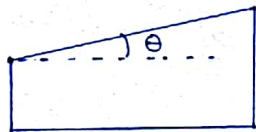
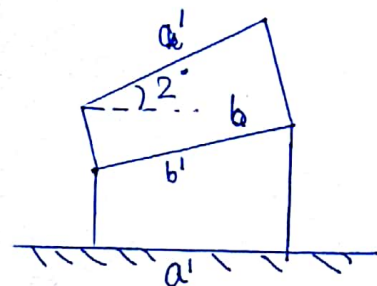
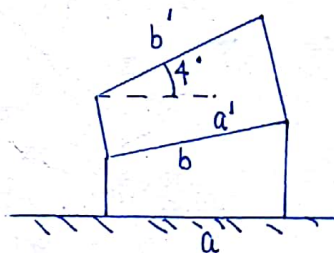
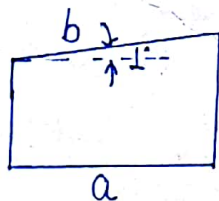


Angle Block :-

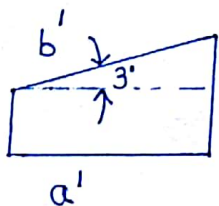


Deg's	1	3	9	27	45
Mins	1	3	9	27	
Fraction of min	0.05	0.1	0.3	0.5	

eg.



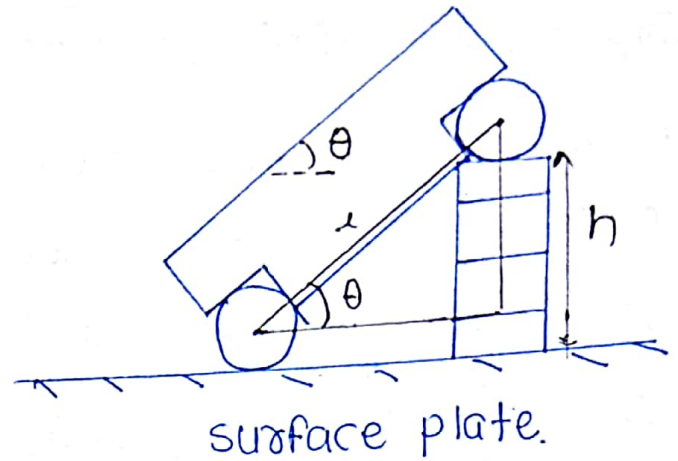
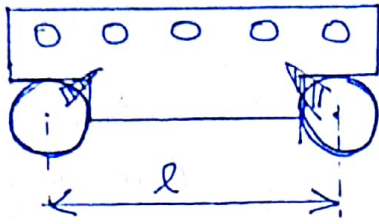
Surface plate



- * To add up the angles one plate surface and one inclined surface are working together.
- * To subtract angles both inclined surface should be working together.

Sine bar

Allen
screw



Two rollers of exact size are fixed to the body of sine bar through Allen screw. size of sine bar is define by the centre to centre distance between the rollers. Hole are made in the body of sine bar to make the assembly light.

$$\sin \theta = \frac{h}{l}$$

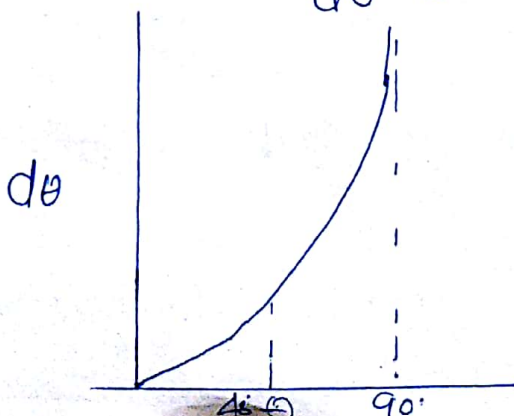
$$\cos \theta d\theta = \frac{l dh - h dl}{l^2}$$

$$\cos \theta d\theta = -\frac{h}{l} \cdot \frac{dl}{l}$$

$$d\theta = -\tan \theta \cdot \frac{dl}{l}$$

$dh \rightarrow 0$

Slip Gauge are very accurate



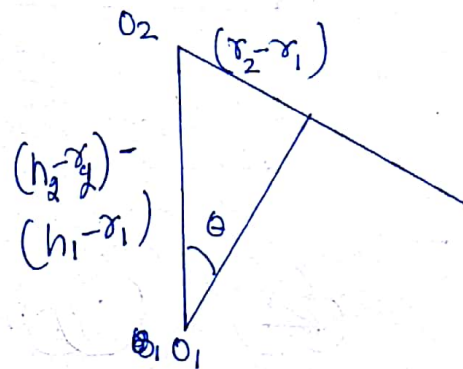
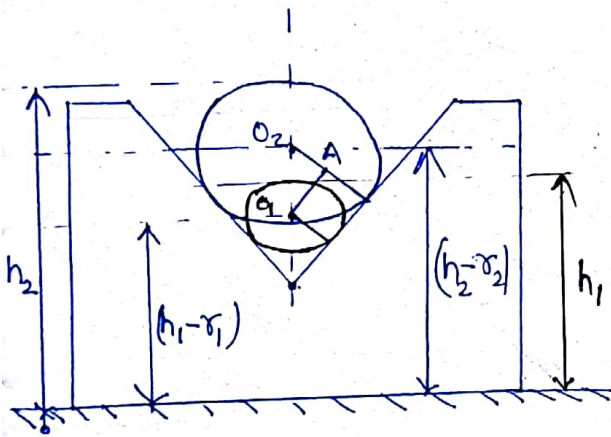
dh = tolerance sink of slip gauge

dl = error b/w centre to centre dist b/w rollers

$d\theta$ = error between angle measurement.

