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> 14. A mass of 1 kg attached to the bottom of a spring has certain frequency of vibration. What mass is to be added in order to reduce the frequency by half?

- (A) 1 kg
- (B) 2 kg
- (C) 3 kg

15. A pendulum suspended from the ceiling of a compartment of a train has periodic time 2 s. When the train is accelerating at 10 ms⁻². What will be its time period when the train retards at 10 m s⁻².

- (A) 2 s

- (B) $\sqrt{2}$ s (C) $2\sqrt{2}$ s (D) $\frac{2}{\sqrt{2}}$ s

ANSWERS

- **1.** (B) **2.** (A) **3.** (D) **4.** (C) **5.** (B) **6.** (C)
- **8.** (A) **9.** (C) 7. (C) **10.** (B) **11.** (B) **12.** (D)
- **14.** (C) **13.** (D) **15.** (A)

Answer the following questions in short:

- 1. What is the work done by simple pendulum in one complete oscillation?
- What is the periodic time of a pendulum in freely falling lift? 2.
- Write equation for peiodic time of oscillation of the liquid in U-tube. 3.
- What is an epoch? In which unit it is measured? 4.
- Amplitude of an SHO is 4 cm. At what distance from the equilibrium position, 5. the kinetic energy and potential energy becomes equal?
- **6.** What is the SI unit of force constant?
- 7. Write the relation between the acceleration amplitude (a), the displacement amplitude (A) and the angular frequency (ω) for SHM.
- 8. Why does a simple pendulum eventually stop?
- 9. Write expression of the mechanical energy of damped harmonic oscillation for $b \ll \sqrt{km}$.
- 10. Write general form of the second order differential equation for forced oscillation.

Answer the following questions:

- 1. Define periodic motion and oscillatory motion. Give proper examples of it.
- 2. Deduce an expression for the time period of a simple pendulum.
- What are damped oscillations? What are the factors affecting its motion? 3.
- Deduce the relation for the total energy of damped harmonic oscillator. 4.
- 5. Explain forced oscillations and resonance.
- Show that for a particle in linear SHM the average KE over a period of 6. oscillation equals the average PE over the same period.

Obtain the co-ordinates of the points where the KE and PE against displacement graphs intersect.

- **8.** What is the nature of acceleration against displacement curve of SHM? What is the slope of this curve?
- 9. Periodic time of the particle excluding SHM is $T = 2\pi \sqrt{\frac{m}{k}}$. Explain why then the periodic time of a simple pendulum is independent of a mass of the pendulum?
- **10.** What provides the restoring force for simple harmonic oscillator in the following cases ?
 - (i) Simple pendulum (ii) Spring (iii) Column of mercury in U-tube.

Solve the following problems:

1. Obtain the equation for SHM of the Y-projection of the radius vector of the revolving particle P in case (a) and (b) of Figure 7.22.

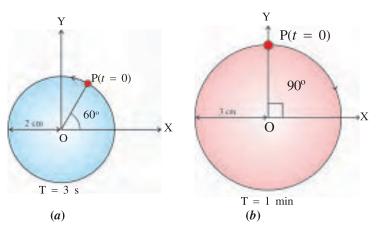


Figure 7.22

[Ans.: (a)
$$y = 2 \sin\left(\frac{2\pi t}{3} + \frac{\pi}{3}\right)$$
 (b) $y = 3 \cos\left(\frac{\pi}{30}t\right)$]

2. Three springs are connected to a mass m = 80 g as shown in Figure 7.23. What is the effective spring content and periodic time, if k = 2 N m⁻¹?

[Ans. :
$$k = 8 \text{ Nm}^{-1}$$
, T = 0.628 s]

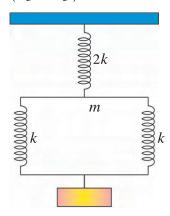


Figure 7.23

3. A spring of length l and force constant k is cut into two parts of length l_1 and l_2 . Here $l_1 = nl_2$. Obtain force constants k_1 and k_2 respectively of these parts in terms of n and k. [Ans.: $k_1 = \left(1 + \frac{1}{n}\right)k$, $k_2 = (n+1)k$]

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4. An oscillator of mass $100 \ g$ is performing damped oscillations. Its amplitude becomes half of its initial amplitude after $100 \ \text{oscillations}$. If its period is $2 \ \text{s}$ find the damping co-efficient. [Ans.: $0.693 \ dyn \ \text{s} \ \text{cm}^{-1}$]

- 5. Amplitude of an SHO is A. When it is at a distance y from the mean position of the path of its oscillation, the SHO receives blow in the direction of its motion which doubles its velocity instantaneously. Find the new amplitude of its oscillations.

 [Ans.: $\sqrt{4A^2 3y^2}$]
- 6. For an SHM prove that $a^2T^2 + 4\pi^2v^2 = \text{constant}$, where a and v are acceleration and velocity respectively at any instant. T is periodic time.
- 7. A simple pendulum has a length L and a bob of mass m. The bob is oscillating with amplitude A. Show that the maximum tension (T) in the string is (for small angular displacement). $T_{max} = mg \left[1 + \left(\frac{A}{L} \right)^2 \right]$.
- 8. Two simple harmonic motions are represented by $y_1 = 10 \sin \frac{\pi}{4} (12t + 1)$ and $y_2 = 5(\sin 3\pi t + \sqrt{3}\cos 3\pi t)$. Find out the ratio of their amplitudes. What are the time period of two motions? [Ans.: $\frac{A_1}{A_2} = 1$, $T_1 = T_2 = \frac{2}{3}$ s]
- 9. For a linear harmonic oscillator the force constant is 2×10^6 N/m and total mechanical energy is 160 J. At some instant of time, its displacement is 0.01 m. Find its potential energy and kinetic energy at this position.

10. For a linear SHM, when the distance of the oscillator from the equilibrium postion has values y_1 and y_2 , the velocities are v_1 and v_2 . Show that the time

period of oscillation is
$$T = 2\pi \left[\frac{y_2^2 - y_1^2}{v_1^2 - v_2^2} \right]^{\frac{1}{2}}$$
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CHAPTER 8

WAVES

- **8.1** Introduction
- 8.2 Waves
- **8.3** Classification of Waves
- 8.4 Amplitude of a Wave,
 Propagation of Energy in a
 Wave, Wavelength and
 Frequency
- **8.5** Wave Equation
- 8.6 Wave Speed and Phase Speed
- **8.7** Wave Speed in Medium
- **8.8** Superposition Principle and Reflection of the Wave
- **8.9** Stationary Waves
- **8.10** Stationary Waves in a Pipe
- **8.11** Beat
- 8.12 Doppler Effect
 - Summary
 - Exercises

8.1 Introduction

Friends, earlier we have studied that the universe is made up of matter and radiation. This radiation propagates in the form of waves. Waves have basic importance in almost every branch of physics. Light and sound energy also propagate in the form of waves. Different types of radiant energy emitting from the sun also reaches us in the form of waves. Music produced from musical instruments also reaches us in the form of waves. Communication done through radio, television and mobile is due to the waves. In 20th century, concept of matter wave was introduced due to which importance of the waves also increase.

In this chapter we will learn about waves, types of waves, speed of waves in different medium, reflection of waves, superposition of waves, beats and Doppler effect.

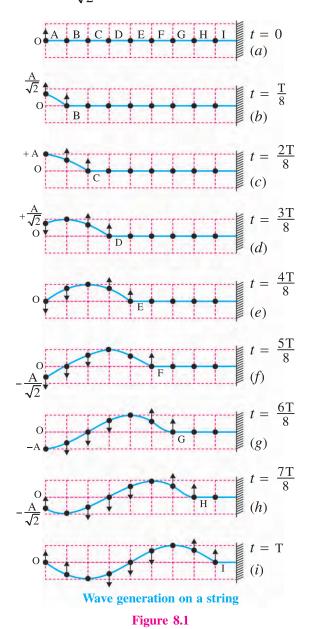
8.2 Waves

When a particle moves in space it carries the kinetic energy associated with it. There is another way to transport energy in which the particle oscillates near its position and yet the energy reaches too far from it. They transport their associated energy to the far distance without leaving their position. Sound is transmitted in air in this manner. When you say 'Hello' to your friend, no material particle is ejected from your lips and reaches to your friend's ear. You create some disturbance in the air close to your lips which propagates as a wave and reaches to ear of your friend.

To understand clearly the concept of a wave, consider a long and elastic string with one end fixed to rigid support and other held by a person. The person pulls on the string keeping it tight. Here, string is a one dimensional elastic medium. As shown in Figure 8.1, suppose that A, B, C, I are the particles of a string. At time t = 0 all the particles of the medium are in the equilibrium state. (See Figure 8.1*a*)

- (i) Suppose, at t = 0 a disturbance is produced by the person in the particle A so that it starts simple periodic motion according to $y = A \sin \omega t$. The period of this oscillation is T.
- (ii) Because of elastic property of the medium, suppose the effect of disturbance produced at A is transmitted to particle B

in time $\frac{T}{8}$. During this time $\frac{T}{8}$, the displacement of a particle A would be $y = A\sin\left(\frac{2\pi}{T}\right)\left(\frac{T}{8}\right) =$ $\frac{A}{\sqrt{2}}$ and particle B is on the verge of starting its simple periodic oscillation, (See Figure 8.1 b) (iii) Now, during an additional time period of $\frac{T}{8}$, that is at $\frac{T}{8} + \frac{T}{8} = \frac{T}{4}$, the disturbance is on the verge of starting its oscillation. During this time $\frac{T}{4}$, the displacement of particle A would be $y = A\sin\left(\frac{2\pi}{T}\right)\left(\frac{T}{4}\right) = A$ i.e. Displacement of A is equal to its amplitude and that of B is equal to $\frac{A}{\sqrt{2}}$. (See Figure 8.1(c)).



is like a sine curve. If the displacement or oscillation of particle A had been of some other type, the shape formed in the string would also have been accordingly of the other type. Thus, the shape formed in the string gives an idea of the type of disturbance. For example, if the free end of the string snappad one, then the shape

(iv) Thus, due to the disturbance produced at A, the subsequent particles start oscillations

(v) In this way the propagating disturbance

and transmit the effect of their oscillation to the subsequent particles and the disturbance

reaches the particle D at $t = \frac{3T}{8}$, the particle E

at $\frac{4T}{8}$ and the particle I at time T. At time

T one oscillation of A is completed and the par-

in the equilibrium position. At time t = 0, we

produced a simple periodic disturbance at the particle A. This disturbance has travelled in the medium and reached the particle I at time t = T.

This entire situation is shown in Figure 8.1. Remember that the particles of the medium were

(vi) Here, disturbance considered is such that it produces a simple periodic motion in the particle A and hence the shape produced in the string

ticle I is just to start its oscillation.

propagates in the medium.

formed in string is shown in Figure 8.2, which is known as a pulse.



Shape formed on the string according to the type of disturbance

Figure 8.2

As the time elapses this disturbance (or shape in the string) passes over the particles J, K, L,.... etc. Here, the shape is that of the sine curve is lying between the particles A and I at time t = T. This shape proceeds further along the string and comes between particles I and Q at time t = 2T as shown in Figure 8.3. During this time the particles between A and I stop oscillating and string comes back to its original position.



Shape of the string at t = 2TFigure 8.3

Thus, by producing a disturbance at any particle in the string, a shape corresponding to the disturbance is produced and that shape (without alteration) moves along the string, which means that the disturbance propagates in the medium of the string. The motion of the disturbance in the medium (or in free space) is called a wave disturbance or generally a wave.

Remember that here the particles of the string A, B, C... are not moving as a 'single unit' in the medium but they only displace or oscillate about their equilibrium positions. Thus, wave is not physical 'body' travelling in the medium. As the effect of disturbance produced in any part of the medium is being experienced by the subsequent particles of the medium, the wave is said to propagate. After the disturbance has passed through any particle, it comes back to its equilibrium position.

When the engine of a railway train joins the coaches, in the beginning the first coach vibrates, then the second coach and then the third coach and so on. Thus, the effect of vibration moves from the first to the last coach. This phenomenon is the propagation of the wave in the medium 'made up of railway coaches.'

Wavetrain

In the above discussion, if the particle continues to oscillate in its simple harmonic motion, the second waveform generated after the first one follows it and so on. Thus, a series of waveform appears to move ahead as a continuous chain. Such a series of propagating waveform is called a wave train.

We discussed a situation in which particles participating in wavemotion are executing a simple harmonic oscillation, here the wave shape formed in medium is of the nature of a sine (or equivalent cosine) curve. Such a wave is called a harmonic wave.

If the waves are continuously moving ahead in the medium, they are called **travelling or progressive waves.**

8.3 Classification of Waves

- (i) Mechanical waves: The waves which require elastic medium for their transmission are called mechanical waves. Such a wave propagates due to the elastic properties of the medium. For example, waves on a string, ripples on the water suface, sound waves and seismic waves. All these waves have the characteristics that they are governed by Newton's laws.
- (ii) Electromagnetic waves: For the propagation of electromagnetic waves no material medium is essential. They can propagate in the vacuum also. In this types of waves the disturbance in the electric and magnetic fields that propagates. Here, instead of particles, the vectors of the electric and magnetic field intensities are oscillating.

Light waves, radio waves, microwave, X-ray etc. are the examples of the electromagnetic waves. (More information you will get in Std. 12)

(iii) Matter waves: Matter waves are associated with moving electrons, protons, neutrons and other fundamental particles and even atoms and molecules. These particles constituting matter, therefore, such waves are called matter waves. The concept of these types of wave you will learn in Std. 12. From the concept of these waves scientific instruments are developed in modern technology. The matter waves associated with electron are employed in the electron microscope.

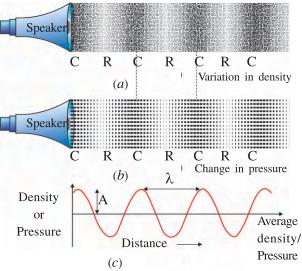
In this chapter we will study only the mechanical waves.

Transverse wave: Waves in which the oscillations of the particles are in a direction perpendicular to the direction of wave propagation is called the **transverse wave**. The waves along a string discussed in article 8.2 is an example of transverse wave. Electromagnetic waves (e.g. light waves) are also a transverse waves. In such waves the locations of the maximum displacement of the particle in one direction are called the 'crests' and locations of maximum displacement in the opposite direction are called 'trough'.

These waves propagate through a medium in the form of crests and troughs.

Longitudinal wave: Waves in which the oscillations of the particles of medium are along the direction of wave propagation are called longitudinal waves. Sound waves propagating in air are longitudinal. Such waves propagate through a medium by forming condensations and rarefaction in the medium. When waves propagate in medium, the particles at medium oscillate about their equilibrium position, in the direction of propagation of waves.

For simplicity, the positions of the particles of air at some instant of time in case of longitudinal waves is shown in Figure 8.4.



Longitudinal wave in air Figure 8.4

When sound waves pass through that region of air, the air molecules in certain region are pushed very close to each other during their oscillations. Hence, both density and pressure of air increase in such regions. In such region condensation is said to be formed. In the regions between consecutive condensations, the air molecules are found to be quite separated. In such regions density and pressure of air decreases and here rarefaction is said to be formed. (See Figure 8.4)

Thus, during the propagation of sound the layers of medium perform oscillation about their mean positions and during this the condensations and rarefactions are alternatingly formed. As the effect of such oscillations reaches one layer after the other, the condensations and rarefactions

propagate further and further in the medium. In this way the sound propagates in a medium. During the propagation of sound the pressure in different region of the medium changes with time and position. Hence, such waves are also called the **pressure waves.**

The direction of the oscillations of the particles of the medium is perpendicular to the direction of propagation of transverse waves in the medium. Hence during the propagation of the transverse waves every element of the medium experience shearing strain. But shearing stress is possible only in solid medium. So, the transverse waves can propagate in solid medium like string, wire, rod but they cannot propagate in a fluid medium.

During the propagation of the longitudinal waves, the oscillations of the particles of the medium are in the direction of propagation of the waves. Hence, compressive strain is produced during the propagation of these waves. Now, compressive stress is possible in solids, liquids and gases. So, the longitudinal waves can propagate in any medium.

Thus, in a solid medium both types of mechanical waves, transverse waves and longitudinal waves can propagate whereas in a fluid medium only longitudinal waves can propagate.

[During an earthquake two types of waves, transverse and longitudinal are produced on the earth. They are known as S-wave (secondary wave) and P-wave (primary wave) respectively. Longitudinal wave (P-wave) is similar to sound waves produced in the earth's interior. The speed of P-wave is approximately 4 – 8 km/s and that of S-wave is approximately 2 – 5 km/s. In an S-wave, particles in the earth's interior vibarate at right angles to the direction of the wave propagation. By measuring the time interval between the first arrivals of P-wave and S-wave, the origin of earthquake (epicentre) can be determined.

8.4 Amplitude of A Wave, Propagation of Energy in a Wave, Wavelength And Frequency

Amplitude of a wave:

Amplitude of wave is the amplitude of

oscillation of particle of the medium. As shown in Figure 8.5 amplitude of the wave is A.

Propagation of energy in a wave:

A particle has to be displaced from its mean position in order to produce a wave. Hence some work has to be done on the particle. This energy imparted to the particle will be in the form of kinetic and potential energy of its oscillations. As the successive particles experience the disturbance, this energy is communicated to them. Thus, energy is propagated in a wave. If the medium has some internal friction, energy is dissipated in the form of heat and hence, the wave weakens on propagation.

Energy passing through a unit area taken in the direction normal to the propagation of the wave in one second is called intensity of wave.

Wave Intensity (I) =
$$\frac{\text{Energy / Time}}{\text{Area}}$$

SI unit of intensity of wave is $\frac{J/s}{m^2}$ or $\frac{W}{m^2}$.

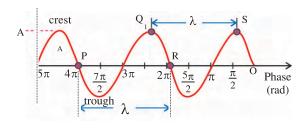
Its dimensional formula is M¹L⁰T⁻³.

Energy of an oscillatory particle is

 $E = \frac{1}{2}kA^2$, hence the intensity of wave is directly proportional to the square of its amplitude. (I $\propto A^2$).

Wavelength:

The linear distance between any two points or particles having phase difference of 2π rad is called the wavelength (λ) of the wave. Its SI unit is m.



Amplitude and wavelength of a wave

Figure 8.5

As shown in Figure 8.5 the phase difference of oscillation between particles P and R is $4\pi - 2\pi = 2\pi$ rad. Hence, the distance between

P and R represent the wavelength (λ) of a wave. From the figure it is clear that phase difference between consecutive crests or consecutive trough is 2π rad. Therefore, the distance between consecutive crests/trough is also a wavelength of a wave. Same way, in case of the sound waves the distance between consecutive condensations or consecutive rarefactions also represents the wavelength.

Wave number and wave vector:

Number of waves per unit distance is called wave number $\left(\frac{1}{\lambda}\right)$. The SI unit of wave number is m^{-1} .

In the wave propagation the particles at a distance of λ has the phase difference of 2π rad. Hence, the particle at a unit distance has phase difference of $\frac{2\pi}{\lambda}$. $\frac{2\pi}{\lambda}$ is known as wave vector or angular wave number or propagation constant (k).

$$k = \frac{2\pi}{\lambda}$$

The SI unit of k is rad/m. Its dimensional formula is $M^0L^{-1}T^0$. Wave vector is in the direction of wave propagation.

Frequency of a wave:

The number of oscillations performed by the particle of medium in one second is known as the frequency of oscillation of particle. Frequency (f) of the wave is just the frequency of oscillation of the particles of the medium. The number of the wave passing through point in one second is called frequency of the wave.

Its SI unit is s^{-1} or Hz (Hertz).

