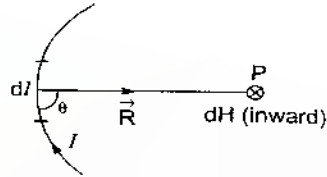


Magnetostatic Field

4

Biot-Savart's Law

The Biot-Savart's law states that the differential magnetic field intensity dH produced at a point P , by the differential current element Idl is proportional to the product Idl and the sine of the angle θ between the element and the line joining P to the element and is inversely proportional to the square of the distance R between P and the element.



$$dH \propto \frac{Idl \sin \alpha}{R^2} \text{ A/m}$$

$$dH = \frac{Idl \times a_r}{4\pi R^2} = \frac{Idl \times \vec{R}}{4\pi |\vec{R}|^3}$$

$$H = \oint \frac{Idl \times a_r}{4\pi R^2} \text{ A/m}$$

where, a_r = unit vector pointing from the different element of current to the point of interest.

Magnetic Field Intensity for Distributed Current Source

(i) Line current

$$\vec{H} = \int_L \frac{Idl \times a_r}{4\pi R^2}$$

(ii) Surface current

$$\vec{H} = \int_s \frac{K \cdot dS \times a_r}{4\pi R^2}$$

where, K = surface current density

(ii) Volume current

$$\vec{H} = \int_v \frac{J \cdot dV \times a_r}{4\pi R^2}$$

where, J = volume current density

Magnetic field intensity due to straight current carrying filamentary conductor

(i) Finite length AB

$$\vec{H} = \frac{I}{4\pi \rho} (\cos \alpha_2 - \cos \alpha_1) a_\phi$$

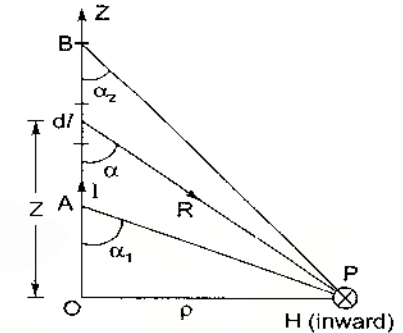
(ii) Semi-infinite length

$$\vec{H} = \frac{I}{4\pi \rho} a_\phi$$

(iii) Infinite length

$$\vec{H} = \frac{I}{2\pi \rho} a_\phi$$

$$a_\phi = a_l \times a_\rho$$



where, a_l is unit vector along the line current and a_ρ is unit vector along the perpendicular line from the line current to the field point.

Ampere's Circuit Law

The closed line integral of static magnetic field intensity \vec{H} , integrated over any closed curve 'C' is always equal to total current enclosed within the closed curve 'C'.

$$\oint \vec{H} \cdot d\vec{l} = I_{enc} \text{ A}$$

$$\oint \vec{H} \cdot d\vec{l} = \iiint \vec{J} \cdot d\vec{S} \text{ Ampere's circuit law in the integral form}$$

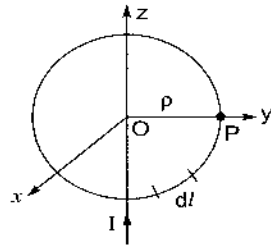
- The Curl of static magnetic field intensity \vec{H} at any point in the electromagnetic region is equal to volume current density \vec{J} present at that point.

$$\nabla \times \vec{H} = \vec{J} \text{ Ampere's circuit law in point form of differential form}$$

Note:

- $\nabla \times \vec{H} = \vec{J}$ is the also known as Maxwell's third equation.
- Ampere's circuit law is applicable irrespective of shape of the closed curve 'C'.
- The magnetostatic field is not conservative as $\nabla \times H = J \neq 0$.

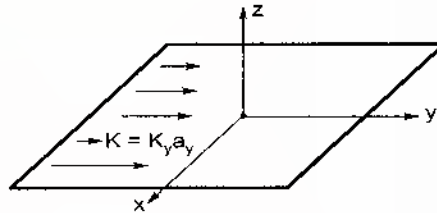
Magnetic Field Intensity Due to Infinite Line Current



$$\vec{H} = \frac{1}{2\pi\rho} a_\phi$$

Magnetic Field Intensity Due to Infinite Sheet of Current

$$\vec{H} = \frac{1}{2} \vec{K} \times a_n$$



where, a_n = Unit normal
 K = uniform current density

$$H = \begin{cases} \frac{1}{2} K_y a_x; & z > 0 \\ -\frac{1}{2} K_y a_x; & z < 0 \end{cases}$$

Magnetic Flux Density

$$\vec{B} = \mu_0 \vec{H} \text{ Wb/m}^2$$

where, μ_0 = permeability of free space.