- * Since slip gauge are very accurate, dh will very significant compared to d .
- * Since the error is proportional to $\tan \theta$ when the Angle that has to be measured is more than 45° , the error will approach towards infinity. So Sine bar is not measure beyond 45° .

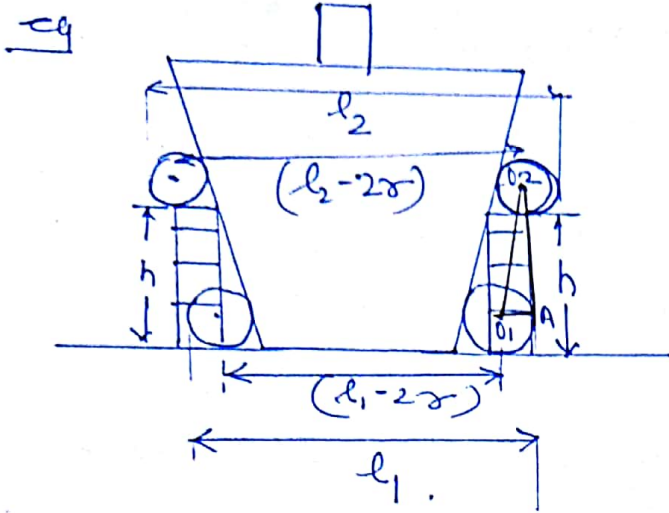
Precision ball measurement:-



$$\operatorname{Cosec} \theta = \frac{(h_2 - r_2) - (h_1 - r_1)}{r_2 - r_1}$$

$$\operatorname{Cosec} \theta = \frac{(h_2 - h_1)}{r_2 - r_1} - 1$$

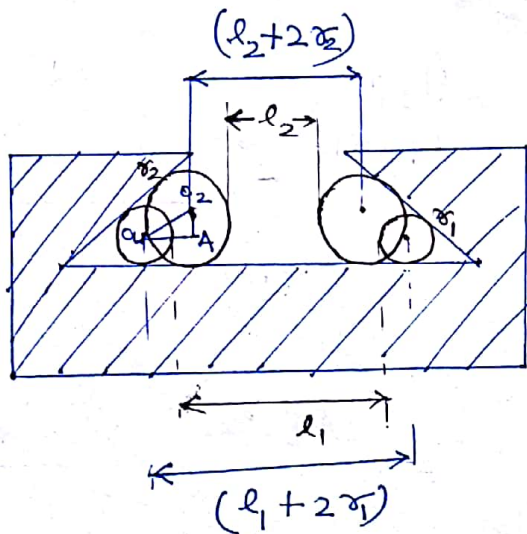
$$\boxed{\operatorname{Cosec} \theta = \frac{h_2 - h_1}{r_2 - r_1} - 1}$$



$$\frac{(l_2 - 2r) - (l_1 - 2r)}{2} = \frac{l_2 - l_1}{2}$$

$$\tan \theta = \frac{2h}{l_2 - l_1}$$

eq



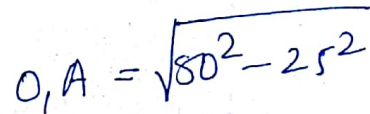
$$\frac{(l_1 + 2r_1) - (l_2 + 2r_2)}{2}$$

$$\cot \theta = \frac{\left(\frac{l_1 - l_2}{2}\right) + (r_1 - r_2)}{(r_2 - r_1)}$$

$$\cot \theta = \frac{l_1 - l_2}{2(r_2 - r_1)} - 1$$



$$H_1 = 35.55 \quad H_2 = 20.55$$



$$O_A = 43.30$$

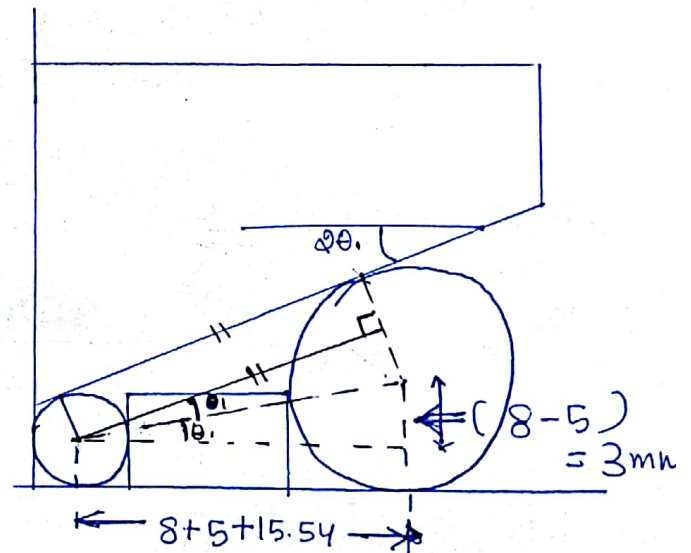
$$AO_2 = (H_1 + r_1) - (H_2 + r_2)$$
$$(35.55 + 30) - (20.55 + 20)$$
$$= 25$$

$$D = r_1 + r_2 + 0, A$$

$$b = 30 + 20 + 43.30$$

$$b = 93.30 \text{ mm}$$

Q. 49



$$\tan \theta = \frac{(r_2 - r_1)}{(r_1 + r_2 + h)}$$

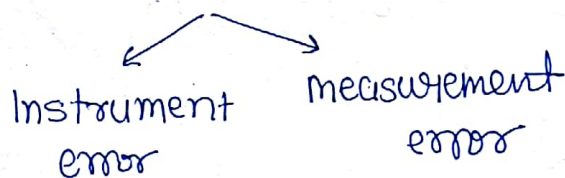
$$\tan \theta = \frac{3}{28.54} \Rightarrow \theta = 6$$