 $\omega = 2\pi f$ is called angular frequency of the

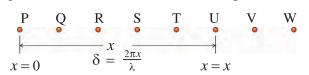
wave. $T = \frac{1}{f}$ is the periodic time of the wave.

8.5 Wave Equation

A complete description for a wave propagation can be obtained if we know displacements of all the particles of medium participating in the wave motion at any time. For this purpose we shall derive the wave equation for wave in one dimension, which gives displacement of a particle having coordinate x at time t. From such an equation, substituting the appropriate values for x and t, we get the displacement for any particle at a required time and thus obtain a description of the wave motion.

Such an equation is called **wave equation**. (Here, we shall discuss wave equation only for one dimension).

Here we shall obtain an equation for travelling wave or progressive harmonic waves. To obtain the wave equation of a wave propagating in positive *x* direction, consider particles of a medium as shown in Figure 8.6.



Wave equation

Figure 8.6

Suppose, at t = 0, simple harmonic oscillations of the particle P start with zero intial phase i.e. wave originates at P at time t = 0. The x-coordinate of the particle P is zero as well as initial phase is also zero ($\phi = 0$). The equation for the displacement of this particle would be,

$$y = A \sin \omega t \tag{8.5.1}$$

Now when the wave originating at P travels through a distance x, the medium particle (U) lying at a distance x from P starts its simple harmonic motion and the phase of its oscillation would be less than that of P. Let the phase of this particle (U) be δ less than that of P. Hence the equation for the displacement of particle at distance x from P, would be,

$$y = A \sin(\omega t - \delta) \tag{8.5.2}$$

Let the wavelength of wave be λ . We know that the phase of the particle at a distance λ from P, is less than that of P by 2π . Hence, the phase of the particle at a distance x from P would be less than that of P by $\frac{2\pi x}{\lambda}$.

$$\therefore \delta = \frac{2\pi x}{\lambda} \tag{8.5.3}$$

Substituting δ in equation (8.5.2)

$$y = A \sin\left(\omega t - \frac{2\pi x}{\lambda}\right)$$
But $\frac{2\pi}{\lambda} = k$

$$\therefore y = A \sin(\omega t - kx)$$
(8.5.4)

Here, $(\omega t - kx)$ is known as the phase of the wave at distance x from the origin at time t. The direction of wave vector k is taken along the direction of propagation of the wave.

Equation (8.5.4) is the wave equation for the progressive harmonic wave travelling in the direction of the increasing value of x. If the wave is travelling in the direction of decreasing value of x then $\omega t - kx$ is replaced by $\omega t + kx$.

$$y = A \sin(\omega t + kx) \tag{8.5.5}$$

substituting $\omega = \frac{2\pi}{T}$ and $k = \frac{2\pi}{\lambda}$ in equation (8.5.4)

$$y = A \sin 2\pi \left(\frac{t}{T} - \frac{x}{\lambda}\right) \tag{8.5.6}$$

If the velocity of wave is v, then substituting $\lambda = vT$ in above equation

$$y = A \sin 2\pi \left(\frac{t}{T} - \frac{x}{vT}\right)$$
$$y = A \sin 2\pi f \left(t - \frac{x}{v}\right) \left(\because \frac{1}{T} = f\right) \quad (8.5.7)$$

$$y = A \sin 2\pi \frac{f}{v} (vt - x)$$

$$y = A \sin \frac{2\pi}{\lambda} (vt - x) (\because v = f \lambda)$$
(8.5.8)

The above equations (8.5.6), (8.5.7) and (8.5.8) are the different forms of wave equation for the progressive harmonic wave.

If particle P is oscillating with initial phase ϕ , then the wave equation (8.5.4) will be as follows:

$$y = A \sin(\omega t - kx + \phi) \tag{8.5.9}$$

8.6 Wave speed and phase speed

Wave travells a distance $\boldsymbol{\lambda}$ in periodic time T.

$$\therefore \text{ wave speed } v = \frac{\text{Distance}}{\text{Time}} = \frac{\lambda}{T}$$
Put $\frac{1}{T} = f$

But
$$\frac{1}{T} = f$$

$$\therefore v = f \lambda$$

$$= \frac{\lambda(2\pi f)}{2\pi}$$
(8.6.1)

But,
$$2\pi f = \omega$$
 and $\frac{2\pi}{\lambda} = k$

$$\therefore v = \frac{\omega}{k} \tag{8.6.2}$$

So far in the discussion of wave motion we have seen that amplitude, period of oscillation and

frequency of oscillation (f) of the particles of medium are the amplitude, periodic time and frequency of the wave respectively.

But the velocity of oscillating particle and velocity of wave are not the same.

Note that, the frequency of the wave is the property of the source of the wave while the wavelength is the property of the medium in which the wave propagates.

In the different mediums the wave speed is different. Therefore, the wavelength of the wave is also different in different type of medium. But in a given medium the wave speed is constant.

Phase Speed

As shown in Figure 8.7 the wave is travelling in the direction of increasing value of x. The entire wave pattern is moving a distance Δx in that direction during the interval Δt . As the wave moves, each point of the moving wave form (such as point A) retains its displacement. (Remember that points on the string do not retain their displacement but point on the wave forms do). For each point on the wave pattern phase must be constant. In Figure 8.7 phase at point A and A' is same.

$$\therefore \omega t - kx = \text{constant}$$
 (8.6.3)

Here, both x and t are changing. As t increases, x must also increase to keep the $\omega t - kx$ constant. This confirms that the wave pattern is moving towards increasing x.

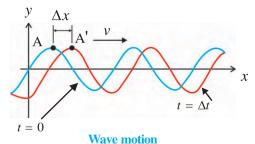


Figure 8.7

Differentiating above equation with respect to t.

$$\frac{d}{dt}(\omega t - kx) = 0$$

$$\therefore \ \omega - k\frac{dx}{dt} = 0$$

$$\therefore \ \frac{dx}{dt} = v = \frac{\omega}{k}$$
(8.6.4)

Here, v is the phase speed of the wave.

Above equation (8.6.4) is similar to the equation (8.6.2). So, the wave speed which we find is the phase-speed of the waves in reality.

Illustration 1: The frequency of the radio-waves broadcast by Ahmedabad Vividhbharati is 96.7 MHz. Find the wavelength, wave vector and angular frequency of these waves. Speed of radio waves in air is 3×10^8 m/s.

Solution:

$$f = 96.7 \text{ MHz} = 96.7 \times 10^6 \text{ Hz}$$

 $v = 3 \times 10^8 \text{ m/s}$

Wave speed, $v = f\lambda$

$$\therefore \lambda = \frac{v}{f} = \frac{3 \times 10^8}{96.7 \times 10^6} = 3.102 \text{ m}$$

Wave vector,
$$k = \frac{2\pi}{\lambda}$$

$$= \frac{2 \times 3.14}{3.102}$$

$$= 2.024 \text{ rad/m}$$

Angular frequency, $\omega = 2\pi f$

$$= 2 \times 3.14 \times 96.7 \times 10^6$$

$$= 6.07 \times 10^8 \text{ rad/s}$$

Illustration 2: The wave equation of a propagating wave is given by $y = 0.5\sin(x - 60t)$ cm. Find, (i) amplitude of the wave (ii) wave vector (iii) wavelength (iv) angular frequency and frequency of wave (v) periodic time and (vi) wave speed.

Solution: Compare the equation

$$y = 0.5 \sin(x - 60t) = -0.5\sin(60t - x)$$
 with wave equation

$$y = A \sin(\omega t - kx)$$

- (i) Amplitude of a wave A = -0.5 cm
- (ii) wave vector k = 1 rad/cm

(iii) wavelength
$$\lambda = \frac{2\pi}{k}$$

$$= \frac{2 \times 3.14}{1} = 6.28 \text{ cm}$$

(iv) Angular frequency of a wave $\omega = 60 \text{ rad/s}$

Now, from $\omega = 2\pi f$, the frequency of wave,

$$f = \frac{\omega}{2\pi} = \frac{60}{2 \times 3.14} = 9.55 \text{ Hz}$$

(v) Periodic time $T = \frac{1}{f} = \frac{1}{9.55} = 0.105 \text{ s}$

(vi) Wave speed
$$v = \frac{\omega}{k} = \frac{60}{1} = 60$$
 cm/s

Illustration 3: How far does sound travel in air when a tuning fork of frequency 250 Hz completes 50 vibrations? The speed of sound in air is 340 m/s.

Solution : Wavelength of the wave produced from tuning fork $\lambda = \frac{v}{f} = \frac{340}{250} = 1.36$ m.

One wavelength is the distance travelled by the wave in one complete vibration of tuning fork.

 \therefore Distance travelled by the sound in 50 vibrations.

$$= 50 \times \lambda$$

= 50 × 1.36 = 68 m

Illustration 4: A stone dropped from the top of a tower of height 100 m high splashed into the water of a pond near the tower. When is the splash heard at the top? The speed of sound in air is 340 m/s. At what time the splash is heared at the top, after it is dropped?

Solution: Suppose t_1 is the time taken by the stone to reach the surface of water and t_2 is the time taken by the splash to reach from water surface to the top. The splash will be heard at the top of the tower after time $t = t_1 + t_2$.

Now, time t_1 taken by stone to reach water surface can be determine as follows:

$$s = v_0 t_1 + \frac{1}{2} g t_1^2$$

$$s = 100 \text{ m}, v_0 = 0, g = 9.8 \text{ m/s}^2$$

$$\therefore 100 = 0 + \frac{1}{2} (9.8) t_1^2$$

$$\therefore t_1 = 4.52 \text{ s}$$

Now, time t_2 taken by the splash to reach water surface to the top is,

$$t_2 = \frac{\text{Distance}}{\text{Sound speed}} = \frac{100}{340} = 0.29 \text{ s}$$

$$\therefore t = t_1 + t_2 = 4.52 + 0.29 = 4.81 \text{ s}$$

Illustration 5 : Equation of a one dimensional propagating wave is,

$$y = 5\sin 30\pi \left(t - \frac{x}{240}\right).$$

Here, y is in metre and t is in second.

- (i) Is the particle of medium moving in positive Y or negative Y direction at the origin at time t=0? i.e. what will be produced first-crest or trough?
- (ii) Find the displacement, velocity of the particle and the slope of the wave at 480 m away from the origin at time $t=2\,\mathrm{s}$.
 - (iii) Find the speed of wave.

Solution:

(i) At x = 0, starting from t = 0, if y increases in the negative direction then the trough will be produced and if y increases in the positive direction then the crest will be produced.

Here, at x = 0, $y = 5 \sin 30\pi t$. Hence, starting from t = 0, here y increases in the positive direction. Hence, first a crest will be produced at the origin.

(ii) Displacement at t = 2 s for a particle at x = 480 m

$$y = 5\sin 30\pi \left(2 - \frac{480}{240}\right)$$
$$= 5\sin 30\pi (0) = 0 \text{ m}$$

Velocity of the particle,

$$v = \frac{dy}{dt} = 150\pi\cos 30\pi \left(t - \frac{x}{240}\right)$$
$$= 150\pi\cos 30\pi \left(2 - \frac{480}{240}\right)$$
$$= 150\pi \text{ m/s}$$

Slope of the wave,

$$\frac{dy}{dx} = -\frac{5\pi}{8}\cos 30\pi \left(t - \frac{x}{240}\right)$$
$$= -\frac{5\pi}{8}\cos 30\pi \left(2 - \frac{480}{240}\right)$$
$$= -\frac{5\pi}{8}$$

(iii) Compare the given equation with,

$$y = A \sin 2\pi f \left(t - \frac{x}{v} \right)$$

 \therefore Wave speed v = 240 m/s

Here, note that the wave speed and the magnitude of velocity of the particle taking part in the wave propagation are not equal.

8.7 Wave Speed in Medium

8.7.1 Speed of Transverse Wave on Stretched String:

Earlier we have seen that the particles of the string come back to their original position after the disturbance (or wave) has passed through those particles. In order that particles come back to their original positions, restoring force and hence elasticity in medium are essential. Moreover, the inertia of the medium plays a role in deciding the displacement of the oscillatory particles. Thus, the elasticity and intertia of medium are necessary for the propagation of the mechanical waves. From these two properties of medium, the speed of wave in a meduim is determined.

It is found that the speed of transverse wave in a medium like a string kept under the tension, depends on (i) linear mass density (μ) and (ii) tension T in the string.

Here, we will obtain the speed of wave on a string using dimensioned analysis.

Linear density of a string means mass per unit length (μ) of the string.

Dimensional formula of

$$\mu = \frac{[Total \ mass \ of \ string]}{[Total \ length \ of \ string]} = \frac{\underline{M}^1}{\underline{L}^1}$$
$$= \underline{M}^1 \underline{L}^{-1} \underline{T}^0$$

Dimension of Tension $T = M^1L^1T^{-2}$

Suppose, wave speed

$$v = k \, \mu^a \, \mathrm{T}^b \tag{8.7.1}$$

Here, k = dimensionless constant and $[a, b] \in \mathbb{R}$.

Substituting dimensions on both the sides,

$$M^{0}L^{1}T^{-1} = [M^{1}L^{-1}T^{0}]^{a} [M^{1}L^{1}T^{-2}]^{b}$$

= $M^{a+b} L^{-a+b} T^{-2b}$

Comparing dimensions of both the sides, a + b = 0, -a + b = 1 and -2b = -1

$$\therefore a = -\frac{1}{2} \text{ and } b = \frac{1}{2}$$

Substituting value of a and b in equations (8.7.1)

$$v = k \mu^{-\frac{1}{2}} T^{\frac{1}{2}}$$

From the experimental and other studies, k = 1

$$\therefore v = \sqrt{\frac{T}{\mu}}$$
 (8.7.2)

Above equation shows that wave speed is independent of frequency of a wave and amplitude of a wave.

Illustration 6: A long wire PQR is made by joining two wires PQ and QR of equal radii. The wire PQ has length 4.8 m and mass. 0.06 kg. The wire QR has length 2.56 m and mass 0.2 kg. The wire PQR is under the tension of 80 N. Find the time taken by a wave produced at the end P to reach the other end R.

Solution:

Mass per unit length for the wire PQ,

$$\mu_1 = \; \frac{0.06}{4.8} \; = \; \frac{1}{80} \;\; \frac{kg}{m}$$

Mass per unit length for the wire QR,

$$\mu_2 = \frac{0.2}{2.56} = \frac{10}{128} \frac{\text{kg}}{\text{m}}$$

.. Speed of wave in the wire PQ,

$$v_1 = \sqrt{\frac{T}{\mu_1}} = \sqrt{\frac{80}{180}} = 80 \text{ m/s}$$

.. Speed of wave in the wire QR,

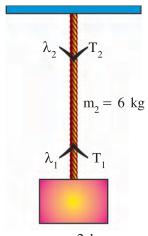
$$v_2 = \sqrt{\frac{T}{\mu_2}} = \sqrt{\frac{80}{128}} = 32 \text{ m/s}$$

... Time taken by the wave to reach R from P, $t=t_1+t_2$

$$= \frac{PQ}{v_1} + \frac{QR}{v_2}$$
$$= \frac{4.8}{80} + \frac{2.56}{32}$$
$$= 0.14 \text{ s}$$

Illustration 7: A uniform rope of length 12 m and mass 6 kg hangs vertically from a rigid support. A block of mass 2 kg is attached to the free end of the rope. A transverse pulse of wavelength 0.06 m is produced at the lower end of the rope. What is the wavelength of the pulse when it reaches the top of the rope?





 $m_1 = 2 \text{ kg}$ Figure 8.8

As the rope is heavy, its tension will be different at different points.

mass of rope $m_2 = 6 \text{ kg}$

mass a block $m_1 = 2 \text{ kg}$

Tension at the lower end of rope,

$$T_1 = m_1 g = 2g$$

Tension of the upper end of rope,

$$T_2 = (m_1 + m_2)g$$

= $(6 + 2)g = 8g$

wave speed in a string
$$v=\sqrt{\frac{T}{\mu}}$$

$$\therefore f\lambda = \sqrt{\frac{T}{\mu}}$$

$$(\because v=f\lambda)$$

The frequency of the wave pulse will be the same everywhere on the rope and μ is also the same throughout the rope as it is uniform. Therefore,

$$\lambda \alpha \sqrt{T}$$

Wavelength of wave at lower end of rope,

$$\lambda_1 \propto \sqrt{T_1}$$

Wavelength of wave at upper end of rope,

$$\lambda_2 \propto \sqrt{T_2}$$

$$\therefore \frac{\lambda_2}{\lambda_1} = \sqrt{\frac{T_2}{T_1}}$$
and $\lambda_2 = \lambda_1 \sqrt{\frac{T_2}{T_1}}$

$$= (0.06) \sqrt{\frac{8g}{2g}}$$

$$= 0.12 \text{ m}$$

Illustration 8: The speed of transverse wave going on a wire having length 50 cm and mass 5.0 g is 80 m/s. The area of crosssection of the wire is 1.0 mm² and its Young's modulus is 16×10^{11} N/m². Find the extension of the wire over its natural length.

Solution:

Length of the wire $L = 50 \text{ cm} = 50 \times 10^{-2} \text{ m}$ mass of wire $m = 5g = 5 \times 10^{-3} \text{ kg}$ cross sectional area of wire

$$A = 1 \text{mm}^2 = 1 \times 10^{-6} \text{ m}^2$$

Young's modulus of wire $Y = 16 \times 10^{11} \text{ N/m}^2$ wave speed in a wire v = 80 m/s. mass per unit length of wire,

$$\mu = \frac{\text{m}}{\text{L}} = \frac{5 \times 10^{-3}}{50 \times 10^{-2}} = 1 \times 10^{-2} \text{ kg/m}$$

The wave speed in wire $v = \sqrt{\frac{T}{u}}$

∴ Tension in wire = T = F =
$$\mu v^2$$

= $(1 \times 10^{-2}) (80)^2$
= 64 N

Now, Young's modulus $Y = \frac{r'_A}{\Delta L}$

: Extension in the length of wire,

$$\Delta L = \frac{FL}{AY}$$

$$= \frac{(64)(50 \times 10^{-2})}{(1 \times 10^{-6})(16 \times 10^{11})}$$

$$= 0.03 \text{ pm}$$

8.7.2 Speed of sound waves (longitudinal wave) in a medium:

It is found that the speed of longitudinal waves like sound waves in a medium depends on (i) the elastic constant E and (ii) density ρ of the medium.

Using these facts, we can obtain the speed of the longitudinal waves using dimensional analysis as follows.

Wave speed $v = kE^a \rho^b$

Here, k is dimensionless constant and $[a, b] \in \mathbb{R}$.

Now,
$$[E] = M^1L^{-1}T^{-2}$$
, $[\rho] = M^1L^{-3}T^0$

Writing dimensional formula on both the sides,

$$M^{0}L^{1}T^{-1} = [M^{1}L^{-1}T^{-2}]^{a} [M^{1}L^{-3}T^{0}]^{b}$$

= $M^{a+b} I^{-a-3b} T^{-2a}$

Comparing dimensions on both the sides, a + b = 0, -a - 3b = 1 and -2a = -1

$$\therefore a = \frac{1}{2} \text{ and } b = -\frac{1}{2}$$

$$\therefore v = k E^{\frac{1}{2}} \rho^{-\frac{1}{2}}$$

From the experimental and other studies k = 1,

$$\therefore v = \sqrt{\frac{E}{\rho}}$$
 (8.7.3)

The propagation of longitudinal waves in fluid is in the form of condensations and rarefactions. In such a situation due to the variation in pressure of different regions of the medium bulk modulus (B) is taken as the elastic constant.

$$\therefore v = \sqrt{\frac{B}{\rho}}$$
 (8.7.4)

During the propagation of longitudinal waves in a linear medium like a rod, the longitudinal strain is produced. Hence in such a situation Young's modulus is taken as the elastic constant.

$$\therefore v = \sqrt{\frac{Y}{\rho}} \tag{8.7.5}$$

Table 8.1 gives the speed of sound in various media.