Magnetic flux through a surface S

$$\psi = \int_S \vec{B} \cdot d\vec{S} \text{ Wb}$$

Remember:

- An isolated magnetic charge does not exist. Thus the total flux through a closed surface in a magnetic field must be zero.

$$\oint \vec{B} \cdot d\vec{S} = 0$$

Maxwell's fourth equation: $\nabla \cdot \vec{B} = 0$

Magnetic Energy Density (W_m)

The magnetic energy density represents magnetic energy stored at a point in the electro magnetic region and gives total magnetic energy per unit volume of the given configuration.

$$W_m = \frac{1}{2} \mu H^2 = \frac{1}{2} \vec{B} \cdot \vec{H}$$

Magnetic Energy

$$W_m = \iiint_V W_m dV = \frac{1}{2} L I^2 \text{ Joule}$$

Remember:

The magnetic energy density depends upon

- Magnetic field due to given current distribution in the configuration.
- Permeability of the magnetic medium.

Magnetic Scalar and Vector Potentials

The magnetic potential could be scalar V_m or vector \vec{A}

Magnetic scalar potential (V_m)

The magnetic scalar potential is only defined in a region where $J = 0$.

$$\vec{H} = -\nabla V_m$$

Vector Magnetic Potential \vec{A}

$$\vec{B} = \nabla \times \vec{A}$$

For line current

$$A = \int \frac{\mu_0 I dl}{4\pi R} \text{ Wb/m}$$

For surface current

$$A = \int_S \frac{\mu_0 K dS}{4\pi R}$$

For volume current

$$A = \int_V \frac{\mu_0 J dV}{4\pi R}$$

Remember:

Important identities which must always hold for any scalar field V and vector field \vec{A} .

$$\nabla \times (\nabla V) = 0 \quad \text{and} \quad \nabla \cdot (\nabla \times \vec{A}) = 0$$

Forces Due to Magnetic Field**Force on a Charged Particle**

(i) Magnetic force

$$\vec{F}_m = Q(\vec{u} \times \vec{B}) \quad \text{Newton}$$

where, u = Velocity of moving charge Q

B = Magnetic field

(ii) Electric force

$$\vec{F}_e = Q\vec{E}$$

where, Q = electric charge ; E = electric field intensity

Lorentz force equation

For a moving charge Q in the presence of both electric and magnetic fields

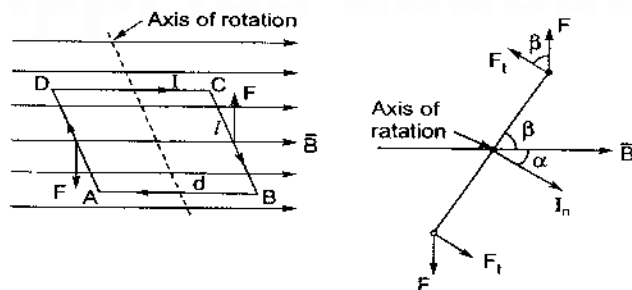
$$\vec{F} = \vec{F}_e + \vec{F}_m = Q(\vec{E} + \vec{u} \times \vec{B})$$

Force on a Current Element**Force on a current carrying conductor**

The magnetic field is defined as the force per unit current element.

$$\vec{F} = \oint I d\vec{l} \times \vec{B}$$

where $I d\vec{l}$ = Current element of current carrying conductor

Magnetic Torque and Magnetic Moment**Magnetic Torque**

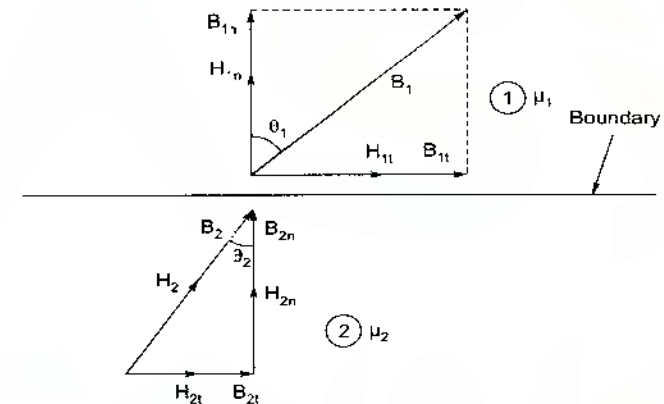
$$T = BIS \sin \alpha$$

where, S = area of the loop

$$\vec{T} = \vec{m} \times \vec{B}$$

Magnetic Dipole Moment

$$\vec{m} = IS\vec{i}_n$$

Magnetic Boundary Conditions**Tangential component relation**

$$\vec{H}_{1t} = \vec{H}_{2t} \quad \text{or} \quad \frac{\vec{B}_{1t}}{\mu_1} = \frac{\vec{B}_{2t}}{\mu_2}$$

Normal component relation

$$\vec{B}_{1n} = \vec{B}_{2n} \quad \text{or} \quad \mu_1 \vec{H}_{1n} = \mu_2 \vec{H}_{2n}$$

Remember:

- The tangential component of H is continuous while that of B is discontinuous at boundary.
- The normal component of B is continuous while that of H is discontinuous at boundary.

$$\frac{\tan \theta_1}{\tan \theta_2} = \frac{\mu_1}{\mu_2}$$