$Q\theta = 12^\circ$ Ans

Vernier Caliper Vs Micrometer

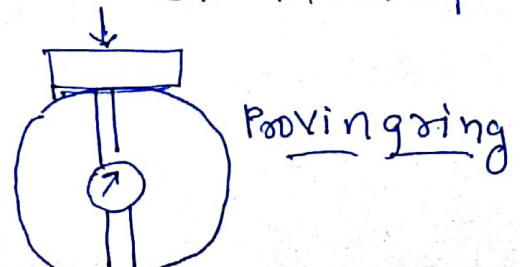
- * For any metrological equipment it is important that the plane of measurement doesn't change.
- * In vernier caliper Since Vernier Scale moving over the main scale so it an area Contact so reference plane keep on shifting. so it is an not accurate instrument.
- * In case of micrometer reference plane is well define with the help of balls. So it is ~~not~~ more accurate.

Types of errors:-

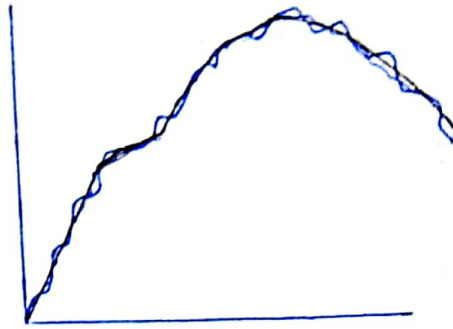


Instrument error:-

- ① System/Systematic error:- Since no two product are same so output of different instrument will also vary Called system error. This error can eliminated by calibrating the equipment.



② Short period error:-



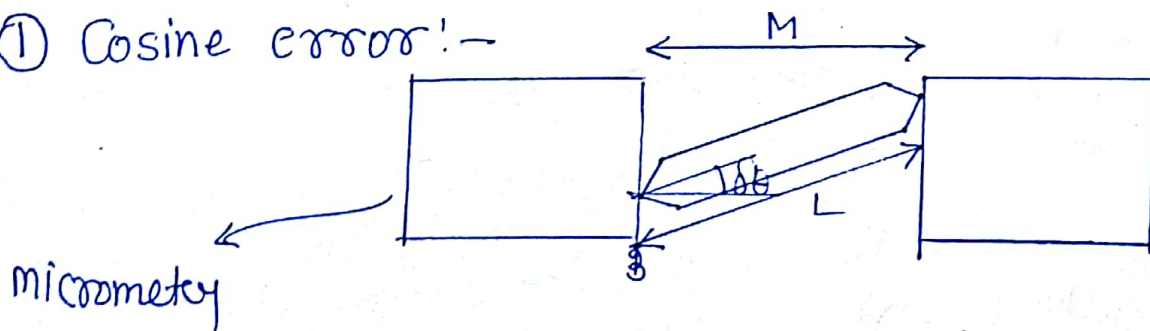
UTM बनाने वाली
ITW ← Company
Instron BISS

This type of error appears due to change in environmental condition. Like unexpected increase in temp of load cell, etc. These error can be taken care of by neglecting the data.

③ Erratic error: these errors occur during the maintenance of equipment. Some part of it are not properly fixed or tight ~~slightly~~ correctly.

Measurement error:-

① Cosine error:-

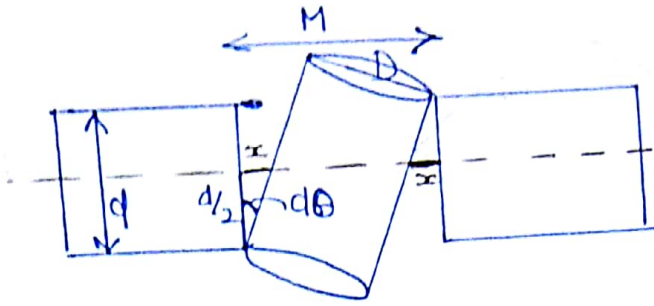


$$\text{error} = L - M = L - L \cos \theta$$

$$\theta \rightarrow 0 \quad \Rightarrow 0$$

This error can be neglected.