Table 8.1 Speed of sound in some media (Only For Information)

(Omy For Information)			
Medium	Speed (m/s)		
Gases			
Air (0°C)	331		
Air (20°C)	343		
Helium	965		
Hydrogen	1284		
Liquids			
Water (0°C)	1402		
Water (20°C)	1482		
Seawater	1522		
Solids			
Aluminium	6420		
Copper	3560		
Steel	5941		
Rubber	54		

It is clear from the Table (8.1) that although the densities of liquids and solids are much greater than those of the gases, the speed of sound in them is higher. It is because liquids and solids are less compressible than gases. i.e have much greater bulk modulus.

Newton's Formula:

Newton assumed that the process of propagation of sound in gas (or air) is isothermal. Hence, the isothermal bulk modulus is to be used in the equation (8.7.4).

For an isothermal process PV = constant

(Taking T = constant, $PV = \mu RT = constant$)

Differentiating with respect to V,

$$P\frac{dV}{dV} + V\frac{dP}{dV} = 0$$

$$\therefore P = -V \frac{dP}{dV} = -\frac{dP}{dV/V} = Bulk \text{ modulus } B$$

Thus, isothermal bulk modulus B = Pressure P.

$$(:: B = -\frac{dP}{dV/V})$$

$$\therefore \text{ Wave speed } v = \sqrt{\frac{B}{\rho}} = \sqrt{\frac{P}{\rho}} \qquad (8.7.6)$$

This formula is called Newton's formula for the speed of sound in air.

Illustration 9 : Obtain the speed of sound in air at STP using Newton's formula. Mass of 1 mole of air = 29.0×10^{-3} kg.

$$P = 1.01 \times 10^5 P_a$$

Solution : Volume of 1 mole of air at STP = $22.4 L = 22.4 \times 10^{-3} m^3$

Density of air at STP $\rho = \frac{Mass}{Volume}$

$$\therefore \rho = \frac{29.0 \times 10^{-3}}{22.4 \times 10^{-3}} = \frac{29.0}{22.4}$$

.. Speed of sound in air at STP,

$$v = \sqrt{\frac{P}{\rho}}$$

$$= \sqrt{\frac{1.01 \times 10^5 \times 22.4}{29.0}} = 279.3 \text{ m/s}$$

Laplace's Correction:

The speed of sound according to Newton's formula is 279.3 m/s while its experimental value is 332 m/s at STP. This suggests that there is some defect in the formula (8.7.6)

Laplace suggested that the temperature of the region where condensation is formed increases and that of the region of rarefaction decreases. Hence, the process of propagation of sound in a medium cannot be considered isothermal.

The process of formation of condensation and rarefaction in the medium is so quick that the heat produced during the condensation, is absorbed at the same place during rarefaction before being dissipated outside. Relatively small thermal conductivity of gas also helps in not allowing the heat to be dissipated outside. Thus, the process of sound propagation in the gas is adiabatic and not isothermal. Hence, adibatic bulk modulus of the gas should be used in place of isothermal bulk modulus.

For an adiabatic process of an ideal gas,

 $PV^{\gamma} = constant$

Where γ is the ratio of two specific heats $C_{_{\rm P}}$ and $C_{_{\rm V}}.$

Differentiating the equation with respect to V.

$$P \cdot \gamma V^{\gamma - 1} + V^{\gamma} \frac{dP}{dV} = 0$$

$$\therefore \gamma P + V \frac{dP}{dV} = 0$$

$$\therefore \frac{-d\mathbf{P}}{d\mathbf{V}_{\mathbf{V}}} = \gamma \mathbf{P}$$

$$\therefore B = \gamma P$$

Thus, for an adiabatic process bulk modulus $B=\gamma\ P.$

Using this value of B in equation (8.7.4)

wavespeed
$$v = \sqrt{\frac{\gamma P}{\rho}}$$
 (8.7.7)

For air γ is 1.41. Speed of sound comes out 331.6 m/s at STP on taking this value of ν . This agrees very well with the experimental value. To

determine speed of wave in ideal gas Laplace equation (8.7.7) should use instead of Newton's formula.

Various factors affecting speed of sound waves: The equation of state for 1 mole of ideal gas is.

$$PV = RT \ (\mu = 1 \ mol)$$

$$RT$$

$$\therefore P = \frac{RT}{V}$$

Substituting value of P in $v = \sqrt{\frac{\gamma P}{\rho}}$

$$\therefore v = \sqrt{\frac{\gamma RT}{V\rho}}$$

But, ρV = mass of one mole gas = molecular mass M of gas

$$\therefore \text{ Speed } v = \sqrt{\frac{\gamma RT}{M}}$$
 (8.7.9)

From this expression it is clear that the speed of sound in a gas is directly proportional to the square root of its absolute temperature (T).

i.e.
$$v \propto \sqrt{T}$$

If pressure (P) of the gas is changed keeping its temperature constant, $\frac{P}{\rho}$ remains constant as the density ρ of the gas directly varies as the pressure P. Therefore, the speed of sound in a gas does not depend on the pressure of the gas at constant temperature and constant humidity.

Density of water vapour is less than the density of dry air at same pressure. Hence, the speed of sound increases with increasing

humidity as per
$$v = \sqrt{\frac{\gamma P}{\rho}}$$
.

Illustration 10: Show that the velocity of sound in a gas at temperature t is given by,

$$v_t = v_0 \left(1 + \frac{t}{546} \right)$$

Where, v_0 is speed of sound in air at 0° C (t << 273)

Solution: The speed of the wave in gas is

$$v = \sqrt{\frac{\gamma RT}{M}}$$

i. e.
$$v \propto \sqrt{T}$$

If, v_t = speed of sound in gas at t^0 C

 v_0 = speed of sound in gas at 0° C

$$\therefore \frac{v_t}{v_0} = \sqrt{\frac{273 + t}{273}}$$

$$(\because T(K) = t(^{\circ}C) + 273)$$

$$\therefore v_t = v_0 \left(1 + \frac{t}{273} \right)^{\frac{1}{2}}$$

Using binomial expansion and neglecting higher order terms,

$$v_{t} = v_{0} \left(1 + \frac{1}{2} \times \frac{t}{273} \right)$$

$$v_{t} = v_{0} \left(1 + \frac{t}{546} \right)$$

[Note: If the speed of sound in air at 0° C is 332 m/s, than speed at 1° C will be,

$$v_t = v_0 \left(1 + \frac{t}{546} \right)$$

= 332 $\left(1 + \frac{1}{546} \right)$ = 332.61 m/s

Thus, the velocity of sound in air increases by 332.61 - 332 = 0.61 m/s for every 1° C rise in temperature.]

Illustration 11: If the velocity of sound in air at 27° C and 76 cm of mercury is 345 m/s. Find the velocity at 127° C and 75 cm of mercury.

Solution : Remember that there is no effect of change of pressure on the velocity of sound.

If v_1 and v_2 be the velocities of sound at

27° C and 127° C, then we have

$$\frac{v_2}{v_1} = \sqrt{\frac{T_2}{T_1}} = \sqrt{\frac{273 + 127}{273 + 27}} = \sqrt{\frac{4}{3}}$$

∴ Speed of sound at 127° C,

$$v_2 = v_1 \times \sqrt{\frac{4}{3}} = 345 \times \sqrt{\frac{4}{3}} = 398.4 \text{ m/s}$$

Illustration 12: The speed of sound in dry air at STP is 332 m s^{-1} . Assume air as composed of 4 part of nitrogen and one part of oxygen. Calculate speed of sound in oxygen

under similar condition when the density of oxygen and nitrogen at STP are in the ratio of 16:14.

Solution: Density of air = $\frac{\text{Total mass}}{\text{Total volume}}$

$$\rho_a = \frac{(\text{Mass of oxygen}) + (\text{Mass of nitrogen})}{(\text{Volume of oxygen}) + (\text{Volume of nitrogen})}$$

$$\rho_a = \frac{(V \times \rho_0) + (4V \times \rho_N)}{V + 4V}$$

$$= \frac{\rho_0 + 4\rho_N}{5}$$

$$=\frac{\rho_0\left(1+4\times\frac{\rho_N}{\rho_0}\right)}{5}$$

$$= \frac{\rho_0 \left(1 + 4 \times \frac{14}{16}\right)}{5}$$

$$= 0.9 \rho_0$$

Speed of sound
$$v \propto \frac{1}{\sqrt{\rho}} \ (\because v = \sqrt{\frac{\gamma P}{\rho}})$$

$$\therefore$$
 Speed of sound in oxygen, $v_0 \propto \frac{1}{\sqrt{\rho_0}}$

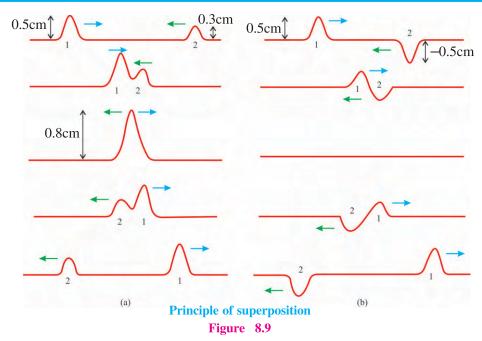
Speed of sound in air $v_a = \frac{1}{\sqrt{\rho_a}}$

$$\therefore \frac{v_0}{v_a} = \sqrt{\frac{\rho_a}{\rho_0}} = \sqrt{\frac{0.9\rho_0}{\rho_0}} = 0.9487$$

$$v_0 = v_a \times 0.9487 = 332 \times 0.9487$$
$$= 314.77 \text{ m/s}$$

8.8 Superposition Principle and Reflection of the Wave

So far we have discussed a single wave propagating on a string. Suppose two persons holding the string at the two ends snap their hands once, then two wave pulses will be produced and move towards each other as shown in figure 8.9(a). The pulses travel at same speed because the medium is same.



Suppose the maximum displacement of particle in first wave is 0.5 cm and in second wave is 0.2 cm. As the two wave approaching each other, at any instant both the waves will overlap in some region of the string. Then after they move with their original shape and in their original direction. The net maximum displacement of the particle of string in overlaped region would be 0.5 cm + 0.3 cm = 0.8 cm.

Suppose the two persons snap the end of the string such that wave pulse generates at both the end of the string as shown in Figure 8.9(b).

In the first wave pulse the maximum displacement of particle is 0.5 cm in upward and in the other wave pulse the maximum displacement of particle is 0.5 cm in downward direction.

When the wave pulses approach each other, at some instant they overlay on the string and displacement of all the particles will be $0.5 \, \text{cm} + (-0.5 \, \text{cm}) = 0$. However, the velocities of the particles will not be zero. In this situation, string becomes straight everywhere than both the wave pulses will emerge and move in their original direction.

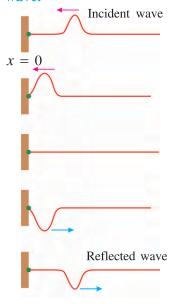
From the above observation principle of superposition can be given as follows.

"When a particle of medium comes under the influence of two or more waves simultaneously, its net displacement is the vector sum of displacement that would occur under the influence of the individual waves."

Reflection of Waves:

(a) Reflection of waves from a rigid support:

Suppose a wave propagating in the direction of decreasing value of x, represented by the equation $y = A \sin (\omega t + kx)$ reaches a point x = 0, when the wave arrives at the rigid end it exerts a force on the support (wall). By Newton's third law, the support exerts an equal but opposite reaction force on the string. This reaction force generates a wave at the support which travels back along the string in the direction opposite that of incident wave. This wave is known as **reflected wave.**



Reflection of wave from rigid support Figure 8.10

Oscillation of the particle at point x = 0, due to wave $y = A \sin(\omega t + kx)$, can be represented as, $y_i = A \sin\omega t$ (8.8.1)

But, the support at x = 0 is fixed, the displacement at x = 0 must always be zero. According to principle of superposition, the displacement at x = 0 due to reflected wave. It can be give as,

$$y_r = -A \sin \omega t \tag{8.8.2}$$

Equation (8.8.2) can be represented as follows:

$$y_r = A\sin(\omega t + \pi) \tag{8.8.3}$$

This shows that as the wave reflected from a fixed support, its phase is increased by π . Thus, the 'shape' of the waveform is inverted on reflection. i.e. Crest becomes a trough and trough becomes a crest.

The reflected wave is travelling in the direction of increasing value of x. So the equation can be written as,

$$y_r = A \sin(\omega t + \pi - kx)$$

$$\therefore y_r = -A \sin(\omega t - kx)$$
(8.8.4)

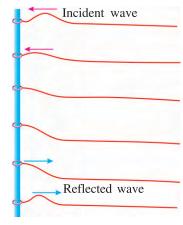
If the incident wave is travelling in the direction of increasing value of x, then $y_i = A \sin(\omega t - kx)$ (8.8.5)

And equation of reflected wave can be given as,

$$y_r = -A \sin(\omega t + kx) \tag{8.8.6}$$

(b) Reflection of waves from a free end:

As shown in Figure 8.11 suppose one end of a string is tied to a very light ring which can slide or move without any friction on a vertical rod. Such an end of the ring is said to be free end and here, we will understand the reflection of waves from such a free end.



Reflection of a wave from a free end

Figure 8.11

Suppose the crest like shape of the wave produced from the other end of the string reaches the ring. The ring is then pushed upwards as it is not fixed. Hence the string tied to the ring is also pulled up. As a result of this, now, a reflected wave pulse is generated from this end of the string. Phase of this reflected waves is equal to the phase of the incident wave. So, in this situation the shape is not inverted and a crest is reflected as a crest and a trough as a trough only. Moreover, during such a reflection both the waves are simultaneously present on the ring in same phase and hence the displacement of the ring on the rod is twice the amplitude of the incident wave.

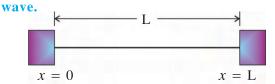
From this discussion it is clear that if the equation of the incident wave is $y_i = A \sin(\omega t + kx)$ then the equation of its reflected wave from a free end will be

$$y_r = A \sin (\omega t - kx) \tag{8.8.7}$$

Thus, a travelling wave at a rigid boundary or a closed end, is reflected with a phase reversal of π but the reflection at an open boundary takes place without any phase change.

8.9 Stationary Waves

When two waves having the same amplitude and frequency (i.e. wavelength) and travelling in mutually opposite directions are superposed, the resultant wave formed loses the property of propagation and a stationary pattern is created in the medium. Such a wave is called a **stationary**



A string fixed at both the ends with rigid supports
Figure 8.12

To understand stationary waves, consider a string of length L, kept under a suitable tension, fixed at its two ends. The harmonic waves produced in this string will be reflected from rigid supports repeatedly so that each element of string is under the influence of "incident" and "reflected" waves.

Let the wave propagating in the direction of increasing x be

$$y_1 = A \sin(\omega t - kx) \tag{8.9.1}$$

The reflected wave propagating in the direction of decreasing x will then be,

$$y_2 = -A \sin(\omega t + kx) \tag{8.9.2}$$

According to principle of superposition, the displacement of a particle of a string is given by,

$$y = y_1 + y_2$$

= A sin(\omega t - kx) - A sin(\omega t + kx)

Now,

∴
$$y = -2A\cos\omega t \sin kx$$
 (see foot note)
= $-2A \sin kx \cos\omega t$ (8.9.3)

The functional form of this wave is not of type $f(\omega t \pm kx)$ which means that it is not a travelling or progressive wave. Equation (8.9.3) is an equation of a stationary wave. Energy does not propagate in this type of a wave and hence it is named as a stationary wave.

The term 'cos ωt ' of the equation (8.9.3) shows that each particle of the string is executing a simple harmonic motion and their amplitudes depends upon position x according to $2A\sin kx$. Here, amplitudes of all the particles are not same.

The location of particles for which $\sin kx = 0$, have zero amplitude and these points remains stationary. These points are called 'Nodes'.

The positions in a stationary wave where the amplitude always remains zero are called the 'Nodes'.

Now $\sin kx = 0$

$$\therefore kx = n\pi$$
 where $n = 1, 2, 3 \dots$

$$\therefore x = \frac{n\pi}{k} = \frac{n\pi}{2\pi/\lambda}$$

$$\therefore x = \frac{n\lambda}{2}$$
(8.9.4)

This shows that the nodes are located at a distance $x = \frac{\lambda}{2}$, λ , $\frac{3\lambda}{2}$, $\frac{n\lambda}{2}$ from the end x = 0. The distance between the successive node is $\frac{\lambda}{2}$.

node is
$$\frac{\lambda}{2}$$
.

Foot note: $\sin C - \sin D = 2 \cos \left(\frac{C+D}{2}\right) \sin \left(\frac{C-D}{2}\right)$

Maximum amplitudes occur at points for which $\sin kx = \pm 1$. These points are called "Antinodes".

The positions in a stationary wave where the amplitude always remains maximum are called the 'Antinodes'.

$$\sin kx = \pm 1$$

$$\therefore kx = (2n - 1)\frac{\pi}{2} \text{ where, } n = 1, 2, \dots$$

$$\therefore x = \frac{(2n - 1)\pi}{2k}$$

$$= (2n - 1)\frac{\lambda}{4}$$
(8.9.5)

Thus, the antinodes are located at $x = \frac{\lambda}{4}$, $\frac{3\lambda}{4}$, $\frac{5\lambda}{4}$, from the end x = 0. Distance between successive antinode is also $\frac{\lambda}{2}$. Distance between a node and an adjacent antinode is $\frac{\lambda}{4}$.

In Figure 8.13 the antinodes are shown as A and the nodes are shown as N.

The displacement of string at the end x = 0 and at the end x = L is always zero because the string is fixed to a rigid support at x = L.

$$\therefore \sin k L = 0$$

$$\therefore k L = n\pi \qquad \text{where } n = 1, 2, 3, \dots$$

$$\therefore \frac{2\pi}{\lambda} L = n\pi$$

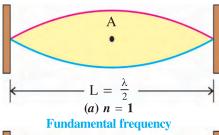
$$\therefore \lambda_n = \frac{2L}{n} \qquad (8.9.6)$$

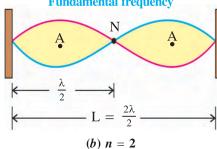
This equation shows that for a string at given length L, stationary wave can be formed only with waves having specific discrete values for their wave length like 2L, L, $\frac{2L}{3}$, $\frac{L}{2}$, appropriate to different values of n. Thus, waves with arbitrary wavelength cannot form stationary waves on a string of a given length.

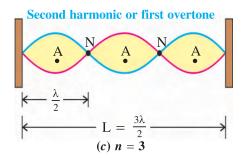
The frequency of the standing waves produced on a string will have corrosponding to its restricted wavelength. It is given by,

$$f_n = \frac{v}{\lambda_n}$$

 $\therefore f_n = \frac{nv}{2L}$ (from equation 8.9.6) (8.9.7)







Third harmonic or second overtone

Stationary waves on a string

Figure 8.13

or
$$f_n = \frac{n}{2L} \sqrt{\frac{\Gamma}{\mu}}$$
 (8.9.8)

Where, v = speed of wave on string = $\sqrt{\frac{T}{\mu}}$ Substituting n = 1 in equation (8.9.7)

$$f_1 = \frac{v}{2L}$$

Here, f_1 is called **fandamental frequency** or **first harmonic.**

Taking n=2,

$$f_2 = \frac{2v}{2L} = 2f_1$$

 f_2 is called **second harmonic** or **first overtone.**

Taking n = 3,

$$f_3 = \frac{3v}{2I} = 3f_1$$

 f_3 is called **third harmonic** or **second** overtone

In this way taking successive integral values of n, all possible oscillation of the string are

obtained and corresponding frequencies of the fourth, fifth etc. harmonics are obtained.

