}{4}$   
and  
 $\beta = \tan^{-1}(\tan(\pi - \frac{2\pi}{3}))$   
 $\beta = \tan^{-1}(\tan(\frac{\pi}{3}))$   
 $\beta = \frac{\pi}{3}$   
 $4\alpha = 4 \times \frac{\pi}{4} = \pi$ ...(i)  
 $3\beta = 3 \times \frac{\pi}{3} = \pi$ ...(ii)  
From (i) and (ii)  
 $4\alpha = 3\beta$ .  
Which is the required solution.

#### 42. **(d)** 132

**Explanation:** Here , minimize Z = 3x + 4y ,

Corner points	Z = 3x + 4y
C( 0 ,38 )	132(Min.)
B ( 52 ,0)	156
D(44, 16)	196

The minimum value is 132

43. **(c)** m<sup>2</sup>y

**Explanation:**  $y = ae^{mx} + be^{-mx} \Rightarrow y_1 = ame^{mx} + (-m)be^{-mx} \Rightarrow y_2 = am^2e^{mx} + (m^2)be^{-mx} \Rightarrow y_2 = m^2(ae^{mx} + be^{-mx}) \Rightarrow y_2 = m^2y$ 

44. **(b)** -1

**Explanation:**  $f(x) = 2x^3 - 3x^2 - 12x + 5$   $\Rightarrow f'(x) = 6x^2 - 6x - 12$ For local maxima or minima we have f'(x) = 0  $6x^2 - 6x - 12 = 0$   $\Rightarrow x^2 - x - 2 = 0$   $\Rightarrow x = 2 \text{ or } x = -1$  f''(x) = 12x - 6 f''(2) = 18 > 0function has local minima at x = 2. f''(-1) = -18 < 0function has local maxima at x = -1.

- (a) an equivalence relation 45. Explanation: an equivalence relation Reflexivity: Let  $a \in R$ Then,  $aa = a^2 > 0$  $\Rightarrow (a,a) \in R orall a \in R$ So, S is reflexive on R. Symmetry: Let  $(a,b)\in S$ Then, (a, b) ∈ S  $\Rightarrow ab \geq 0$  $\Rightarrow$  ba  $\geq 0$  $\Rightarrow (b,a) \in S orall a, b \in R$ So, S is symmetric on R. Transitive: If  $(a,b), (b,c) \in S$  $\Rightarrow$  ac  $\geq$  0 [::  $b2 \geq$  0]  $\Rightarrow$   $(a,c) \in S$  for all a, b, c  $\in$  set R Hence,. S is an equivalence relation on R
- 46. **(d)**  $\frac{1}{3}t^2 + 20t + 1$ Explanation:  $\frac{1}{3}t^2 + 20t + 1$
- 47. (c) 376 miles/sec Explanation: 376 miles/sec
- 48. (d) 27 seconds Explanation: 27 seconds
- 49. (a) 21 Explanation: 21
- 50. (c)  $\frac{4}{3}$

Explanation:  $\frac{4}{3}$