② Sine error :-



$$\text{error} = M - D \approx 2x$$

$$\frac{x}{d/2} = \tan \theta \approx \theta$$

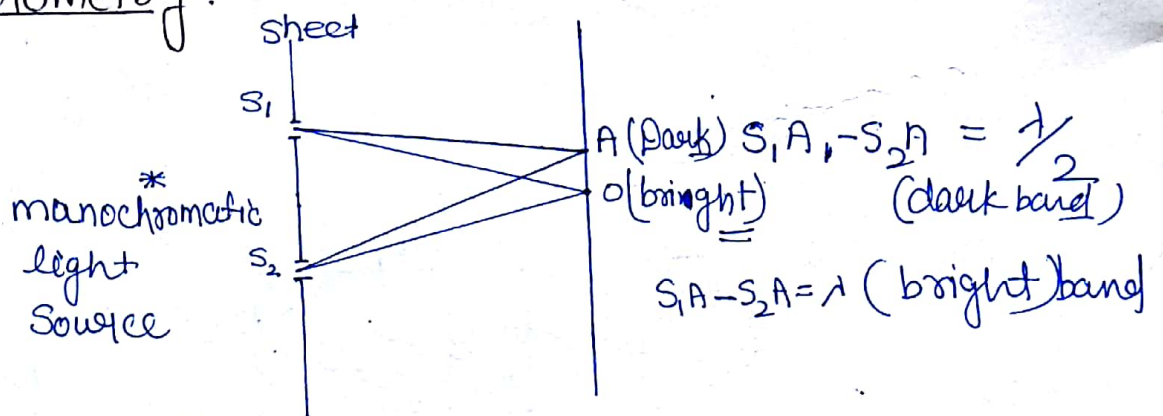
$$x = \frac{d}{2} \times \theta$$

$$\text{So error} = 2x$$

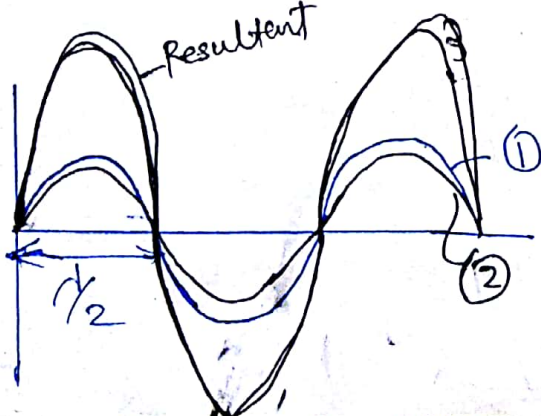
$$\boxed{\text{Error} = d \theta}$$

Can't be neglected
d-dia. of micrometer.

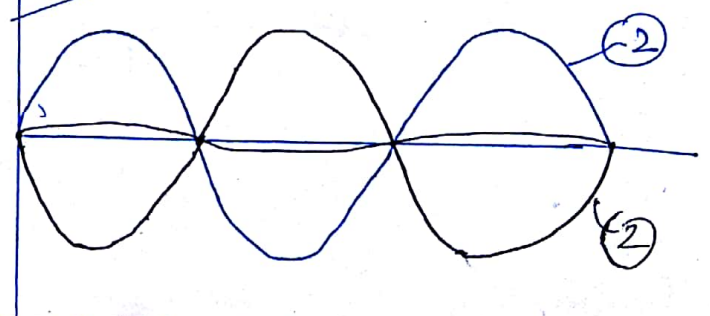
Interferometry :-



Constructive Interference
Bright



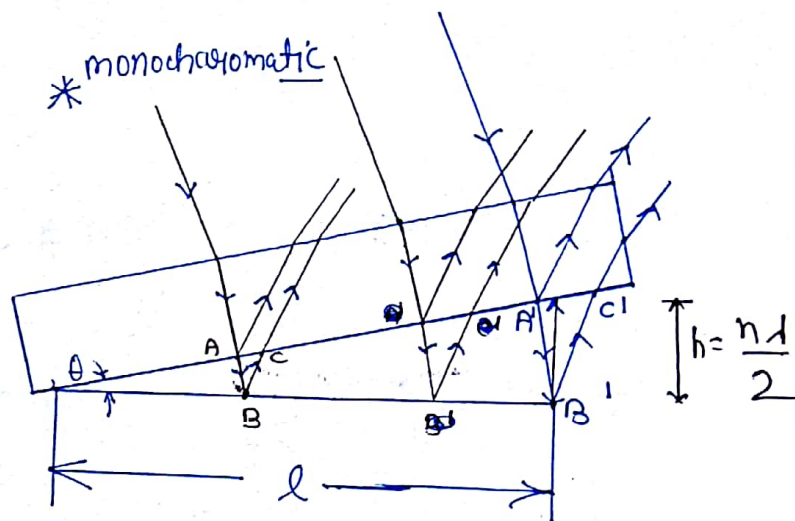
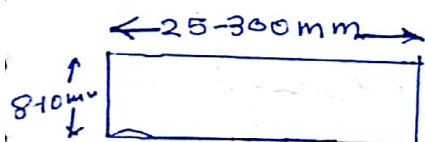
* Destructive Interference
Dark



* Every odd integer of $\lambda/2$ path difference leads to destructive interference and it produces a dark band on screen.

* Every even integer of $\lambda/2$ path difference leads to constructive interference and it produces a bright fringe on screen.
(white fringe)

Optical Flat



$$AB + BC = \text{Band Gap}$$

if 'n' no. of fringe are there

$$A'B' + B'C' = n\lambda$$

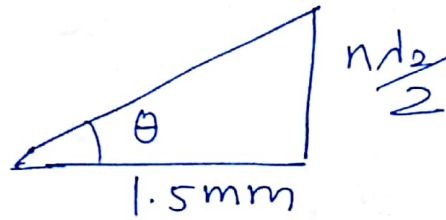
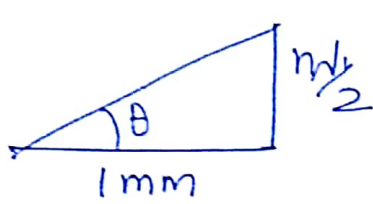
$$\theta \text{ is very small} \Rightarrow A'B' \approx B'C' \approx \frac{n\lambda}{2}$$

$$\tan \theta = \frac{A'B'}{l} = \frac{n\lambda}{2L}$$

$$\theta \approx \frac{n\lambda}{2L}$$

Problem

Fringe space $l_1 = 1 \text{ mm}$, $\lambda_1 = 450 \text{ nm}$
 $l_2 = 1.5 \text{ mm}$, $\lambda_2 = ?$