Figure 8.13 shows oscillation of string with first, second and third harmonics. Form figure it is clear that number of loops produced on the string is same as value of n.

These oscillations with discrete frequencies in various harmonics are called the 'Normal Modes of Oscillation of a system.

Frequencies appropriate to the different normal modes of vibrations can be obtained from the following equation.

$$f_n = \frac{nv}{2L} = nf_1$$
 where $n = 1, 2, 3...$

Here, f_n is the frequency of wave produced on a string. It is also called nth harmonic or (n-1)th overtone. The integer n indicates the number of loops on the string.

Illustration 13.: The stationary waves produced in a 60 cm long string tied at both the ends with rigid support are represented by $y = 4\sin\left(\frac{\pi x}{15}\right)\cos\left(96\pi t\right)$. Here, x and y are in cm and t is second. Find out,

- (1) position of nodes,
- (2) positions of anti-nodes,
- (3) maximum displacement of the particle at x = 5 cm
 - (4) the equation of the component waves.

Solution: Comparing

$$y = 4\sin\left(\frac{\pi x}{15}\right)\cos(96\pi t)$$
 with

$$y = 2A\sin(kx)\cos(\omega t)$$
,

A = 2 cm,
$$k = \frac{\pi}{15} \frac{\text{rad}}{\text{cm}}$$
 and $\omega = 96\pi$ rad/s

But,
$$k = \frac{2\pi}{\lambda}$$

$$\therefore \frac{2\pi}{\lambda} = \frac{\pi}{15} \Rightarrow \lambda = 30 \text{ cm}$$

(1) Positions of nodes

$$=\frac{n\lambda}{2}$$
, where $n = 1, 2,...$
= 15 cm, 30 cm, 45 cm

(The particles at 0 cm and 60 cm are tied to the rigid supports and hence they are not considered here.)

(2) Positions of antinodes, = $(2n - 1)\frac{\lambda}{4}$, where n = 1, 2, 3,...

= 7.5 cm, 22.5 cm, 37.5 cm, 52.5 cm

(3) Maximum displacement of the particle at a distance

$$x = 2A\sin kx$$

$$= 4\sin\left(\frac{\pi x}{15}\right)$$

$$= 4\sin\left(\frac{\pi}{3}\right) \ (\because x = 5 \text{ cm})$$

$$= 4\frac{\sqrt{3}}{2}$$

$$= 2\sqrt{3} \text{ cm}$$

(4)
$$y = 4\sin\left(\frac{\pi x}{15}\right)\cos(96\pi t)$$

= $2\sin\left(\frac{\pi x}{15} + 96\pi t\right) + 2\sin\left(\frac{\pi x}{15} - 96\pi t\right)$

... Component of waves are

$$y_1 = 2\sin\left(\frac{\pi x}{15} + 96\pi t\right)$$
cm and,

$$y_2 = 2\sin\left(\frac{\pi x}{15} - 96\pi t\right) \text{cm}$$

Illustration 14: The equation of a progressive, harmonic waves travelling in a medium is given by an equation $y_i = A\cos(ax + bt)$; where A, a and b are positive constants. This wave is reflected from a rigid support kept at x = 0. The intensity of the reflected wave is 0.64 times that of the incident wave.

- (a) What are wavelength and frequency of the incident wave?
 - (b) Write the equation of the reflected wave.
- (c) Express the resultant wave in the form of progressive and stationary waves.

Solution:

(a) Incident wave is $y_i = A\cos(ax + bt)$

Comparing this equation with the waveequation $y = A\cos(kx + \omega t)$, \therefore wave-vector k = a

$$\therefore \frac{2\pi}{\lambda} = a$$

$$\lambda = \frac{2\pi}{a}$$

Angular frequency $\omega = 2\pi f = b$

$$\therefore f = \frac{b}{2\pi}$$

(b) Intensity I \propto A², where A = amplitude.

Suppose amplitudes of the incident and the reflected waves are A_1 and A_2 respectively and I_1 and I_2 are their intensities respectively.

$$\therefore \frac{I_2}{I_1} = \frac{(A_2)^2}{(A_1)^2}$$

$$\therefore \frac{A_2}{A_1} = \left(\frac{I_2}{I_1}\right)^{\frac{1}{2}} = (0.64)^{\frac{1}{2}}$$

 \therefore A₂ = 0.8 A (\because A₁ = Amplitude of the incident wave = A)

 \therefore Amplitude of the reflected wave $A_2 = 0.8 \text{ A}$

Equation of the reflected wave

$$y_r = -A_2 \cos(bt - ax)$$

$$\therefore y_r = -0.8 \text{ A } \cos(bt - ax)$$

(c) Resultant wave $y = y_i + y_r$

$$= A \cos(bt + ax) - 0.8 A \cos(bt - ax)$$

$$= 0.8 \text{ A } \left[\cos(bt + ax) - \cos(bt - ax)\right]$$

+ 0.2 Acos (bt + ax)

 $= -1.6 \text{ Asin } (ax) \cdot \sin (bt)$

$$+ 0.2 \text{ Acos } (bt + ax),$$

where, stationary wave,

$$y_s = -1.6 \text{ Asin } (ax) \cdot \sin (bt) \text{ and}$$

progressive wave $y_p = 0.2 \text{ Acos } (bt + ax)$

Illustration 15: A block is attached to the free end of a sonometer wire. The wire has fundamental frequency f_1 Hz in this situation. Now the block is immersed in water and it is found that the wire has a fundamental frequency f_2 Hz. When the block is immersed in some liquid, the fundamental frequency of the wire is f_3 Hz. Find the specific gravity of the material of the block and that of the liquid.

Solution: The force of buoyancy is different when the block is in air, in water and in liquid. So the effective weight is different in these cases. Hence, tension in the wire is also different and as a result the frequency is also different for the wire of same length and same material.

Suppose, the weight of block in air is W_1 , in water W_2 and in liquid W_3 .

Fundamental frequency, $f = \frac{1}{2L} \sqrt{\frac{T}{\mu}}$

Here, L and μ being constant,

$$f \propto \sqrt{T}$$

 \therefore T = kf^2 where, k = constant of proportionality.

But, tension T = Weight W

$$\therefore W = kf^2$$

$$\therefore W_1 = kf_1^2; W_2 = kf_2^2; W_3 = kf_3^2$$

According to Archimedes' principle,

Specific gravity of block

 $= \frac{\text{Weight of block in air}}{\text{Loss of weight of block in water}}$

$$= \frac{W_1}{W_1 - W_2} = \frac{f_1^2}{f_1^2 - f_2^2}$$

Specific gravity of liquid

 $= \frac{Loss of weight of block in liquid}{Loss of weight of block in water}$

$$= \frac{W_1 - W_3}{W_1 - W_2} = \frac{kf_1^2 - kf_3^2}{kf_1^2 - kf_2^2}$$
$$= \frac{f_1^2 - f_3^2}{f_1^2 - f_2^2}$$

8.10 Stationary Wave in Pipes

As stationary waves are formed on a string due to superposition of incident and reflected transverse waves of definite frequencies, stationary waves are also formed due to reflection of longitudinal waves of definite frequencies in the air column, from the end of a pipe. The flute trumpet, clarionet etc. are the musical instrument that are organ pipes in which stationary longitudinal waves are formed. Such pipes are of two types: (1) an open pipe in which both ends are open e.g. flute. (2) a closed pipe in which one end is closed, e.g. clarionet.

Just as in case of string, a node obtained at the fixed end, for a closed pipe a **node** is always formed at the closed end because longitudinal waves are reflected from closed end. If the pipe is narrow compared to the wavelength of wave, an **antinode** is formed at the open end (slightly outside). The situation is slightly complicated for the reflection of longitudinal waves at the open end of the pipe.

Stationary Waves in a Closed Pipe:

For stationary waves to be formed in a closed pipe the wavelength (λ) of the wave should be such that a node is formed at the closed end of the pipe and an antinode at its open end. In stationary waves the distances between nodes and

antinodes are
$$\frac{\lambda}{4}$$
, $\frac{3\lambda}{4}$, $\frac{5\lambda}{4}$,(2*n*-1) $\frac{\lambda}{4}$, where $n = 1, 2, 3,...$

Similarly, in general stationary waves is produced in a pipe of length L for wavelength λ only when,

$$L = (2n - 1)\frac{\lambda}{4} \tag{8.10.1}$$

where n = 1, 2, 3, ...

In a closed pipe the value of possible wavelengths required for stationary waves are given by,

$$\lambda_n = \frac{4L}{(2n-1)} \tag{8.10.2}$$

The frequency of stationary waves in pipe will be,

n = 1 Fundamental frequency (first harmonic)

n = 2 Third harmonic (first overtone)

n = 3 Fifth harmonic (second overtone)

Stationary waves in a closed pipe

Figure 8.14

$$\therefore f_n = \frac{v}{4L}(2n - 1) \tag{8.10.3}$$

where, v is a speed of wave.

(i) Taking n = 1,

$$f_1 = \frac{v}{4L}$$

 f_1 is known as **fundamental frequency** or the **first harmonic.**

(ii) Taking n = 2,

$$f_2 = \frac{3v}{4L} = 3f_1$$
 (:: $f_1 = \frac{v}{4L}$)

 f_2 is known as third harmonic or first overtone.

(iii) Similarly for n = 3,

$$f_3 = \frac{v}{4L}(2(3) - 1) = \frac{5v}{4L} = 5f_1$$

 f_3 is known as fifth harmonic or second overtone.

In general, the frequency of n^{th} mode of normal oscillation in closed pipe is given by,

$$f_n = \frac{v}{4L} (2n - 1)$$

= $(2n - 1)f_1$ (8.10.4)
where $n = 1, 2, 3,...$

Here, f_n represents (2n - 1) harmonic or (n - 1)th overtone.

Thus, in the closed pipe all the harmonics are not possible. The harmonics are possible only for odd multiples of fundamental frequency $(f_1, 3f_1, 5f_1, \dots)$.

[In this reference, equation (8.10.3) can be written as,

$$f_n = nf_1 = \frac{nv}{4L}$$
 where $n = 1, 3, 5...$

where, f_n represent nth harmonic or $\left(\frac{n-1}{2}\right)$ th overtone

The frequencies for which stationary waves are formed are called natural or characteristic frequencies of the given pipe.

Stationary waves in an open pipe:

In an open pipe, antinodes are formed at both the ends. We know that in stationary waves

distances of antinodes are $\frac{\lambda}{2}$, λ , $\frac{3\lambda}{2}$ $\frac{n\lambda}{2}$.

Where n = 1, 2, 3,...

Therefore, in an open pipe of length L, the stationary waves can be produced only of those wavelength λ for which,

$$L = \frac{n\lambda}{2}$$

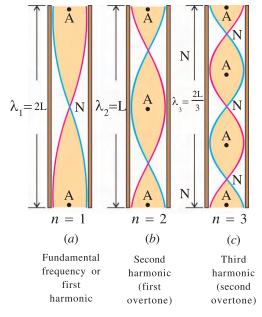
So, possible wavelenghts in pipe will be,

$$\lambda_n = \frac{2L}{n} \tag{8.10.5}$$

The frequency of a stationary waves in open pipe will be,

$$f_n = \frac{v}{\lambda_n} = \frac{nv}{2L} \tag{8.10.6}$$

where, v is speed of a wave.



Stationary waves in open pipes

Figure 8.15

(i) Substituting n = 1 in equation (8.10.6)

$$f_1 = \frac{v}{2L}$$
 (8.10.7)

Here, f_1 is called the **fundamental frequency** or the **first harmonics** (See Figure 8.15*a*) which is double than the fundamental frequency of a closed pipe. (: $f_1 = \frac{v}{4I}$).

(ii) Taking n = 2,

$$f_2 = \frac{2v}{2L} = \frac{v}{L} = 2f_1$$

 f_2 is called the **second harmonics** or **first overtone.**

Thus, taking different values of n in equation (8.10.6) third, fourth harmonics can be obtained. In general, for an open pipe the nth harmonic or (n-1)th overtone,

$$f_n = \frac{nv}{2L} = nf_1 \tag{8.10.8}$$

where, n = 1, 2, 3...

Thus, all the harmonics $(f_1, 2f_1, 3f_1...)$ are possible for an open pipe.

Thus, in both the types of the pipes there are normal mode of oscillation for the air columns of the pipes.

Illustration 16: If the second overtone of a closed pipe and third overtone of an open pipe are same, find the ratio of their lengths.

Solution:

For a closed pipe second overtone means fifth harmonics. Put n = 5, in following equation,

$$f = \frac{nv}{4L} = \frac{5v}{4L_1}$$

for an open pipe, third overtone means fourth harmonics. Put n = 4 in following equation,

$$f = \frac{nv}{2L} = \frac{4v}{2L_2}$$

Now, the frequency is same for both the pipes.

$$\frac{5v}{4L_1} = \frac{4v}{2L_2}$$

$$\therefore \frac{L_1}{L_2} = \frac{5}{8} \text{ OR } L_1 : L_2 = 5 : 8$$

Illustration 17: Air column of a resonance tube resonates with a tuning fork of frequency 800 Hz when its lengths is 9.75 cm. If the length of the air column is increased to 31.25 cm then also it resonates with the same tuning fork. Find speed of sound in air.

Solution : In the experiment of resonance tube, the arrangement of a closed pipe is obtained by immersing one end of a pipe in the water.

When oscillations are produced in the air column with the help of a tuning fork having frequency equal to the natural frequency of air column it oscillates with large amplitude, and large intense of sound is heard. This is a phenomenon of **resonance**.

Here, f = 800 Hz, $L_1 = 9.75 \text{ cm}$, $L_2 = 31.25 \text{ cm}$

Resonance tube is a closed pipe. For a closed pipe the natural frequency is given by

$$f = (2n - 1) \frac{v}{4L}$$

Taking n = 1 for first resonance,

$$f = \frac{v}{4L_1}$$

$$\therefore L_1 = \frac{v}{4f}$$

Taking n = 2 for second resonance,

$$f = (2 \times 2 - 1) \frac{v}{4L_2} = \frac{3v}{4L_2}$$

$$\therefore L_2 = \frac{3v}{4f}$$

$$\therefore L_2 - L_1 = \frac{3v}{4f} - \frac{v}{4f} = \frac{2v}{4f} = \frac{v}{2f}$$

$$\therefore$$
 Speed of sound $v = (L_2 - L_1)$ (2f)

$$= (31.25 - 9.75) (2 \times 800)$$

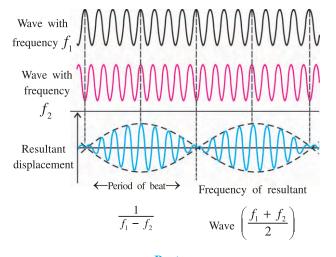
= 34400 cm/s

= 344 m/s

8.11 Beats

So far we have applied principle of superposition to two waves propagating in opposite direction with equal amplitude and equal frequency. It produces the non-progressive wave like stationary waves.

Let us now consider two waves having equal amplitudes and travelling in a medium in the same direction but having slightly different frequencies. Now we will apply principle of superposition to study the oscillation of a particle of a medium.



Beats
Figure 8.16

Suppose, two harmonic waves superpose at a particular position in the medium are,

$$y_1 = A \sin \omega_1 t = A \sin 2\pi f_1 t$$
 and $y_2 = A \sin \omega_2 t = A \sin 2\pi f_2 t$

Here, initial phase of both waves is zero. f_1 and f_2 are the frequency of first wave and second wave respectively.

Remember that here we are locally observing the effect of superposition of two waves on any one particle.

Suppose, at time t, the resultant displacement of a given particle is y then according to superposition principle,

$$y = y_1 + y_2$$

$$= A \sin 2\pi f_1 t + A \sin 2\pi f_2 t$$

$$\therefore y = \left[2A\cos 2\pi \left(\frac{f_1 - f_2}{2}\right)t\right] \sin 2\pi \left(\frac{f_1 + f_2}{2}\right)t$$
(8.11.1)

$$y = A'\sin 2\pi \left(\frac{f_1 + f_2}{2}\right)t$$

or
$$y = A' \sin 2\pi ft$$
 (8.11.2)

Above equation shows that the resultant oscillations of a given particle are the oscillation

with a frequency
$$f = \left(\frac{f_1 + f_2}{2}\right)$$
. Here, f is the

average of the two combining frequencies. The resultant amplitude is,

$$A' = 2A\cos 2\pi \left(\frac{f_1 - f_2}{2}\right)t$$
 (8.11.3)

and it changes periodically with time. Here, amplitude is a periodic function of time. Its

frequency is
$$\left(\frac{f_1 - f_2}{2}\right) = f'$$

Therefore, the period of oscillation is,

$$T = \frac{1}{f'} = \frac{2}{f_1 - f_2} \tag{8.11.4}$$

In time period T, the 'cosine' function attains its maximum value and zero twice. Hence, this function becomes f_1-f_2 times maximum in unit time. Therefore, the amplitude of oscillations becomes f_1-f_2 times maximum and f_1-f_2 times zero in unit time.

Foot Note:
$$\sin C + \sin D = 2\sin \left(\frac{C+D}{2}\right)\cos \left(\frac{C-D}{2}\right)$$

If these waves are sound waves, then loudness of sound is proportional to the square of the amplitude (I \propto A²), the loudness of sound also becomes $f_1 - f_2$ times maximum and $f_1 - f_2$ times zero in unit time.

Thus, phenomenon of the loudness of sound becoming maximum periodically due to superposition of two sound waves of equal amplitude and slightly different frequencies is called the 'beats'. The number of beats in unit time is $f_1 - f_2$. It is also called frequency of beat.

Note: In case of sound waves, in order to hear the beats clearly, $f_1 - f_2$ should not exceed about 6 to 7.

The phenomenon of beats can be experienced by taking two tuning forks of the same frequency and putting some wax on the prongs of one of the forks. Loading with wax decreases the frequency of a tuning fork a little. (By filling one of the prongs of a fork, its frequency will increase a little) When these two forks are vibrated and kept side by side, the listener can recognise the periodic variation of loudness of resulting sound. Musician tune their different musical instruments with the help of beat phenomenon.

Illustration 18: When two tuning forks A and B were sounded together, 20 beats were produced in 8 seconds. After loading one of the tuning forks with a little wax, they produce 32 beats in 8 seconds. If the unloaded fork had a frequency of 512 Hz. calculate the frequency of the other.

Solution : Suppose, tuning fork B is loaded with wax. Frequency of tuning fork A,

$$f_{\rm A} = 512 \text{ Hz}$$

Frequency of tuning fork B, $f_{\rm B} = ?$

Before loading wax, number of beats per second,

$$=\frac{20}{8}=2.5 \text{ Hz}$$

 \therefore Frequency of B before loading wax either 512 + 2.5 = 514.5 Hz

or
$$512 - 2.5 = 509.5$$
 Hz

After loading wax on B, beats per second = $\frac{32}{8}$ = 4 Hz. Frequency of B after loading is, either 512 + 4 = 516 Hz or 512 - 4 = 508 Hz

Since, after loading the wax frequency of a tuning fork B is lowered. In above calculation we can see that before loading wax, frequency of B is 509.5 Hz and after loading it is 508 Hz.

Hence, original frequency of B (i.e. before loading) will be 509.5 Hz.

8.12 Doppler Effect

Whenever there is a relative motion between a source of a sound and a listener with respect to medium in which the waves are propagating, the frequency of sound experienced by the listener is different from that which is emitted by the source. This phenomenon is called **Doppler effect.** This effect was discovered by Austrian physicist Johann Christian Doppler (1803–1853).

The frequency of sound of a whistle of the train is found to be more than original frequency and hence its sound appears more shrill (of higher pitch) when the train is approaching you. When it is passing by you, the frequency of sound experienced is same of that of actual sound emitted, and when the train is receding from you, the frequency listens lower than actual and sound appears less shrill than the actual.

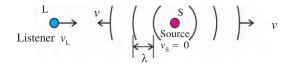
To understand Doppler effect, consider, as shown in Fig. 8.17, a listener moving with velocity $v_{\rm L}$ and a source of sound moving with a velocity $v_{\rm S}$ along straight line with respect to stationary air.

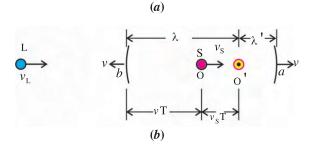
As a convention, the velocities in the direction from listener to source are considered as positive and from the source to the listener are considered as negative. The speed of sound is always considered positive. With this convention, we will obtain a general result from which other cases can be obtained easily.

Moving Listener: Suppose, a listener L moving with velocity v_L towards a stationary

sources S. (See Figure 8.17a) The source emits a sound wave with frequency $f_{\rm s}$ and wavelength

 $\lambda = \frac{v}{f_{\rm S}}$. Where, v is the speed of sound wave in air.





Doppler effect

Figure 8.17

These waves are travelling towards the listener. Hence, the speed of waves travelling towards the listener, relative to the listener will be $\nu + \nu_{\rm L}$. So the frequency $f_{\rm L}$ listened by the listener will be,

$$f_{\rm L} = \frac{v + v_{\rm L}}{\lambda} \tag{8.12.1}$$

Moving Source and Moving Listener: Now suppose the source is also moving with velocity v_s in the direction of L to S. (See Figure 8.17 b)

Let the source of sound (S) be at O at time t=0 and at O'at time t=T. Where, $T=\frac{1}{f_{\rm S}}$ is the periodic time of emitted sound.

Now, the distance travelled by the source in time T will be,

$$OO' = v_ST$$

The wave (crest) emitted by the source at t = 0 will cover the distance vT in time T. From the figure, Oa = Ob = vT

Now, at time t = T, the source is at O' and it emits successive wave (crest). The wave moving towards the listener will be in the region O'b and the wave moving away from the listener will be in region O'a.

The wavelength of the wave moving towards the listner,

 λ = Distance between successive wave (crest) in region O'b

$$= v_{S}T + vT$$

$$\therefore \lambda = \frac{v_S + v}{f_S} \ (\because \ T = \frac{1}{f_S}) \quad (8.12.3)$$

Substituting value of λ in equation (8.12.1)

$$f_{\rm L} = \frac{v + v_{\rm L}}{v + v_{\rm S}} \cdot f_{\rm S}$$
 (8.12.3)

or
$$\frac{f_{\rm L}}{v + v_{\rm L}} = \frac{f_{\rm S}}{v + v_{\rm S}}$$
 (8.12.4)

From the Figure (8.17) it is clear that the waves in the front of the source (region O'a) are compressed, hence the wavelength is decreasing due to motion of the source, while behind the source (region O'b) waves are stretched out hence its wavelength is increasing. Here, waves are travelling in the same medium (air), then why their wavelengths are changing? Think over it. The relative displacement of source and wave is responsible for that.

Some Special Cases:

(i) Listener is stationary and source is moving towards the listener, then according to the accepted conventions, taking $v_{\rm S}=-v_{\rm S}$ and $v_{\rm L}=0$ in equation (8.12.3), the frequency listened by listener,

$$f_{\rm L} = \frac{v}{v - v_{\rm S}} f_{\rm S}$$

i.e. listener will listen the frequency higher than the actual frequency ($f_{\rm L}>f_{\rm S}$).

(ii) Listener is stationary and source is moving away from the listener, then $v_L = 0$ and $v_S = +v_S$,

Frequency listened by listener $f_{\rm L} = \frac{v}{v + v_{\rm S}} f_{\rm S}$

This shows that $f_{\rm L} < f_{\rm S}$. i.e. Listener will hear the lower frequency than actual frequency.

(iii) Both the source and listener are approaching each other, then $v_L = +v_L$ and $v_S = -v_S$ Therefore,

$$f_{\rm L} = \frac{v + v_{\rm L}}{v - v_{\rm S}} f_{\rm S}$$

In this case, $f_{\rm L} > f_{\rm S}$

(iv) Both the source and listener are moving aways from each other, then $v_L = -v_L$ and $v_S = +v_S$

$$\therefore f_{\rm L} = \frac{v - v_{\rm L}}{v + v_{\rm S}} f_{\rm S}$$

In this case, $f_{\rm L} < f_{\rm S}$

In all these cases the medium (air) is considered stationary. If wind is blowing from the source to the listener (in the direction of velocity of sound) with velocity $v_{\rm w}$, the velocity of sound will be $v + v_{\rm w}$ and if the wind is blowing in opposite direction to the motion of sound waves, the velocity of sound will be $v - v_{\rm w}$.

Moreover, it is assumed that the velocities of the listener and of the source are less than the velocity of sound.

Illustration 19: A police siren emits a wave with frequency 300 Hz. The speed of sound is 340 m/s. (a) Find the wavelength of the waves in the air if the police car is at rest. (b) If the police car is moving at 108 km/h, find the wavelength of the waves in front and behind the car.

Solution : (a) When the police car is at rest, $f_S = 300 \text{ Hz}, v = 340 \text{ m/s}$

Wavelength of the waves emitted from the siren.

$$\lambda = \frac{v}{f_S} = \frac{340}{300} = 1.13 \text{ m}$$

(b) Speed of a police car $v_S = 108$ km/h = 30 m/s

Now,
$$f_{\rm L} = \frac{v + v_{\rm L}}{v + v_{\rm S}} f_{\rm S}$$

If the listener is in the region of the front of the moving car, then $v_1 = 0$, and $v_S = -v_S$

$$\therefore f_{\text{front}} = \frac{v}{v - v_{\text{S}}} f_{\text{S}}$$

$$\therefore \frac{v}{\lambda_{\text{front}}} = \frac{v}{v - v_{\text{S}}} f_{\text{S}}$$

$$\therefore \ \lambda_{\text{front}} = \frac{v - v_{\text{S}}}{f_{\text{S}}} = \frac{340 - 30}{300} = 1.033 \text{ m}$$

For behind the police car,

$$v_{\rm L} = 0$$
 and $v_{\rm S} = +v_{\rm S}$

$$f_{\text{behind}} = \frac{v}{v + v_{\text{S}}} f_{\text{S}}$$

$$\therefore \lambda_{\text{behind}} = \frac{v + v_{\text{S}}}{f_{\text{S}}} = \frac{340 + 30}{300} = 1.233 \text{m}$$

Illustration 20 : A SONAR system fixed in a stationary submarine in the sea operates at a frequency 40 kHz. An enemy submarine moves towards the SONAR with a speed of 360 kmh⁻¹. What is the frequency of sound reflected by the submarine ? The speed of sound in water is 1450 m s⁻¹.

Solution:
$$f_S = 40 \text{ kHz}, v = 1450 \text{ m/s}$$

The frequency of the waves from the SONAR will undergo a change in frequency in two steps.

(i) When the waves are moving towards the enemy's submarine which is in motion, the frequency of waves will change. In this case

SONAR is a source (S) and submarine is a listener (L).

Therefore, $v_S = 0$ and

$$v_{\rm L} = 360 \text{ km/h} = \frac{360 \times 1000}{3600} = 100 \text{ m/s}$$

Now,
$$f_{L_1} = \frac{v + v_L}{v + v_S} \times f_S$$

= $\frac{1450 + 100}{1450 + 0} \times 40 \times 10^3$
= 42.758 kHz

(ii) The enemy submarine will reflect waves of frequency 42.758 kHz and will act as a source of waves, while SONAR will act as a listener (L).

$$f_{\rm S} = 42.758 \text{ kHz}, v_{\rm I} = 0, v_{\rm S} = -100 \text{ m/s}$$

Frequency of reflected wave,

$$f_{L_2} = \frac{v + v_L}{v + v_S} \times f_S$$

$$= \frac{1450 + 0}{1450 - 100} \times 42.758 \times 10^3$$

$$= 45.92 \text{ kHz}$$

Thus the frequency of reflected waves from submarine, moving towards SONAR is 45.92 kHz.

SUMMARY

- 1. Waves: The motion of the disturbance in the medium (or in free space) is called wave pulse or generally a wave.
- **2. Amplitude of a wave :** Amplitude of oscillation of particles of the medium is called the amplitude of a wave.
- 3. Wavelength and frequency: The linear distance between any two points or particles having phase difference of 2π rad is called the wavelength (λ) of the wave.

Frequency of wave is just the frequency of oscillation of particles of the medium. Relation between wavelength and frequency:

$$v = f$$
, $\lambda = \frac{\omega}{k}$, where, v is the speed of wave in the medium.

- **4. Mechanical waves**: The waves which require elastic medium for their transmission are called mechanical waves. e.g. sound waves.
- **5.** Transverse and longitudinal waves: Waves in which the oscillations are in a direction perpendicular to the direction of wave propagation are called the transverse wave.

Waves in which the oscillations of the particles of medium are along the direction of wave propagation are called longitudinal waves.

6. Wave Equation: The equation which describe the displacement for any particle of medium at a required time is called wave equation. Various forms of wave equations are as follows:

(i)
$$y = A \sin (\omega t - kx)$$
 (ii) $y = A \sin \left(\frac{t}{T} - \frac{x}{\lambda}\right)$

(iii)
$$y = A \sin 2\pi f \left(t - \frac{x}{v}\right)$$
 (iv) $y = A \sin \frac{2\pi}{\lambda} (vt - x)$

The above equations are for the wave travelling in the direction of increasing value of x. If the wave is travelling in the direction of decreasing value of x then put '+' instead of '-' in above equations.

- 7. The elasticity and inertia of the medium are necessary for the propagation of the mechanical waves.
- 8. The speed of the transverse waves in a medium like string kept under tension, \sqrt{T}

$$v = \sqrt{\frac{T}{\mu}}$$

where, T = Tension in the string and μ = mass per unit length of the string = $\frac{m}{L}$

9. Speed of sound waves in elastic medium, $v = \sqrt{\frac{E}{\rho}}$

where, E = Elastic constant of a medium, $\rho = Density$ of the medium.

Speed of longitudinal waves in a fluid, $v = \sqrt{\frac{B}{\rho}} = \sqrt{\frac{\gamma P}{\rho}}$

where, B = Bulk modulus of a medium $\gamma = \frac{C_P}{C_V} = 1.41$ (for air)

Speed of longitudinal waves in a linear medium like a rod, $v = \sqrt{\frac{y}{\rho}}$

where, y = Young modulus, $\rho = \text{Density of a medium}$

At constant pressure and constant humidity, speed of sound waves in gas is directly proportional to the square root of its absolute temperature.

$$v = \sqrt{\frac{\gamma RT}{M}} : v \propto \sqrt{T}$$

The speed of sound in a gas does not depend on the pressure variation.

- 10. Principle of Superposition: When a particle of medium comes under the influence of two or more waves simultaneously, its net displacement is the vector sum of displacement that could occur under the influence of the individual waves.
- 11. Stationary Waves: When two waves having same amplitude and frequency and travelling in mutually opposite directions are superposed the resultant wave formed loses the property of propagation. Such a wave is called a stationary wave.

Equation of stationary wave : y = -2 A $\sin kx \cos \omega t$

Amplitude of stationary wave : 2 A $\sin kx$

Position of nodes in stationary wave $x_n = \frac{n\lambda}{2}$

where, n = 1, 2, 3... At all these points the amplitude is zero.

Position of antinodes in stationary waves,

$$x_n = (2n - 1)\frac{\lambda}{4}$$
 where , $n = 1, 2, 3,...$

The amplitude of all these points is 2A.

12. Frequencies corresponding to different normal modes of vibration in a stretched string of length L fixed at both the ends are given by,

$$f_n = \frac{nv}{2L} = \frac{n}{2L} \sqrt{\frac{T}{\mu}}$$
 where $n = 1, 2, 3...$

13. In a closed pipe the values of possible wavelengths required for stationary wave pattern are given by.

$$\lambda_n = \frac{4L}{(2n-1)}$$
 and possible frequencies, $f_n = (2n-1)\frac{v}{4L} = (2n-1)f_1$

where, n = 1, 2, 3,... and L = length of pipe.

In a closed pipe only odd harmonics like f_1 , $3f_1$, $5f_1$, are possible.

14. In an open pipe the values of possible wavelength required for stationary waves are given by,

$$\lambda_n = \frac{2L}{n}$$
 and possible frequencies, $f_n = \frac{nv}{2L} = nf_1$ where, $n = 1, 2, 3, \dots$ and $L = \text{length of pipe}$.

In open pipe of the harmonics like f_1 , $2f_1$, $3f_1$, are possible.

15. Beat : The phenomenon of the loudness of sound becoming maximum periodically due to superposition of two sound waves of equal amplitude and slightly different frequencies is called the 'beats'.

Number of beats produced in unit time = $f_1 - f_2$

16. Doppler Effect: Whenever there is a relative motion between a source of sound and a listener with respect to the medium in which the waves are propagating the frequency of sound experienced by the listener is different from that which is emitted by the source. This phenomenon is called Doppler effect.

Frequency listened by the listener,
$$f_{\rm L} = \frac{v \pm v_{\rm L}}{v \pm v_{\rm S}} f_{\rm S}$$

Where, v = velocity of sound, $v_1 = \text{velocity of a listener}$,

 $v_{\rm S}$ = velocity of a source, $f_{\rm S}$ = frequency of sound emitted by the source.

EXERCISES

Choose the correct option from the given options:

Mechanical waves carry

(A) energy

(B) matter

(C) both energy and matter

(D) neither energy nor matter.

2. A tuning fork makes 256 vibrations per second in air. When the velocity of sound is 330 m/s, then wavelength of the wave emitted is

(A) 0.56 cm

(B) 0.89 m

(C) 1.11 m

(D) 1.29 m

When a sound wave of frequency 300 Hz passes through a medium, the **3.** maximum displacement of a particle of the medium is 0.1 cm. The maximum velocity of the particle is equal to

(A) 60π cm/s

(B) 30π cm/s

(C) 30 cm/s

(D) 60 cm/s

The speed of wave of frequency 500 Hz is 360 m s⁻¹. The minimum distance between two particles on it, having phase difference of 60° is

(A) 0.23 m

(B) 0.12 m

(C) 8.33 m

(D) 60 m

If the speed of the wave shown in the Figure is 330 m/s in the given medium, then the equation of the wave propagating in the positive *x*-direction will be

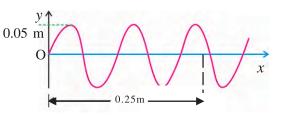


Figure 8.18

(A) $y = 0.05 \sin 2\pi (4000 t - 12.5x) m$

(B) $y = 0.05 \sin 2\pi (4000 t - 122.5x) \text{ m}$

(C) $y = 0.05 \sin 2\pi (3300 t - 10x) m$

(D) $y = 0.05 \sin 2\pi$ (3300 t - 10t) m

The equation $y = A \sin^2 (kx - \omega t)$ represents a wave with amplitude and frequency

(A) A, $\omega/2\pi$

(B) $\frac{A}{2}$, $\frac{\omega}{\pi}$ (C) 2A, $\frac{\omega}{4\pi}$ (D) \sqrt{A} , $\frac{\omega}{2\pi}$

Two pulse travels in mutually opposite directions in a string with a speed of 2.5 cm/s as shown in figure. Initially (at t = 0) the pulses are 10 cm apart. What will be the state of string after two seconds?

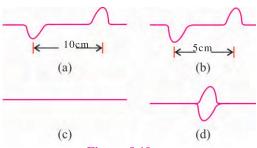


Figure 8.19

The speed of the component waves of a stationary wave represented by $y = 10 \sin (100 t) \cos (0.01x)$ is

Where, x and y are in metre and t is in second.

 1 m s^{-1} (A)

(B) 10^2 m s^{-1} (C) 10^3 m s^{-1} (D) 10^4 m s^{-1}

9.	The mass of 7 m long string is 0.035 kg. If the tension in the string is 60.5 N, then the speed of wave on string will be				
	(A) 77 m s^{-1}	(B) 102 m s ⁻¹	(C) 110 m s^{-1}	(D) 165 m s ⁻¹	
10	` /	• •	* *	* /	
10.		•	•	superposition of two	
	waves is x times th	e intensity of supe	rposing wave then	$x = \dots$	
	(A) 1	(B) $\sqrt{2}$	(C) 2	(D) 4	
11.	Two waves of wave	elengths 2.00 m and	d 2.02 m superpos	se with each other to	
		•		he same, their same	
	speed is	s. If the speed c	of both waves is t	ne same, then same	
	•	(B) 402 m/s	(C) 404 m/s	(D) 406 m/s	
10	(A) 400 m/s	` ′	` '	(D) 406 m/s	
12.	2. The speed of the component waves of a stationary wave is 1200 m/s. I distance between consecutive antinode and node is 1 m, then frequence				
			e and node is 1 n	n, then frequency of	
	standing wave will	be			
	(A) 300 Hz	(B) 400 Hz	(C) 600 Hz	(D) 1200 Hz	
13.	Suppose the listener	and sound source	both are approach	hing each other with	
	speed of 50 m/s on	a straight path. If	the v frequency 1	istened by listener is	
	-		* *	the source ? (speed	
	of wave in air is 34	• •	wave produced by	are source . (speed	
			1	1	
	(A) 327 s^{-1}	(B) 367 s^{-1}	(C) 390 s^{-1}	(D) 591 s^{-1}	
14.	The fundamental from	equency of the air	column in a close	d pipe is 512 Hz. If	
		*		equency will be	
	Hz.				
	(A) 1024	(B) 512	(C) 256	(D) 128	
1.5	(11) 1021	(2)			
	The oir column in o	alacad mima armani	anaaa finat maaanan	as with a tuning foul.	
15.				ce with a tuning fork	
15.	of frequency 264 H	z. If the length of t	the air column in t	ce with a tuning fork he closed pipe is	
15.		z. If the length of t	the air column in t	•	
15.	of frequency 264 H	z. If the length of t	the air column in t	•	
	of frequency 264 Hz cm. The speed of the	z. If the length of the sound in air is 3 (B) 62.50	the air column in to 330 m/s. (C) 93.75	he closed pipe is (D) 125	
	of frequency 264 Hz cm. The speed of the (A) 31.25 When the temperature	z. If the length of the sound in air is 3 (B) 62.50 are of an ideal gas	the air column in to 330 m/s. (C) 93.75 is increased by 60	he closed pipe is (D) 125 00 K, the velocity of	
	of frequency 264 Hz cm. The speed of the (A) 31.25 When the temperatus sound in the gas be	z. If the length of the sound in air is 3 (B) 62.50 are of an ideal gas comes $\sqrt{3}$ times the	the air column in to 330 m/s. (C) 93.75 is increased by 60	he closed pipe is (D) 125	
	of frequency 264 Hz cm. The speed of the (A) 31.25 When the temperature sound in the gas be perature of the gas	z. If the length of the sound in air is $\frac{3}{6}$ (B) $\frac{62.50}{62.50}$ are of an ideal gas comes $\sqrt{3}$ times the is	the air column in to the air column in the air c	(D) 125 00 K, the velocity of in it. The initial tem-	
	of frequency 264 Hz cm. The speed of the (A) 31.25 When the temperatus sound in the gas be	z. If the length of the sound in air is 3 (B) 62.50 are of an ideal gas comes $\sqrt{3}$ times the	the air column in to the air column in the air c	he closed pipe is (D) 125 00 K, the velocity of	
16.	of frequency 264 H. cm. The speed of the (A) 31.25 When the temperature sound in the gas be perature of the gas (A) -73 °C	z. If the length of the sound in air is $\frac{3}{6}$ (B) $\frac{62.50}{62.50}$ are of an ideal gas comes $\sqrt{3}$ times the is	the air column in to the air column in the air c	(D) 125 00 K, the velocity of in it. The initial tem-	
16.	of frequency 264 Hz cm. The speed of the (A) 31.25 When the temperatus sound in the gas be perature of the gas (A) -73 °C Beats are produced	z. If the length of the sound in air is $\frac{3}{2}$ (B) $\frac{62.50}{1}$ are of an ideal gas comes $\sqrt{3}$ times the is	the air column in to 330 m/s. (C) 93.75 is increased by 60 the initial velocity in the initial velo	the closed pipe is (D) 125 00 K, the velocity of in it. The initial tem- (D) 327 °C in $(2000\pi)t$ (m) and	
16.	of frequency 264 Hz cm. The speed of the (A) 31.25 When the temperature sound in the gas be perature of the gas (A) -73 °C Beats are produced $y_2 = A \sin(2008\pi)$	z. If the length of the sound in air is 3 (B) 62.50 are of an ideal gas comes √3 times the is	the air column in the air column in the air column in the same of the air column in the same of (C) 93.75 is increased by 60 the initial velocity in (C) 127 °C where (C) 128 °C	the closed pipe is (D) 125 00 K, the velocity of in it. The initial tem- (D) 327 °C in $(2000\pi)t$ (m) and er second is	
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16. 17.	of frequency 264 Hz cm. The speed of the (A) 31.25 When the temperatus sound in the gas be perature of the gas (A) -73 °C Beats are produced $y_2 = A \sin(2008\pi)$ (A) 0 A source of sound speed of sound. The	z. If the length of the sound in air is 3 (B) 62.50 are of an ideal gas comes √3 times the is	the air column in to 330 m/s. (C) 93.75 is increased by 60 the initial velocity in the initial velo	the closed pipe is (D) 125 00 K, the velocity of in it. The initial tem- (D) 327 °C (a) $(2000\pi)t$ (m) and er second is (D) 8 there with 1/10 of the is	
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> 20. The temperature at which speed of sound in air becomes double of its value at 0°C is