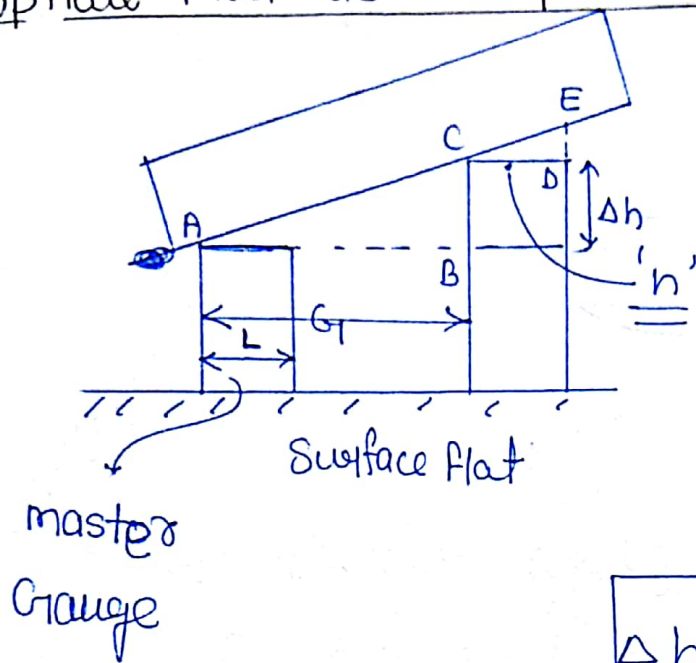
$$\theta_1 = \theta_2$$

$$\frac{n\lambda_1}{2l_1} = \frac{n\lambda_2}{2l_2}$$

$$\frac{450}{1} = \frac{\lambda_2}{1.5} \Rightarrow \underline{\lambda_2 = 675 \text{ nm}}$$

* Upon increasing the angle b/w surface and optical flat since the path diff. is quickly multiplied by $1/2$. So fringe become thinner & thinner so more no. of fringe will be accommodated in the same area. when the angle increase beyond a certain value, fringe are very thin that we are not able to recognize so fringe will disappear.

Optical Flat as comparator.



$\triangle CDE$ & $\triangle ABC$

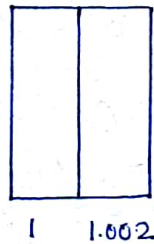
$$\frac{ED}{CB} = \frac{CD}{AB}$$

$$\frac{\left(\frac{n\lambda}{2}\right)}{\Delta h} = \frac{L}{G_1}$$

$$\Delta h = \left(\frac{n\lambda}{2}\right) \left(\frac{G_1}{L}\right)$$

Q.39

$L = G_1 = 10$



$(L = G_1)$

$$\Delta h = \frac{n\lambda}{2} \left(\frac{G_1}{L}\right)$$

$$\Delta h = \frac{n\lambda}{2}$$

$$n = \frac{2 \Delta h}{\lambda}$$

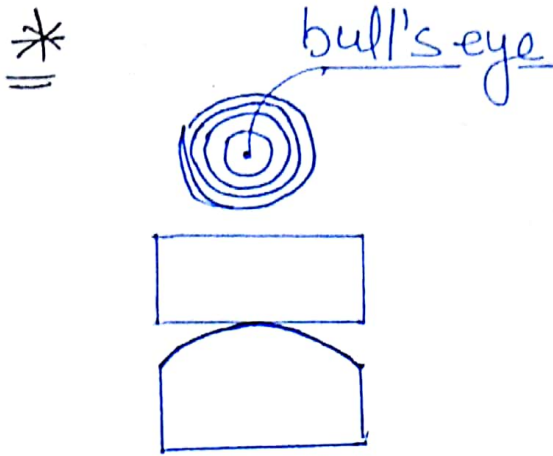
$$n = \frac{2 \times 0.002}{0.00058928}$$

$$n = 6.78$$

$$\text{So total} = 2n = 2 \times 6.78$$

$$= 13.8$$

$$\approx 13 \approx$$



* when optical flat kept over a convex surface center fringe will be dark called Bull's eye. The angle between the optical flat and surface keeps on increasing in outward direction so center fringes will be broad and fringe thickness keeps on decreasing in outward direction. Upon pressing the optical flat if it is a convex surface central fringe will always be dark and since angle b/w optical flat and surface keeps on decrease so fringe thickness keep on increase.

Straightness:- It is departure of any surface from ideal state line. after floating the surface characteristic state line is drawn by joining the first and last point. The maximum deviation of surface from this reference line is called straightness.



① Straight Edge:- straight edge is a piece of block one surface of which is straight. By keeping the straight edge over surface under examination if lesser intensity of light is coming from the interface it means surface is straight.

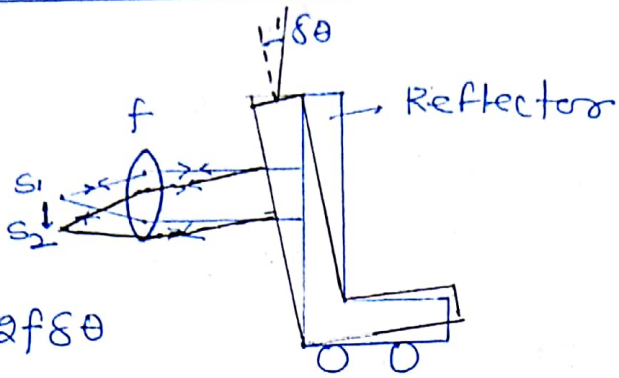
② Spirit level:- surface under examination is divided into segments with segment size is equal to the spirit level. By keeping the spirit level from segment to segment position of its bubble is noted down and surface character can be plotted.

③



Surface
Character

③ Autocollimeter: -

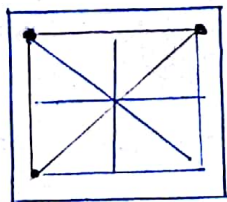


it is an expensive equipment

The reflector of Autocollimeter is moved over surface under examination and deviation of surface are recorded in terms of ΔS values and hence surface characteristic can be plotted on the paper

Flatness:- It is departure of any surface from a reference plane and when the surface is straight along infinite no. of line it is called flat. As

Autocollimeter is moved in three direction to identify three points. By these three point a reference plane defined in autocollimeter is know moved in all possible direction and departure of surface from this reference plane is noted down is called Flatness.