(A) 273 K

(B) 546 K

(C) 1092 K

(D) 0 K

ANSWERS

4. (B)

1. (A) **2.** (D) 3. (A)

5. (C)

6. (B)

7. (C)

9. (C) **10.** (D) **11.** (C)

12. (A)

13. (A)

8. (D) **14.** (A)

15. (A) **16.** (B) 17. (C)

18. (A)

19. (C) **20.** (C)

Answer the following questions in short:

- Give the definition of wave intensity and give its SI unit. 1.
- What is angular wave number of a wave ? 2.
- 3. What is the distance travelled by the progressive wave if its wavelength is λ and frequency is f?
- Which characteristics of a medium are required for the propagation of 4. mechanical wave?
- What is pressure wave?
- How the wave speed is changing with change in the temperature of a medium?
- What will be change in the speed of a wave in wire if the tension in wire increased four times?
- What will be the effect on the speed of a wave if the pressure of the medium will change?
- The wave equation of a wave is $y = 5 \sin (0.01x 2t)$. Where x and y are in cm. What is the speed of a wave?
- 10. What will be the change in the phase of a wave, if the wave on the string is reflected from the rigid support?
- 11. What is the amplitude of node and antinode in a stationary wave?
- 12. What is the distance between consecutive antinode in a stationary wave if the distance between consecutive node and antinode is 5 cm?
- 13. In a closed pipe fundamental frequency is 300 Hz. What will be the frequency of second overtone?
- 14. Frequency of the source of sound is 440 Hz. If the relative velocity of source and listener is zero then which frequency will be listened by a listener?
- 15. What is a beat?

Answer the following questions:

- Explain the classification of the waves. Give the example of each wave.
- 2. Explain wavelength, wave number and frequency of a wave.
- With the help of dimensional analysis, obtain the expression for the wave speed 3. propagating in the string kept under tension.
- Explain the propagation of sound waves in the air. 4.
- **5.** Write the Newton's formula for speed of a wave in air. Expain Laplace correction in Newton's formula.

6. Obtain the one dimension wave equation $y = A \sin(\omega t - kx)$ for the wave propagating in the direction of increasing value of x.

- 7. Write the superposition principle for the waves and explain it.
- **8.** What are stationary waves ? Obtain the expression for the stationary wave in case of string fixed at its two ends.
- **9.** Show that in a closed pipe the harmonics are possible only for odd multiples of fundamental frequency.
- 10. What is Doppler effect? When the source of sound is stationary and listener is moving towards the source, obtain the expression for the wavelength of wave travelling towards the listner.

Solve the following problems:

- 1. In case of the progressive harmonic waves, prove that the ratio of the instantaneous velocity of any particle of the medium to the wave speed is equal to the negative of the slope of the waveform at that point at that instant.
- 2. Two types of waves, transverse (S) and longitudinal (P) are produced in the earth during an earthquake. The speed of the S wave is approximately 4.0 km/s and that of the P wave is 8.0 km/s. In a seismograph, recording the earthquake the P wave is recorded 4 min earlier than the S wave. Assuming that both types of waves travel on straight line, find the distance of the origin of the quake from the seismograph.

 [Ans.: Approximately 1920 km]
- 3. The amplitude of the progressive harmonic wave is 10 m. During the wave propagation, the displacement of a particle which is at a distance of 2 m from the origin is 5 m after 2 s. Another particle which is at 16 m from origin has displacement of $5\sqrt{3}$ m in 8 s. Find the angular frequency and wave vector of a wave.

 [Ans.: $\omega = \pi/8$ rad/s, $k = \pi/24$ rad/m]
- 4. The equation for a wave travelling in x-direction on a string is, $y = 3 \sin \left[(3.14x (314)t] \right]$. Where x is in cm and t is in second.
 - (i) Find the maximum velocity of a particle of the string.
 - (ii) Find the acceleration of a particle at x = 6.0 cm at time = t = 0.11 s.

[Ans.: Maximum velocity = 9.4 m/s, a = 0]

- 5. At 0 °C temperature, a source of sound of frequency 250 Hz emits sound waves of wavelength 1.32 m. What will be the increase in wavelength at 27 °C?

 [Ans.: 0.06 m]
- 6. At what temperature the hydrogen gas will have the speed of sound waves in it will be equal to the speed of sound in oxygen at 1200 °C? The density of oxygen is 16 times that of hydrogen.

 [Ans.:—180.9 °C]
- 7. The length of a sonometer wire between its fixed ends is 110 cm. Where should the two bridges S_1 and S_2 be placed in between the ends so as to divide the wire into 3 segments whose fundamental frequencies are $f_1:f_2:f_3=1:2:3$?

 [Ans.: $L_1=60$ cm, $L_2=30$ cm, $L_3=20$ cm]

8. A wire having a linear mass density 0.05 g/cm is stretched betwen two rigid supports with a tension of 450 N. The wire resonates at a frequency of 420 Hz. The next higher frequency at which the same wire resonates is 490 Hz. Find the length of the wire.

[Ans.: 2.1 m]

9. The length of a string is 100 cm. The frequencies of two consecutive harmonics formed on the string are 300 Hz and 400 Hz respectively. The maximum amplitude is 10 cm when the string oscillates with its fundamental frequency. Write the equation of the stationary wave in this case.

[Ans.:
$$y = -10\sin\left(\frac{\pi x}{100}\right)\cos(200\pi)t$$
 (cm)]

- 10. Find the difference of apparent frequencies of the sound of a car horn heard by a stationary listener when the car is moving towards and away from the listener with a speed 54 km/4. The frequency of sound emitted by the horn is 500 Hz and speed of sound in air is 340 m/s.

 [Ans.: 44.2 Hz]
- 11. The whistle of an engine, approaching a hill with a speed of 10 m/s produces sound of frequency 660 Hz. Find the frequency experienced by the driver of the sound reflected from the hill. The speed of sound in air is 340 m/s.

[**Ans.**: 700 Hz]

• • •



Meghnad Saha (1893-1956)

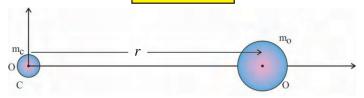
Meghnad Saha was born on October 6, 1893 in Sheoratali, a village in the District of Dacca (now in Bangladesh). In 1911, he came to Calcutta to study in Presidency College. He came to be recognised as a scientist of substance. In 1920, he went to England to prove his theory—equation of

reaction—before the global scientific community. This later became Saha's Thermo Ionization Equation. In 1927, Meghnad was elected as a fellow of London's Royal Society. He invented an instrument to measure the weight and pressure of solar rays. The lasting memorial to him is the 'Saha Institute of Nuclear Physics' founded in 1943 in Calcutta. Saha passed away on February 16, 1956.

SOLUTION

CHAPTER

1.



Figure

Here the origin is taken on the centre of carbon (C).

 $r = \text{distance of oxygen from carbon} = 1.130 \times 10^{-10} \,\text{m},$

 $m_{\rm O} = {\rm mass~of~oxygen} = 16~{\rm g~mol^{-1}}, m_{\rm C} = {\rm mass~of~carbon} = 12~{\rm g~mol^{-1}}$

 $r_{\rm C}$ = distance of carbon from origin = 0, $r_{\rm O}$ = distance of oxygen from origin = r = 1.130 × 10⁻¹m

$$\therefore r_{cm} = \frac{m_{\rm C}r_{\rm C} + m_{\rm O}r_{\rm O}}{m_{\rm C} + m_{\rm O}}$$

- 2. Velocity of centre of mass $\overrightarrow{v}_{cm} = \frac{\overrightarrow{m_1} \overrightarrow{v_1} + \overrightarrow{m_2} \overrightarrow{v_2} + \overrightarrow{m_3} \overrightarrow{v_3}}{\overrightarrow{m_1} + \overrightarrow{m_2} + \overrightarrow{m_3}}$
- 3. Here for car $m_1 = 1000$ kg, $a_1 = 4.0$ m s⁻², initial speed $v_{0_1} = 0$ m s⁻¹ For truck $m_2 = 2000$ kg, $a_2 = 0$ m s⁻², $v_{0_2} = v_2 = 8.0$ m s⁻¹ After 3 sec, the speed of car $v_1 = v_{0_1} + a_1 t$

After 3 secs the distance travelled by car $d_1 = v_{01}t + \frac{1}{2}a_1t^2$

The distance travelled by truck in 3 sec. $d_2 = v_2 t \ (\because \ a_2 = 0)$

(a) The distance of centre of mass of the system of car-truck is

$$d_{cm} = \frac{m_1 d_1 + m_2 d_2}{m_1 + m_2}$$

(b) In one dimension $Mv_{cm} = m_1v_1 + m_2v_2$

$$\therefore v_{cm} = \frac{m_1 v_1 + m_2 v_2}{m_1 + m_2} \quad (\because M = m_1 + m_2)$$

4. At t = 0 sec. $x_1 = -15 m$, $x_2 = 15 m$ $m_1 = 40 \text{ kg}$, $m_2 = 20 \text{ kg}$

$$\therefore x_{cm} = \frac{m_1 x_1 + m_2 x_2}{m_1 + m_2}$$

As the centre of mass is remaining stationary, $x_{cm} = \text{const.}$ Hence find x_2 from the values of x_1 and x_{cm} for t=2, 4, 6 sec. At t=0, the cat and dog are at rest.

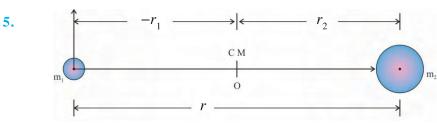
$$\therefore v_1 = v_2 = 0 \Rightarrow p_1 = p_2 = 0$$
$$\Rightarrow p = p_1 + p_2 = 0$$

At t = 2 s

$$v_1 = \frac{x_1(2 \text{ s}) - x_1(0 \text{ s})}{2 \text{ s}} = \frac{\Delta x}{\Delta t}, v_2 = \frac{x_2(2 \text{ s}) - x_2(0 \text{ s})}{2 \text{ s}}$$

Hence, $p_1 = m_1 v_1$, $p_2 = m_2 v_2$ and $p = p_1 + p_2$

Similarly, repeat calculations for t = 4 s and t = 6 s.



Figure

In figure, the origin is taken at centre of mass.

 \therefore Position of m₁ from origin = $-r_1$, Position of m₂ from origin = r_2

$$\therefore r_{cm} = 0 = \frac{m_1(-r_1) + m_2 r_2}{m_1 + m_2} \qquad \therefore m_1 r_1 = m_2 r_2$$

$$\therefore \frac{m_1}{m_2} = \frac{r_2}{r_1}$$
(1)

Performing union in the denominator $\frac{m_1}{m_1 + m_2} = \frac{r_1}{r_1 + r_2} = \frac{r_2}{r}$

$$(:: r = r_1 + r_2) :: r_2 = r \left[\frac{m_1}{m_1 + m_2} \right]$$

Performing union in numerator in equation (1) $\frac{m_1 + m_2}{m_2} = \frac{r_1 + r_2}{r_1} = \frac{r}{r_1}$

$$\therefore r_1 = r \left\lfloor \frac{m_2}{m_1 + m_2} \right\rfloor$$

6. Here, the centre of mass of the system made up of three spheres is

$$\vec{r}_{cm} = \frac{\vec{m} \vec{r}_{cm1} + \vec{m} \vec{r}_{cm2} + \vec{m} \vec{r}_{cm3}}{m + m + m}$$
, Where $\vec{r}_{cm1} = \text{centre of mass of sphere}$
1. etc.

7. Here, the density of sphere of radius R is ρ . Hence, the mass of original sphere

$$M = \rho V = \rho \times \frac{4}{3} \pi R^3 \tag{i}$$

The mass of small sphere of radius 'a' is $m_1 = \rho \times \frac{4}{3} \pi a^3$ (ii)

Hence, the mass of the remaining sphere after removing small sphere of radius 'a' from the original sphere of radius 'R' is $m_2 = M - m_1$.

$$\therefore m_2 = \frac{4}{3}\pi\rho \ (\mathbb{R}^3 - a^3) \tag{iii}$$

The centre of mass of original sphere $r_{cm} = (0, 0, 0)$

The centre of mass of small sphere of radius 'a', $\vec{r_1} = (b, 0, 0)$

The remaining sphere has symmetry about X-axis, but no symmetry about Y and Z axes. Hence, the centre of mass of remaining sphere is, say

$$\stackrel{\rightarrow}{r_2} = (-x, 0, 0)$$

The sphere of radius R is made up of small sphere of radius 'a' and the

remaining sphere (without small sphere). Hence, $M \overset{\rightarrow}{r_{cm}} = m_1 \overset{\rightarrow}{r_1} + m_2 \overset{\rightarrow}{r_2}$. $M(0, 0, 0) = m_1(b, 0, 0) + m_2(-x, 0, 0)$. Comparing x co-ordinates

$$M(0) = m_1 b - m_2 x : x = \frac{m_1}{m_2} b$$
 (iv)

Using results (ii) and (iii), we get x.

8. From the figure, the masses of the three particles, the positions and forces acting on them during steady positions are

$$m_1 = 4.0 \text{ kg},$$
 $\overrightarrow{r_1} = (-2, 3) m,$ $\overrightarrow{F_1} = (-6, 0) \text{ N}$
 $m_2 = 8.0 \text{ kg},$ $\overrightarrow{r_2} = (4, 2) m,$ $\overrightarrow{F_2} = (12 \cos 45^\circ, 12 \sin 45^\circ) \text{ N}$
 $m_3 = 4.0 \text{ kg},$ $\overrightarrow{r_3} = (1, -2) m,$ $\overrightarrow{F_3} = (14, 0) \text{ N}$
 $\therefore \overrightarrow{r_{cm}} = \frac{m_1 \overrightarrow{r_1} + m_2 \overrightarrow{r_2} + m_3 \overrightarrow{r_3}}{m_1 + m_2 + m_3}$

According to the Newton's second law $\overrightarrow{F} = \overrightarrow{Ma_{cm}}$, $\overrightarrow{M} = m_1 + m_2 + m_3$

$$\therefore \vec{F}_1 + \vec{F}_2 + \vec{F}_3 = M \overrightarrow{a_{cm}} \qquad \qquad \therefore \vec{a}_{cm} = \frac{\vec{F}_1 + \vec{F}_2 + \vec{F}_3}{M}$$

$$\therefore \vec{a}_{cm} = (a_{x_{cm}}, a_{y_{cm}})$$

Hence the magnitude of acceleration $|\overrightarrow{a}_{cm}| = \sqrt{(a_{x_{cm}})^2 + (a_{y_{cm}})^2}$

and the direction of acceleration with X-axis is $\theta = tan^{-1} \left(\frac{a_{ycm}}{a_{xcm}} \right) = \dots$

9. From the figure, the centre of mass of the original plate of uniform density 'ρ'

and radius 'R' is
$$\overrightarrow{r}_{cm} = (0, 0)$$
 (1)

The centre of mass of plate of radius
$$\frac{\mathbf{R}}{2}$$
 is $r_{cm_1} = \left(\frac{\mathbf{R}}{2}, 0\right)$ (2)

When the plate of radius $\frac{R}{2}$ is cut from the plate of radius R, the remaining plate has symmetry about X-axis, but no symmetry about Y-axis. Hence the

centre of mass of remaining plate must be away from the origin along X-axis

as say
$$(-x)$$
. $\therefore r_{cm_2} = (-x, 0)$ (3)

The original plate is made up plate of radius $\frac{R}{2}$ and remaining plate

$$\therefore \vec{r}_{cm} = \frac{\vec{M}_1 \vec{r}_{cm1} + \vec{M}_2 \vec{r}_{cm2}}{\vec{M}_1 + \vec{M}_2}$$

$$(4)$$

Where $M_1 = Mass$ of plate of radius $\frac{R}{2}$: $M_1 = \pi \left(\frac{R}{2}\right)^2 t\rho$

 $M_2 = Mass$ of remaining plate = $\pi R^2 t \rho - M_1 = \pi R^2 t \rho - \pi \left(\frac{R}{2}\right)^2 t \rho$

$$M_2 = \pi t \rho \left[R^2 - \left(\frac{R}{2} \right)^2 \right]$$

Where ρ = Density of plate, t = thickness of plate

Hence, from equation (4) calculate r_{cm2} .

CHAPTER 2

- 1. Using equation $\theta = \left(\frac{\omega + \omega_0}{2}\right)t$ find ω_0 . Substituting ω_0 in the equation $\theta = \omega_0 t + \frac{1}{2}\alpha t^2$ find α .
- 2. Substituting values $\theta = \omega_0 t + \frac{1}{2} \alpha t^2$ find α . Now from $\theta = \frac{\omega^2 + \omega_0^2}{2\alpha}$ find θ and represent θ in rotations $(2\pi \text{ rad} = 1 \text{ rotation})$
- 3. Using $\alpha = \frac{\omega \omega_0}{t}$, find α . Now $I = m \ r^2$, using $\tau = I\alpha$, find τ from $\theta = \frac{\omega^2 + \omega_0^2}{2\alpha}$ find θ . Now work $= \tau \cdot \theta$
- 4. Use $\vec{l} = \vec{r} \times \vec{p}$, $\vec{r} = 4\hat{i} + 6\hat{j} + 12\hat{k}$ and $\vec{p} = \vec{m} = 50 (2\hat{i} + 3\hat{j} + 6\hat{k})$
- 5. Linear acceleration for a body rolling down the slope is $a = \frac{g \sin \theta}{\left[1 + \frac{K^2}{R^2}\right]}$

Substituting K = R the radius of gyration for hollow cylinder obtain a.

6. Moment of inertia of the system $I_z = I_{1z} + I_{2z}$. $I_{1z} =$ Moment of inertia of the object of 100 kg relative to z axis $I_{2z} =$ moment of inertia of the object of 200 kg relative to z axis. As the distances are relative to z axis, z coordinate is not taken in to calculation.

$$I_z = I_x + I_y = m(x^2 + y^2)$$
 (1)

position vectors for the objects of 100 kg and 200 kg are (2, 4, 6) and (3, 5, 7) respectively.

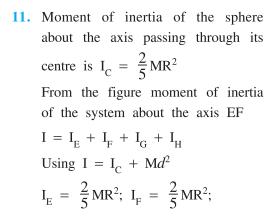
$$\therefore I_{1z} = I_{1x_{1}} + I_{2y_{1}} = 100 (x_{1}^{2} + y_{1}^{2}), I_{2z} = I_{1x_{2}} + I_{2y_{2}} = 200 (x_{2}^{2} + y_{2}^{2})$$
Substitute in (1)

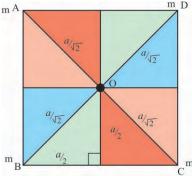
7. Using $K = \sqrt{\frac{2}{5}} R$ for solid sphere in $v^2 = \frac{g \sin \theta}{\left[1 + \frac{K^2}{R^2}\right]}$ find v.

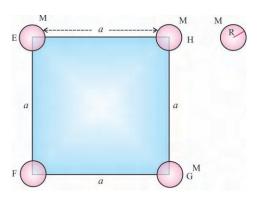
Now using $mgh = \frac{1}{2}mv^2 + \frac{1}{2}I\omega^2$. Calculate rotational kinetic energy. $(\frac{1}{2}I\omega^2)$

- 8. Consider Earth as solid sphere and taking its moment of inertia $I=\frac{2}{5}MR^2$ and $\omega=\frac{2\pi}{T}=\frac{2\pi}{24\times3600}$ substitute in $L=I\omega$ and obtain L.
- 9. $I_1 = I_C + Md_1^2$ $\therefore I_C = I_1 Md_1^2$ Now $I_2 = I_C + Md_2^2 = I_1 - Md_1^2 + Md_2^2$ $= I_1 + M(d_2^2 - d_1^2)$
- **10.** From the figure the moment of inertia I of the system about the axis passing through O.

$$I = \frac{ma^2}{2} + \frac{ma^2}{2} +$$







$$\begin{split} & I_G = \frac{2}{5}MR^2 + Ma^2; \ I_H = \frac{2}{5}MR^2 + Ma^2 \\ & \therefore \ I = \frac{2}{5}MR^2 + \frac{2}{5}MR^2 + \frac{2}{5}MR^2 + ma^2 + .\frac{2}{5}MR^2 + ma^2 \\ & = 2\Big(\frac{4}{5}MR^2 + Ma^2\Big) \end{split}$$

12. $r_1 = 0$, $r_2 = 2m$, $r_3 = 4m$, $r_4 = 6m$, $m_1 = 1$ kg, $m_2 = 2$ kg, $m_3 = 3$ kg, $m_4 = 4$ kg

Now,
$$I_{AB} = m_1 r_1^2 + m_2 r_2^2 + m_3 r_3^2 + m_4 r_4^2$$

13. Total kinetic energy = Linear kinetic energy + Rotational kinetic energy

$$= \frac{1}{2}mv^2 + \frac{1}{2}\operatorname{I}\omega^2$$

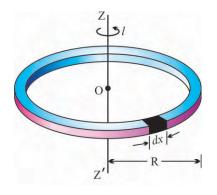
for disc I = $\frac{mr^2}{2}$ substituting $\omega = \frac{v}{r}$ (: $v = r\omega$)

Total kinetic energy =
$$\frac{1}{2}mv^2 + \frac{1}{2}\frac{mr^2}{2}\frac{v^2}{r^2} = \frac{3}{4}mv^2$$

Rotational kinetic energy = $\frac{1}{4}mv^2$

The fraction of total kinetic energy in the form of rotational kinetic energy $= \frac{\frac{1}{4}mv^2}{\frac{3}{4}mv^2} = \frac{1}{3}$

14. To find moment of inertia of thin circular ring or circular wire about an axis passing through its centre and perpendicular to its plane and radius of gyration, consider a thin ring with mass M and radius R as shown in the figure. Length of the ring l that is the circumference of the ring is $2\pi R$.



Mass per unit length of this ring

$$\lambda = \frac{Mass \ of \ the \ ring}{Length \ of \ the \ ring} = \frac{M}{2\pi R}$$

Mass of the element of the length dx as shown in the figure $= \lambda \cdot dx = \frac{M}{2\pi R} dx$

If dI is the moment of inertia about the axis ZZ'.

dI = (mass of the element) (perpendicular distance from ZZ' axis)

$$= \left(\frac{M}{2\pi R} \cdot dx\right) (R^2)$$

$$dI = \frac{M}{2\pi} R \cdot dx \tag{1}$$

For the moment of inertia I of the ring as a whole about axis ZZ' integrate equation (1) in the interval from x = 0 to $x = 2\pi R$.

$$\therefore I = \int dI = \int_{0}^{2\pi R} \frac{M}{2\pi} R \cdot dx$$

$$\therefore I = \frac{M}{2\pi} R \int_{0}^{2\pi R} dx = \frac{M}{2\pi} R [x]_{0}^{2\pi R} = \frac{M}{2\pi} R [2\pi R - 0] I = MR^{2}$$
 (2)

Comparing equation (2) with $I = MK^2$, $K^2 = R^2$, Radius of gyration K = R

15. The vector sum of the forces acting on the light rod,

$$\overrightarrow{F} = \overrightarrow{F_1} + \overrightarrow{F_2} + \overrightarrow{F_3} + \overrightarrow{F_4} + \overrightarrow{F_5}$$
 (\overrightarrow{F} is the resultant force)

$$\stackrel{\rightarrow}{F} = \stackrel{\rightarrow}{F_1} \hat{j} + \stackrel{\rightarrow}{F_2} \hat{j} + \stackrel{\rightarrow}{F_3} (-\hat{j}) + \stackrel{\rightarrow}{F_4} \hat{j} + \stackrel{\rightarrow}{F_5} (-\hat{j})$$

Now, moment of force \overrightarrow{F} relative to point A = vector sum of the moments of component forces.

$$\therefore \mathbf{F} \cdot \mathbf{x} = [\mathbf{F}_1 \times 0] + [\mathbf{F}_2 \times \mathbf{x}_1] - [\mathbf{F}_3 \times (\mathbf{x}_1 + \mathbf{x}_2)] + [\mathbf{F}_4 \times (\mathbf{x}_1 + \mathbf{x}_2 + \mathbf{x}_3)] - [\mathbf{F}_5 \times (\mathbf{x}_1 + \mathbf{x}_2 + \mathbf{x}_3 + \mathbf{x}_4)]$$

$$\therefore x = \frac{x_1 F_2 - (x_1 + x_2) F_3 + (x_1 + x_2 + x_3) F_4 - (x_1 + x_2 + x_3 + x_4) F_5}{F_1 + F_2 + F_4 - F_3 - F_5}$$

CHAPTER 3

1. If two forces become equal at distance x from the centre of the Earth,

$$\frac{GM_e m}{r^2} = \frac{GM_s m}{(r-x)^2}$$
, $M_e = Mass of the Earth,$

 $M_s = Mass$ of the sun. r = Distance between the sun and the Earth. From this find x.

2.
$$M_e = \text{Volume} \times \text{Density} = \left(\frac{4}{3}\pi R_e^3\right)(\rho)$$

$$\therefore g = \frac{GM_e}{R_e^2} = \frac{4}{3}\pi G\rho R_e. \text{ Hence find } g.$$

3.
$$\begin{cases} \text{The required centripetal} \\ \text{force for the Earth's} \\ \text{circular motion} \\ \frac{\text{M}_e v_0^2}{r} \end{cases} = \begin{cases} \text{The gravitational force} \\ \text{on the Earth by} \\ \text{the Sun} \\ \frac{\text{GM}_s \text{M}_e}{r^2} \end{cases}$$

$$\therefore M_s = \frac{r v_0^2}{G}$$

4. For the circular motion of the satellite,

$$v_0 = \sqrt{\frac{\mathrm{GM}_e}{r}} = \sqrt{\frac{\mathrm{GM}_e}{2\mathrm{R}_e}} \ (\because r = \mathrm{R}_e + \mathrm{R}_e = 2\mathrm{R}_e)$$

Find v_0 from this. Now $T^2 = \left(\frac{4\pi^2}{GM_e}\right)r^3$. From this find T

- 5. For circular motion of satellite $mv^2/r = GM_e m/r^2$
 - $\therefore \text{ Kinetic energy of satellite } \frac{1}{2}mv^2 = \frac{GM_em}{2r}$

But potential energy = $\frac{-GM_em}{r}$

- \therefore Total energy = kinetic energy + potential energy = $\frac{-GM_em}{2r}$
- $\therefore \text{ Escape energy} = \frac{GM_e m}{2r}$
- $\therefore \frac{1}{2}mv_e^2 = \frac{GM_em}{2r}.$ From this find v_e .
- 6. For the circular motion of the satellite, $\frac{mv^2}{R_e} = \frac{GM_e m}{R_e^2} = (g)m$ (1) $(\because g = \frac{GM_e}{R_e^2})$ $\therefore v^2 = gR_e$. But $v = \frac{2\pi R_e}{T}$

Put this value in equation (1) and find T.

7. For circular motion of the satellite, $\frac{m{v_0}^2}{R_e} = \frac{GM_e m}{R_e^2}$: $v_0 = \sqrt{\frac{GM_e}{R_e}}$

For the object lying on the surface of the Earth, $v_e = \sqrt{\frac{2GM_e}{R_e}}$. Find $\frac{v_0}{v_e}$

8. At the given point the total energy = $\left[-\frac{GM_1m}{d/2} \right] + \left[\frac{-GM_2m}{d/2} \right]$

$$= \frac{-2G(M_1 + M_2)m}{d} \therefore \text{ Escape energy} = \frac{2G(M_1 + M_2)m}{d}$$

If the escape velocity is v_e , then $\frac{1}{2}mv_e^2 = \frac{2G(M_1 + M_2)m}{d}$. Hence, find v_e

9. In this special case, the circular motion is governed by,

$$\left(\text{Centripetal force } \frac{mv^2}{r}\right) = \left(\text{Gravitational force } \frac{\text{GM}m}{r^{5/2}}\right)$$

Also put $v = \frac{2\pi r}{T}$. Hence, find T^2 .

CHAPTER 4

- 1. Here, weight of wire = tensile force = ldg and breacking stress = $\frac{\text{Tensile force}}{\text{Area}} = ldg \quad \therefore \text{ L} = \frac{\text{Breaking stress}}{dg}$
- 2. If increase in lengths of AB, BC and CD wires are $\Delta l_{\rm AB}$, $\Delta l_{\rm BC}$ and $\Delta l_{\rm CD}$, find these increments using

$$\Delta l = \frac{\mathrm{F} l}{\mathrm{AY}} \,, \, \, \mathrm{Displacement \, \, of } \, \, \mathrm{B} \, = \, \Delta l_{\mathrm{AB}}, \, \, \mathrm{Displacement \, \, of } \, \, \mathrm{C} \, = \, \Delta l_{\mathrm{AB}} \, + \, \Delta l_{\mathrm{BC}}$$
 and Displacement of D = $\Delta l_{\mathrm{AB}} \, + \, \Delta l_{\mathrm{BC}} \, + \, \Delta l_{\mathrm{CD}}.$

3. Centripetal force necessary for circular motion is supplied by restoring force.

$$Y = \frac{FL}{A\Delta l}$$
 :: $F = \frac{YA\Delta L}{L}$ and $F = \frac{mv^2}{L} = \frac{m\omega^2L^2}{L}$ compose these two values of F.

4. Draw F.B.D. for both the masses and calculate tension T.

Here, Stress =
$$\frac{T}{A}$$
 and $\frac{\Delta l}{l}$ = $\frac{Stress}{Y}$

5. First ditermine Δl using $Y = \frac{Fl}{A\Delta L}$; now use illustration 3.

Use
$$U = \frac{1}{2}Y \times stress \times strain \times volume$$
.

6.
$$\Delta l = l \propto \Delta t : \frac{\Delta l}{l} = \infty \Delta t$$

Now use $Y = \frac{F}{A} \frac{l}{\Delta t}$; here F is tension. Now find F.

CHAPTER 5

1. Find velocity of water coming out of nozzle using $A_1v_1 = A_2v_2$

Now for vertical motion $y = \frac{1}{2}gt^2$, y = 1 m, for horizontal motion $x = v_2t$

$$\therefore y = \frac{1}{2}g\left(\frac{x}{v_2}\right)^2 \therefore x = \sqrt{\frac{2yv_2^2}{g}}$$

Liquid

Water

2. Pressure at A = Pressure at B

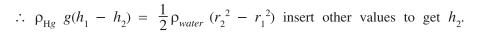
$$\therefore (h + 2d)\rho_l g + P_a = P_a + 1(2d)g$$

Now, find ρ_l .

3. For horizontal flow

$$P_1 + \frac{1}{2} \rho v_1^2 = P_2 + \frac{1}{2} \rho v_2^2$$

$$\therefore P_1 - P_2 = \frac{1}{2}\rho(v_2^2 - v_2^2)$$



4. Work =
$$T\Delta A = T2\pi (r_2^2 - r_1^2)$$

$$5. \quad T = \frac{rh\rho g}{2cos\theta}$$

 $\therefore h = \frac{2T\cos\theta}{r\rho g}$ Use this formula to calculate heights of water in both the arms. Then find the differences.

6.
$$\eta = \frac{2}{9} \frac{v^2}{vt} (\rho - \rho_0) g$$

Here, constant velocity of bubble is the terminal velocity.

7. and 8. Use equation given in hint.

9. Find
$$P_i$$
 using $P_i - P_o = \frac{4T}{R} P_o = 10^5 Pa$

Now for isothermal change $P_i V = P_i' \frac{V}{8}$

Find P_i' , No $P_i' - P_o' = \frac{4T}{R'}$ take $R' = \frac{R}{2}$ and calculate P_o' .

CHAPTER 6

1.
$$m=200$$
 g, $\Delta T=T_f-T_i$, $C=0.215$ cal g⁻¹ C^{o-1}, $Q=mC\Delta T$ and $H_C=\frac{Q}{\Delta T}$

2. (a) 32 g $O_2 = 1$ mole

$$\therefore 10 \text{ g O}_2 = \frac{10}{32} = \frac{5}{6} \text{ mole}$$

$$\therefore \mu = \frac{5}{6} \text{ mole}$$

$$P = 3 \times 10^5 \text{ N m}^{-2}, T = 273 + 10 = 283 \text{ K}$$

From the ideal gas, state equation,

$$PV_1 = \mu RT_1 \Rightarrow V_1 = \frac{\mu RT_1}{P}$$

and
$$V_2 = 10 L = 10^{-2} m^3$$

Hence, the work done by the gas

$$W = P(V_2 - V_1)$$

(b) As O_2 is diatomic rigid rotator,

$$C_{V} = \frac{5}{2} R$$
and $PV_{2} = \mu RT_{2} \Rightarrow T_{2} = \frac{PV_{2}}{\mu R}$

$$\therefore \Delta E_{int} = C_{V} (T_{2} - T_{1})$$

$$(c) \Delta E_{int} = Q - W$$

$$\therefore Q = \Delta E_{int} + W$$

- 3. Here $T_2 = 300$ K, $\eta = 40$ % = 0.4, $\eta = 1 \frac{T_2}{T_1}$, Hence calculate T_1 . Keeping $T_1 = \text{constant}$, $\eta' = 50\% = 0.5$, then $T_2' = ?$ From, $\eta' = 1 \frac{T_2'}{T_1}$, find T_2' .
- **4.** $T_1 = 500 \text{ K}, T_2 = 375 \text{ K}, Q_1 = 600 \text{ k cal}$
 - (i) Efficiency $\eta=1-\frac{T_2}{T_1}$ (ii) $\frac{Q_2}{Q_1}=\frac{T_2}{T_1} \Rightarrow Q_2=\frac{T_2}{T_1}\times Q_1$ Hence network done $W=(Q_1-Q_2)\times 4.2\frac{J}{cal}$
 - (iii) Heat gained back in heat sink is $= Q_2$
- 5. $T_i = 27$ °C = 27 + 273 = 300 K $P_i = 2$ atm, $\mu = 1$ mol, $\gamma = 1.5$, $V_f = \frac{1}{8} V_i$
 - (a) For adiabatic process $PV^{\gamma} = constant$

$$\therefore P_i V_i^{\gamma} = P_f V_f^{\gamma}, \Rightarrow P_f = P_i \left(\frac{V_i}{V_f}\right)^{\gamma}$$

(b) According to the ideal gas state equation $P_iV_i = \mu RT_i$

$$P_f V_f = \mu R T_f :: \frac{P_i V_i}{P_f V_f} = \frac{T_i}{T_f} \Rightarrow T_f = T_i \frac{P_f V_f}{P_i V_i}$$

6. For adiabatic process $W = \frac{\mu R(T_i - T_f)}{\gamma - 1}$. Here the volume decreases, hence, the work done is negative.

$$\therefore W = \frac{-\mu R(T_i - T_f)}{\gamma - 1} = \frac{\mu R(T_f - T_i)}{\gamma - 1}$$

7. According to first law of thermodynamics, $\therefore \Delta E_{int} = Q - W$

For closed gas container, the volume is constant $\Rightarrow \Delta V = 0$: W = 0

$$\Delta E_{int} = Q = \mu C_V \Delta T = \frac{PV}{RT} C_V \Delta T \ (\because PV = \mu RT, \therefore \mu = \frac{PV}{RT})$$

$$\therefore \Delta T = \frac{QRT}{PVC_V} \text{ (For monoatomic gas } C_V = \frac{3}{2}R)$$

 \therefore Final temperature $T_f = T_i + \Delta T$. For ideal gas $P_i V_i = \mu R T_i P_f V_f = \mu R T_f$

$$(:: V_f = V_i)$$

$$\therefore \frac{\mathbf{P}_f}{\mathbf{P}_i} = \frac{\mathbf{T}_f}{\mathbf{T}_i} \implies \mathbf{P}_f = \mathbf{P}_i \frac{\mathbf{T}_f}{\mathbf{T}_i}$$

8. Here, $\mu = 1 \text{ mol}$, $\Delta T = 30 \text{ C}^{\circ} = 30 \text{ K}$, $V \propto T^{\frac{2}{3}}$

$$\therefore V = AT^{\frac{2}{3}}, A = constant, \therefore dV = A^{\frac{2}{3}}T^{-\frac{1}{3}}dT$$

Hence,
$$W = \int_{T}^{T + \Delta T} P dV = \int_{T}^{T + \Delta T} \frac{RT}{V} dV (\because PV = \mu RT, \therefore PV = RT, \mu = 1)$$

$$= \int_{T}^{T + \Delta T} \frac{RT}{AT^{\frac{2}{3}}} A^{\frac{2}{3}} T^{-\frac{1}{3}} dT = \frac{2R}{3} \int_{T}^{T + \Delta T} dT = \frac{2}{3} R [T]_{T}^{T + \Delta T}$$

$$= \frac{2}{3}R[T + \Delta T - T] \qquad \therefore W = \frac{2}{3}R\Delta T$$

9. Here, P = 1.0 atm = 1.01×10^5 N m⁻², T = 300 K, $\mu = 2$ mol, R = 8.31 J mol⁻¹ K⁻¹

For diatomic (rigid rotator) gas $\gamma = \frac{7}{5}$. According to ideal gas state equation

$$PV = \mu RT$$
, $\therefore V = \frac{\mu RT}{P}$. For adiabatic process, $PV^{\gamma} = Constant$

$$\therefore \ Constant = P \left(\frac{\mu RT}{P} \right)^{\gamma}$$

10. Here $T_1 = 300$ K, $T_2 = 600$ K, $T_3 = 455$ K for monoatomic gas f = 3

For 1 mole gas

$$E_{int',1}=\frac{fRT_1}{2},~E_{int',2}=\frac{fRT_2}{2}$$
 and $E_{int',3}=Internal energy at point $3=\frac{fRT_3}{2}$$