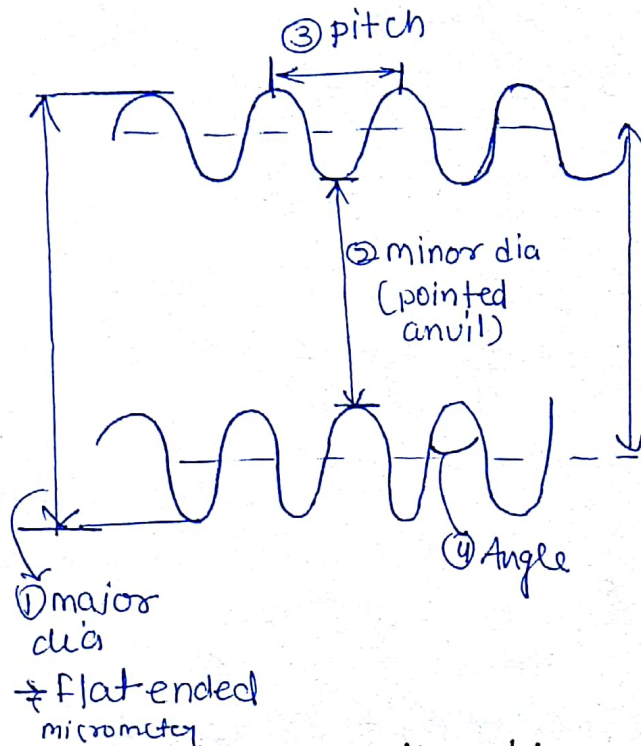
Q. 36

$$\frac{0.5}{50} = 0.01 \text{ mm}$$

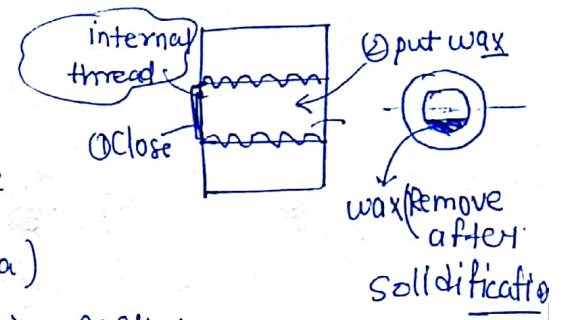
$$5 \times 0.5 + 12 \times 0.01 = 2.62 \text{ mm}$$

Q. 40

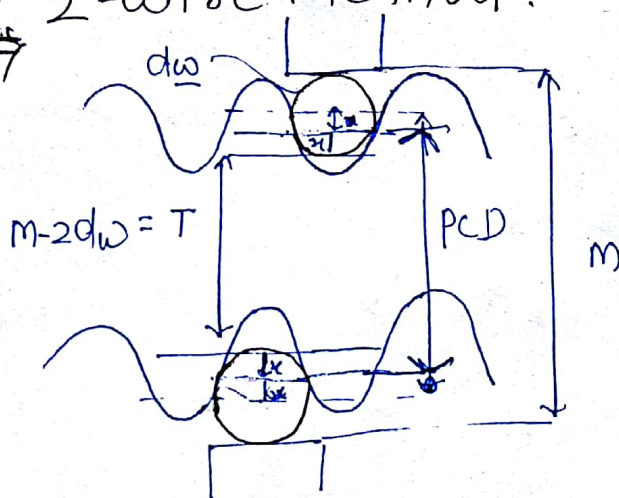
Screw thread metrology :-



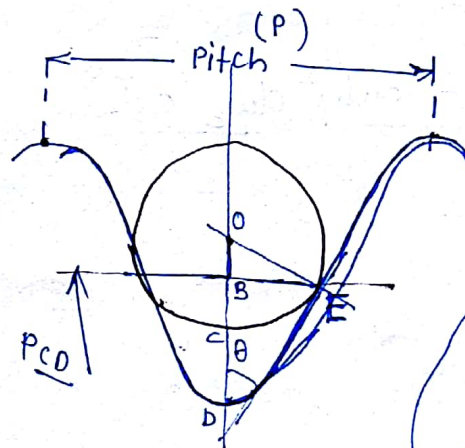
Pitch circle dia. (effective dia.)
↓
3 wire method



2-wire method :-



$$PCD = T + 2x$$



dw-wire diameter

$$x = BC$$

$$x = OC - OB$$

$$x = \frac{dw}{2} - OB$$

wire is not best size
So don't consider DOBE

Now $OB = OD - BD$

$\triangle ODE$

$$\frac{OE}{OD} = \sin \theta \Rightarrow \underline{OD} = \frac{dw}{2} \operatorname{cosec} \theta$$

$\triangle BDE$

$$\frac{BE}{BD} = \tan \theta \Rightarrow BD = \frac{P}{4} \cot \theta$$

So Now $OB = \frac{dw}{2} \operatorname{cosec} \theta - \frac{P}{4} \cot \theta$

So $x = \frac{dw}{2} - OB$

$$x = \frac{dw}{2} (1 - \operatorname{cosec} \theta) + \frac{P}{4} \tan \theta$$

So Pitch Circle

diameter $PCD = T + 2x$

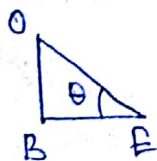
$$PCD = T + dw(1 - \operatorname{cosec} \theta) + \frac{P}{2} \tan \theta$$