Process 1 \rightarrow **2**: Process is isobaric \Rightarrow W₁ = 0

$$\therefore Q_1 = \Delta E_{int', 12} = E_{int', 2} - E_{int', 1}$$

Process 3 \rightarrow 1 : Process is isobaric

$$\therefore \Delta E_{int}, _{31} = Q_3 - W_3, W_3 = PdV$$

But as the volume of the gas is decreasing, W is negative

$$\therefore$$
 W₃ = -PdV = - μ R(T₃ - T₁) and Δ E_{int}, 31 = E_{int}, 1 - E_{int}, 3

Hence $Q_3 = \Delta E_{int}$, $_{31} + W_3$

11.
$$\eta = 22\% = 0.22$$
, $Q_1 - Q_2 = 75$ J, $\eta = \frac{Q_1 - Q_2}{Q_1} \Rightarrow Q_1 = \frac{Q_1 - Q_2}{\eta}$ and $Q_2 = Q_1 - 75$ J

- **12.** Here $Q_1 = 10,000 \text{ J}$, W = 2000 J, $L_C = 5.0 \times 10^4 \text{ J/g}$
 - (a) Efficiency of engine $\eta = \frac{W}{Q_1}$,
 - (b) During each cycle, the heat given into heat sink is $Q_2 = Q_1 W$,
 - (c) Let 'm' gram gasoline is used during each cycle.

$$\therefore Q_1 = mL_C \therefore m = \frac{Q_1}{L_C},$$

- (d) Gasoline used in each cycle = m gram
 - \therefore Gasoline used in 25 cycles per second is M = 25 \times m gram
 - \therefore Gasoline used in 1 hour = 60 \times 60 \times M g/h = kg/h
- (e) Power generated by engine in 1 second = Number of cycles per second \times (work done during each cycle)

CHAPTER 7

1. (a) T = 3 s, A = 2 cm,
$$\omega = \frac{2\pi}{T} = \frac{2\pi}{3}$$
, $\phi = 60^{\circ} = \frac{\pi}{3}$

$$\therefore y = 2 \sin\left(\frac{2\pi}{3}t + \frac{\pi}{3}\right)$$

(b) T = 1 min = 60 s, A = 3 cm,
$$\omega = \frac{2\pi}{T} = \frac{2\pi}{60}$$
, $\phi = -90^{\circ} = -\frac{\pi}{2}$

$$\therefore y = 3 \cos\left(\frac{\pi}{30}t\right)$$

2.
$$K = k + 2k + k = 8 \text{ N m}^{-1}, T = 2\pi \sqrt{\frac{m}{K}} = 0.628 \text{ s}$$

3. Here
$$F = -kl = -k(l_1 + l_2)$$
, Also $F_1 = -k_1l_1 = -k(l_1 + \frac{l_1}{n})$. $k_1 = (1 + \frac{l_1}{n}) k$, And $F_2 = -k_2l_2 = -k(l_2 + l_2)$ $k_2(n + 1)k$

SOLUTIONS 22:

4.
$$m = 100 \text{ g}$$
, A $(t) = \frac{A}{2}$, $t = 100 \times 2 = 200 \text{ s}$, A $(t) = A^{-bt/2m}$

5.
$$v = \pm \omega \sqrt{4A^2 - 3y^2}$$
, $v_{new} = \pm \omega \sqrt{A_1^2 - y_1^2}$ As $v_{new} = 2 v$, $2\sqrt{A_{new}^2 - y^2} = \sqrt{A_{new}^2 - y^2}$, $4(A^2 - y^2) = A_{new}^2 - y^2$ \therefore $A_{new}^2 = A^2 - 4y^2 + y$, $A_{new} = \sqrt{4A^2 - 3y^2}$

6.
$$v = \omega \sqrt{A^2 - y^2}$$
, $a = -\omega^2 y$, $T = \frac{2\pi}{\omega}$, $a^2 T^2 + 4\pi^2 v^2 = 4\pi^2 \omega^2 A^2 = \text{Constant}$.

7.
$$T - mg \cos\theta = mv^2/L$$
 : $T = mg \cos\theta + mv^2/L$

 $T = T_{max}$, when $\cos \theta = 1$ and v is maximum

$$v_{max}^2 = 2 hg = 2g L \frac{\theta_0^2}{2}, v_{max}^2 = 2 hg = 2g L (1 - \cos\theta_1),$$

=
$$2g L (\sin^2 \frac{\theta_0}{2}) (\because \sin^2 \theta = \frac{1 - \cos^2 \theta}{2}) = 2g L \frac{\theta_0^2}{2}$$

$$gL\left(\frac{A}{L}\right)^2 T_{max} = mg \left[1 + \left(\frac{A}{L}\right)^2\right]$$

8.
$$y_1 = 10 \sin (3\pi t + \frac{\pi}{4}), A_1 = 10, \omega_1 = 3\pi \Rightarrow T_1 = \frac{2}{3} \text{ s}$$

$$y_2 = 5 (\sin 3\pi t + \sqrt{3}\cos 3\pi t) = A_2\cos\phi \sin 3\pi t + A_2\sin\phi \cos 3\pi t$$

$$y_2 = A_2 \sin (3\pi t + \phi), A_2 = \sqrt{(5)^2 + (5\sqrt{3})^2} = 10$$

$$\omega_2 = 3\pi$$
, $T_2 = \frac{2}{3}$ s, And $\frac{A_1}{A_2} = 1$

9. PE =
$$\frac{1}{2}ky^2$$
. Total mechanical energy E = K + U : K = E - U

10.
$$v_1 = \omega \sqrt{A^2 - y_1^2}$$
, $v_2 = \omega \sqrt{A^2 - y_2^2}$, $v_1^2 - v_2^2 = \omega^2 (y_2^2 - y_1^2)$

$$T = \frac{2\pi}{\omega}$$

PHYSICS PHYSICS

CHAPTER 8

1. Differentiate wave equation $y = A \sin(\omega t - kx)$ w.r.t 't', the instantaneous velocity of a particle at time 't' will be, $v_p = \frac{dy}{dt} = A\omega \cos(\omega t - kx)$.

Now, wave speed $v = \omega/k$

Slope of wave at $x = \frac{dy}{dx} = -kA\cos(\omega t - kx)$

From above all three equations, $\frac{v_{\rm P}}{v} = -\frac{dy}{dx}$

2. Speed of P wave $v_{\rm P} = \frac{d}{t}$, Speed of S wave $v_{\rm S} = \frac{d}{t + 240}$

$$(: 4 \text{ min} = 60 \times 4 = 240 \text{ s})$$

By solving these two equations t = 240 s

Now, substitute value of t and v_p in equation $v_p = \frac{d}{t}$ and find out d.

3. A = 10 m, $x_1 = 2$ m, $t_1 = 2$ s and $y_1 = 5$ m, $x_2 = 16$ m, $t_2 = 8$ s and $y_2 = 5\sqrt{3}$ m

Now, substitute these values in equation $y_1 = a \sin (\omega t_1 - kx_1)$

$$\omega - k = \frac{\pi}{12} \tag{1}$$

From equation $y_2 = A\sin(\omega t_2 - kx_2)$ you will get,

$$\omega - 2k = \frac{\pi}{24} \tag{2}$$

Subtracting equation (2) from equation (1)

 $k = \frac{\pi}{24}$ rad/m, substitute value of k in equation (1), $\omega = \pi/8$ rad/s

4. $y = 3 \sin ((3.14)x - (314)t)$ differentiate equation w.r.t. 't'

$$v = \frac{dy}{dx} = (3) (314) \cos ((3.14)x - (314)t)$$

 \therefore Max speed of particle = (3) (314) = 9.4 m s⁻¹. Differentiate above equation w.r.t. 't'.

$$a = \frac{dv}{dt} = -(3)(314)(314) \sin((3.14)x - (314)t)$$

Now put x = 6 cm and t = 0.11 s,

$$a = -(3) (314)^2 \sin (6\pi - 11\pi) = (-3) (314)^2 \sin (-5\pi) = 0.$$

5. $T_1 = 0. + 273 = 273 \text{ K}, \lambda_1 = 1.32 \text{ m}, T_2 = 27 + 273 = 300 \text{ K}, \lambda_2 = ?$

Now,
$$\frac{v_1}{v_2} = \sqrt{\frac{T_1}{T_2}}$$

$$\therefore \ \frac{\lambda_1}{\lambda_2} = \sqrt{\frac{T_1}{T_2}} \ (\because \ v = f \, \lambda)$$

Substitute the values in above equation, $\lambda_2 = 1.384$ m,

Increase in the wavelength $\Delta\lambda = \lambda_2 - \lambda_1 = 0.064$ m

6.
$$T_0 = 1200 + 273 = 1473 \text{ K}, \ \rho_0 = 16 \ \rho_H, \ T_H = ? \text{ Now, } v_0 = v_H$$

$$\therefore \sqrt{\frac{\gamma R T_0}{\rho_0 V}} = \sqrt{\frac{\gamma R T_H}{\rho_H V}} \quad \therefore T_H = T_0 \times \frac{\rho_H}{\rho_0} = 1473 \times \frac{1}{16} = 92.06 \text{ K}$$

$$T_{\rm H} = 92.06 - 273 = -180.94$$
°C

7. Wave speed is same in all parts of the wire as the medium (wire) is same

$$\therefore v = f_1 \lambda_1 = f_2 \lambda_2 = f_3 \lambda_3$$

Each section of wire is oscillating with fundamental frequency (f = 2L)

$$f_1(2L_1) = f_2(2L_2) = f_3(2L_3)$$
, Now, put $f_1: f_2 = 1: 2$ and $f_1: f_3 = 1: 3$

in above equation and determine L_1 , L_2 and L_3 .

8.
$$\mu = 0.05$$
 g/cm, $f_n = 420$ Hz, $f_{n+1} = 490$ Hz, T = 490 N

Suppose the wire vibrates at 420 Hz in its nth harmonic and at 490 Hz in its (n+1)th harmonic. According to $f = \frac{n}{2L} \sqrt{\frac{T}{\mu}}$

$$f_n = \frac{n}{2L} \sqrt{\frac{T}{\mu}}$$
 (1) and $f_{n+1} = \frac{n+1}{2L} \sqrt{\frac{T}{\mu}}$ (2)

Taking the ratio,

$$\frac{f_{n+1}}{f_n} = \frac{n+1}{n} \qquad \therefore n = 6 \qquad \text{(by putting value of } f_n \text{ and } f_{n+1})$$

$$420 = \frac{6}{2L} \sqrt{\frac{450}{5 \times 10^{-3}}} = \frac{900}{L} \therefore L = \frac{900}{420} = 2.1 \text{ m}$$

PHYSICS PHYSICS

9. L = 100 cm, $f_n = 300$ Hz, $f_{n+1} = 400$ Hz, 2A = 10 cm

Now,
$$f_{n+1} - f_n = (n+1) f_1 - n f_1$$
, $\therefore f_1 = 100 \text{ Hz}$

$$\pi = \frac{2L}{1} = 200 \text{ cm}, \therefore k = \frac{2\pi}{\lambda} = \frac{\pi}{100} \text{ rad/cm}$$

$$\omega = 2\pi f_1 = 2\pi (100) \text{ rad/s}$$

Equation of stationary wave, $y = -10 \sin(\frac{\pi}{100}x) \cos(200\pi)t$ cm

10. When the car is moving towards the listener, $f_{\rm L_1} = \left(\frac{v+0}{v-v_{\rm S}}\right)f_{\rm s}$

When the car is moving away from the listener, $f_{\rm L_2} = \left(\frac{v+0}{v+v_{\rm S}}\right) f_{\rm S}$

$$\therefore f_{L_1} - f_{L_2} = \left(\frac{v}{v - v_S} - \frac{v}{v + v_S}\right) f_S$$

Substitute, v = 340 m/s, $v_S = 15$ m/s and $f_S = 500$ Hz in above equation.

$$f_{\rm L_1} - f_{\rm L_2} = 44.2 {\rm Hz}$$

11.
$$f_s = 600$$
 Hz, $v = 340$ m/s, $v_1 = 10$ m s⁻¹

When the engine is moving with the speed 10 m s⁻¹ towards the hill, we can consider its image moving in opposite direction. Listener is sitting in the engine and engine is moving towards the hill. Hence, direction of v_L is along L to S and direction of v_S is from S to L.

$$\therefore f_{\rm L} = \frac{v + v_{\rm L}}{v - v_{\rm S}} \times f_{\rm S} = \frac{340 + 10}{340 - 10} \times 600 = 700 \text{ Hz}$$

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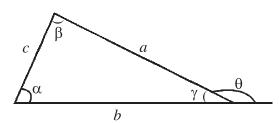
APPENDIX 229

APPENDIX

SINE AND COSINE RULES

(i)
$$\frac{\sin \alpha}{a} = \frac{\sin \beta}{b} = \frac{\sin \gamma}{c}$$

- (ii) $c^2 = a^2 + b^2 2 \ abcos \ \gamma$
- (iii) Exterior angle, $\theta = \alpha + \beta$



TRIGONOMETRIC IDENTITIES

(i)
$$sin^2\theta + cos^2\theta = 1$$

(ii)
$$1 + tan^2\theta = sec^2\theta$$

(iii)
$$1 + \cot^2\theta = \csc^2\theta$$

(iv)
$$sec^2\theta - tan^2\theta = 1$$

(v)
$$cosec^2\theta - cot^2\theta = 1$$

(vi)
$$sin2\theta = 2sin\theta \cos\theta$$

(vii)
$$cos2\theta = cos^2\theta - sin^2\theta = 2cos^2\theta - 1 = 1 - 2sin^2\theta$$

(viii)
$$sin(\alpha \pm \beta) = sin\alpha cos\beta \pm cos\alpha sin\beta$$

(ix)
$$cos(\alpha \pm \beta) = cos\alpha cos\beta \mp sin\alpha sin\beta$$

(x)
$$sin\alpha \pm sin\beta = 2sin\left(\frac{\alpha \pm \beta}{2}\right)cos\left(\frac{\alpha \mp \beta}{2}\right)$$

(xi)
$$cos\alpha + cos\beta = 2cos\left(\frac{\alpha + \beta}{2}\right)cos\left(\frac{\alpha - \beta}{2}\right)$$

(xii)
$$cos\alpha - cos\beta = -2sin\left(\frac{\alpha + \beta}{2}\right)sin\left(\frac{\alpha - \beta}{2}\right)$$

Values of sine and cosine for special angles:

Function	0° 0 rad	30° $\frac{\pi}{6}$ rad	45° $\frac{\pi}{4} \text{ rad}$	$\frac{60^{\circ}}{\frac{\pi}{3}}$ rad	$\frac{90^{\circ}}{\frac{\pi}{2}}$ rad	180° π rad	$\frac{270^{\circ}}{\frac{3\pi}{2}} \text{ rad}$	360° $2\pi \text{rad}$
sin	0	$\frac{1}{2}$	$\frac{1}{\sqrt{2}}$	$\frac{\sqrt{3}}{2}$	1	0	-1	0
cos	1	$\frac{\sqrt{3}}{2}$	$\frac{1}{\sqrt{2}}$	<u>1</u> 2	0	-1	0	1
tan	0	$\frac{1}{\sqrt{3}}$	1	$\sqrt{3}$	8	0	∞	0

Quadratic Formula:

If
$$ax^2 + bx + c = 0$$
, then, $x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$

Formulae of Log:

If $log \ a = x$, then $a = 10^x$

 $2. \log(ab) = \log(a) + \log(b)$

 $log\left(\frac{a}{b}\right) = log(a) - log(b)$ 4. $log(a^n) = n log a$

5. $log_a a = 1$

6. $ln \ a = log_e^{\ a} = 2.303 \ log_{10}^{\ a}$

Important Expansions:

Binomial Expansion $(1 \pm x)^n = 1 \pm nx + \frac{n(n-1)x^2}{2!} + \dots (x < 1)$

$$(1 \pm x)^{-n} = 1 \mp nx + \frac{n(n+1)x^2}{2!}$$
 $(x < 1)$

2. $e^x = 1 + x + \frac{x^2}{2!} + \frac{x^2}{3!} + \dots$ when x < 1, then $e^x = 1 + x$

 $ln(1 + x) = x - \frac{x^2}{2} + \frac{x^2}{3} + \dots + (|x| < 1)$

when $x \ll 1$, then $ln(1 \pm x) = \pm x$.

Trigonometric Expansion (θ in radian)

(i)
$$\sin\theta = \theta - \frac{\theta^3}{3!} + \frac{\theta^5}{5!} + \dots$$

(i) $\sin\theta = \theta - \frac{\theta^3}{3!} + \frac{\theta^5}{5!} + \dots$ (ii) $\cos\theta = 1 - \frac{\theta^2}{2!} + \frac{\theta^4}{4!} + \dots$

(iii)
$$\tan\theta = \theta + \frac{\theta^3}{3} + \frac{\theta^5}{15} + \dots$$

If θ is very small, then $\sin\theta \approx \theta$; $\cos\theta \approx 1$ and $\tan\theta \approx \theta$ rad

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у	$\frac{dy}{dx}$	у	$\frac{dy}{dx}$
x^n	nx^{n-1}	sec x	sec x tan x
sin x	cos x	cosec x	-cosec x cot x
cos x	$-\sin^{-2} x$	lnx	$\frac{1}{x}$
cot x	$-cosec^2 x$	tan x	$sec^2 x$
cos kx	$-k \sin x$	e^x	e^x
sin kx	k cos x	a^x	a^x ln a

Working rules of derivatives :

(1)
$$\frac{d}{dx}(k) = 0$$
 (where, k is a constant) (2) $\frac{d}{dx}(x) = 1$

$$(2) \frac{d}{dx}(x) = 1$$

(3)
$$\frac{d}{dx}(ky) = k\frac{dy}{dx}$$
 (where k is a constant) (4) $\frac{dy}{dx} = \frac{dy}{du} \times \frac{du}{dx}$

(4)
$$\frac{dy}{dx} = \frac{dy}{du} \times \frac{du}{dx}$$

(5) If
$$y = u \pm v$$
, then $\frac{dy}{dx} = \frac{du}{dx} \pm \frac{dv}{dx}$ (6) If $y = uv$, then $\frac{dy}{dx} = u\frac{dv}{dx} \pm v\frac{du}{dx}$

(6) If
$$y = uv$$
, then $\frac{dy}{dx} = u\frac{dv}{dx} \pm v\frac{du}{dx}$

(7) If
$$y = \frac{u}{v}$$
, then $\frac{dy}{dx} = \frac{v\frac{du}{dx} - u\frac{dv}{dx}}{v^2}$

APPENDIX 231

Integrals of Some Standard Functions:

f(x)	$F(x) = \int f(x) dx$	f(x)	$F(x) = \int f(x) dx$
χ^n	$\frac{x^{n+1}}{n+1} + c$	$(ax + b)^n$	$\frac{1}{a}\frac{(ax+b)^{n+1}}{n+1} + c$
$(n \neq + 1)$			
$\frac{1}{x}$	ln x + c	sin x	$-\cos x + c$
e^x	$e^x + c$	cos x	sin x + c
e^{kx}	$\frac{1}{k}e^{kx} + c$	sin kx	$-\frac{1}{k}\cos x + c$
a^x	$\frac{a^x}{lna} + c$	cos kx	$\frac{1}{k}\sin kx + c$

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