In Ques if only dw_b ask

if it is Best Size ϕ wire

dia $\Rightarrow dw_b$

So consider $\triangle OBE$ right angle



$$\frac{\frac{P}{4}}{dw_b/2} = \cos \theta$$

$$\boxed{dw_b = \frac{P}{2} \sec \theta}$$

best size
wire diameter

Q. 34

$$P = 2 \text{ mm}$$

$$2\theta = 60^\circ \quad \underline{\underline{\theta = 30^\circ}}$$

$$d_w = \frac{P}{2} \sec \theta = \frac{2}{2} \sec 30^\circ$$

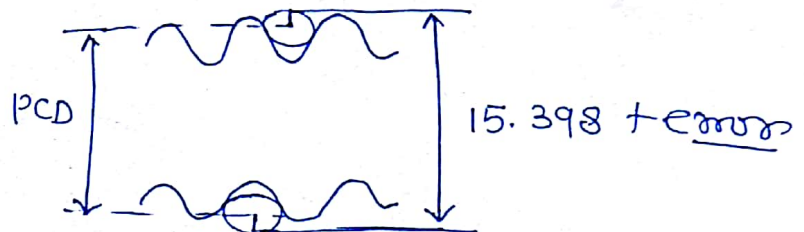
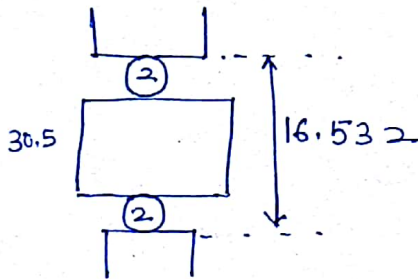
$$d_w = \frac{1}{\cos 30^\circ} = \frac{2}{\sqrt{3}} = 1.154 \text{ mm}$$

Q. 35

$$P = 3.5 \text{ mm}$$

$$d_w = 2 \text{ mm}$$

$$2\theta = 60^\circ \Rightarrow \theta = 30^\circ$$



$$\text{error} = 30.5 + 2 + 2 - 16.532$$

$$= 34.5 - 16.532$$

$$\underline{\text{Now}} \quad M = 15.398 + \text{error}$$

$$m = 33.366 \text{ mm}$$

$$\text{Error} = 17.968 \text{ mm}$$

$$\text{PCD} = 33.366$$

$$\text{PCD} = T + 2x$$

$$= M - 2d_w + d_w(1 - \cos \theta) + \frac{P}{2} \cot \theta$$

$$= 33.366 - 2(2) + 2(1 - \cos 30^\circ) + \frac{3.5}{2} \cot 30^\circ$$

$$= 33.366 - 4 - 2 + 3.0310889$$

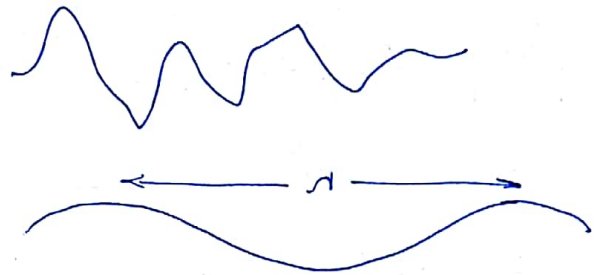
$$\underline{\underline{\text{PCD}}} = 30.397$$

Surface Finish:-

- Small wavelength deviation of surface are called Roughness
- Large wavelength deviation called waviness
- waviness appear in machiness component due to error in guide ways, machine vibration, chatter.
- Roughness appear due to improper selection of cutting parameter, improper selection of cutting fluids etc.



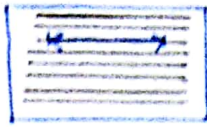
Roughness



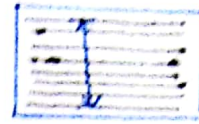
waviness

Flaw:- Flaw is highly localize and it may appear due to sudden change into cutting speed, some operator mistake, some localized impurities within the work.

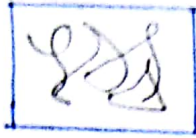
Lay:- It is the predominant surface pattern produce by feed marks



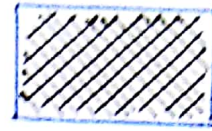
Parallel '||'
lay



Perpendicular '⊥'
lay



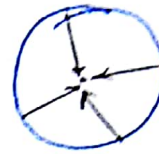
Multidirection 'M'
in Grinding there
is no predefined
direction



Crossed 'X'
lay
in knurling



Circular 'c'
lay
in facing

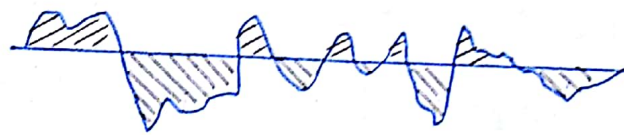


Radial lay 'R'
in slotting.

Establishing Datum:-

① M System:-

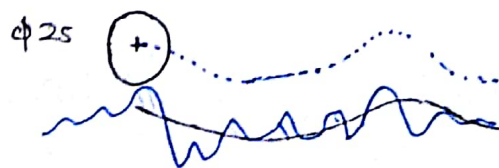
→ Mean line



After plotting surface characteristic straight line drawn by joining the ~~first~~ first point and last point. This line shifted to upward and downward dirⁿ to the plate when area below the line and area above the line are same called mean line.

② E-System:-

→ Envelope



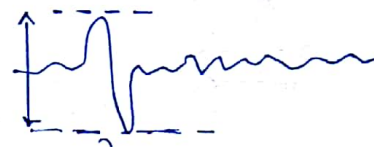
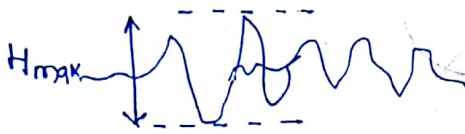
Sphere of $\phi 25$ mm is rolled over the surface of examination and the locus of its centre is being traced called envelope.

This envelope is lowered such that the area above the envelope and below the envelope are same.

* Envelope eliminates waviness from surface.

Measurement of surface Roughness

① Peak to Valley height:- (H_{max} , R_t , R_{max})



Sometimes it doesn't give good result

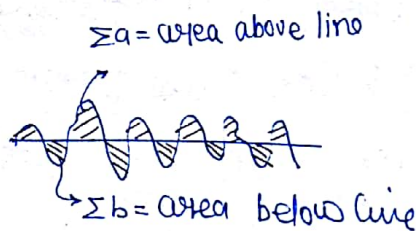
this is may be due to some fault.

It is the difference between highest peak and deepest valley. But some time it doesn't represent the surface characteristic properly.

② Centre line avg value (CLA), (R_a)

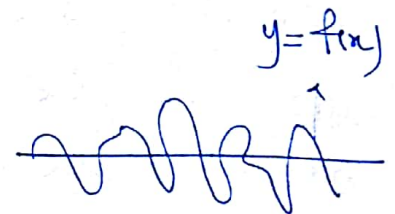


$$R_a = \frac{y_1 + y_2 + y_3 + y_4 + y_n}{n}$$



$$R_a = \frac{\Sigma a + \Sigma b}{L}$$

L = Cutoff length



$$R_a = \frac{1}{L} \int_0^L y dx$$

according to Mathematic.

$$H_{max} = \frac{f^2}{8R}$$

$$H_{max} = \frac{f}{\tan \psi + \cot \psi_1}$$

ψ - side cutting edge angle

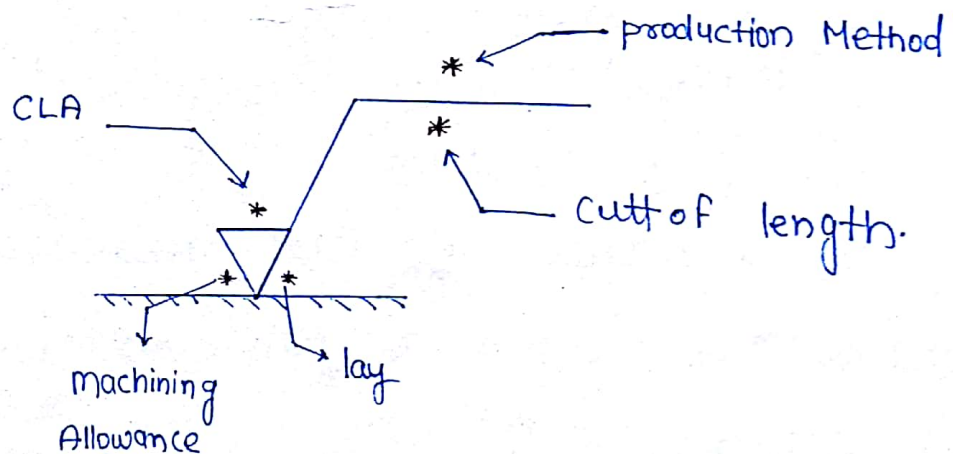
ψ_1 - end cutting edge angle

③ Root mean Square Value (RMS) (R_q)

$$R_q = \sqrt{\frac{y_1^2 + y_2^2 + y_3^2 + \dots + y_n^2}{n}}$$

④ 10 point Value (R_z) :- It is the average of 5 highest peak and 5 deepest valley's

★ Representation

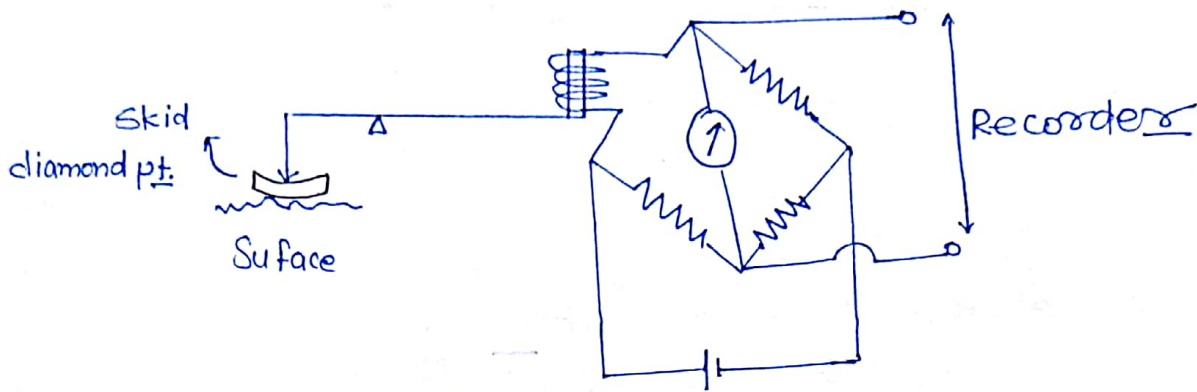


★



R_q 8-25 μs 1.6-8 μs 0.025 - 1.6 μs < 0.025 μs

Taly Surf :-



A diamond point is placed at one side of lever arm which moves over the hill down the valley through skid.

Skid. it a soft material ment to protect diamond point. As diamond point moving it changes the position of core in induction coil. This changes the effective resistance.

Since induction coil is connected to the 4th arm of wheat stone bridge so change in resistance can be measured in terms of flow of current. Hence Surface characteristics can be plotted.